
libmodule Documentation

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1.1 Module

A module is core entity of libmodule: it is a single and independent logical unit that reacts to certain events, both pubsub and socket ones. It can be seen as an Actor with the power of managing socket events. It offers some callbacks that are used by libmodule to manage its life. It is initialized through MODULE macro:

```
MODULE("test")
```

This macro creates a “test” module. MODULE macro also creates a constructor and destructor that are automatically called by libmodule at start and at end of program. Finally, this macro declares all of needed callbacks and returns an opaque handler for the module, that will be transparently passed with each call to libmodule API while using *Easy API*.

1.2 Context

A context is a way to create subnets of modules. You can loop on events from each context, and each context behaves independently from others. This can be particularly useful when dealing with 2+ threads; ideally, each thread has its own module’s context and thus its own events to be polled. A context is automatically created for you first time a module that binds on that context is registered; so, multi-context API is very similar to single context one. To initialize a module binding it to its context, use MODULE_CTX macro:

```
MODULE_CTX("test", "myCtx")
```

This macro firstly creates a “myCtx” context, then a “test” module using same MODULE macro as before. Indeed, MODULE macro is only a particular case of MODULE_CTX macro, where myCtx is automatically setted to “default”. This makes sense, as you can expect: single context API is a multi context API with only 1 context. Modules can only see and reach (through PubSub messaging) other modules from same context.

2.1 Macros

```
#define MODULE_VERSION_MAJ @PROJECT_VERSION_MAJOR@
#define MODULE_VERSION_MIN @PROJECT_VERSION_MINOR@
#define MODULE_VERSION_PAT @PROJECT_VERSION_PATCH@

#define MODULE_DEFAULT_CTX "default"
#define MODULE_MAX_EVENTS 64
```

2.2 Types

```
/* Incomplete structure declaration to self handler */
typedef struct _self self_t;

/* Modules states */
enum module_states { IDLE = 0x1, RUNNING = 0x2, PAUSED = 0x4, STOPPED = 0x8 };

/* PubSub message types */
enum msg_type { USER, LOOP_STARTED, LOOP_STOPPED, TOPIC_REGISTERED, TOPIC_
↳DEREGISTERED };

typedef struct {
    const char *topic;
    const unsigned char *message;
    const ssize_t size;
    const self_t *sender;
    const enum msg_type type;
} pubsub_msg_t;

typedef struct {
```

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```

    const int fd;
    const void *userptr;
} fd_msg_t;

typedef struct {
    const bool is_pubsub;
    union {
        const fd_msg_t      *const fd_msg;
        const pubsub_msg_t  *const pubsub_msg;
    };
} msg_t;

/* Callbacks typedefs */
typedef void(*init_cb)(void);
typedef bool(*evaluate_cb)(void);
typedef void(*recv_cb)(const msg_t *const msg, const void *userdata);
typedef void(*destroy_cb)(void);

/* Logger callback */
typedef void (*log_cb)(const self_t *self, const char *fmt, va_list args, const void_
↳*userdata);

/* Memory management user-passed functions */
typedef void *(*malloc_fn)(size_t size);
typedef void *(*realloc_fn)(void *ptr, size_t size);
typedef void *(*calloc_fn)(size_t nmemb, size_t size);
typedef void (*free_fn)(void *ptr);

/* Struct that holds user defined callbacks */
typedef struct {
    init_cb init;                // module's init function (should return_
↳a FD)
    evaluate_cb evaluate;        // module's state changed function
    recv_cb recv;                // module's recv function
    destroy_cb destroy;         // module's destroy function
} userhook;

/* Struct that holds user defined memory functions */
typedef struct {
    malloc_fn _malloc;
    realloc_fn _realloc;
    calloc_fn _calloc;
    free_fn _free;
} memalloc_hook;

```

2.3 Return Codes

```

typedef enum {
    MOD_WRONG_PARAM = -8,
    MOD_NO_MEM,
    MOD_WRONG_STATE,
    MOD_NO_PARENT,
    MOD_NO_CTX,
    MOD_NO_MOD,

```

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```
MOD_NO_SELF,  
MOD_ERR,  
MOD_OK  
} module_ret_code;
```


Every module needs 5 functions that must be defined by developer. If using *Easy API*, they are automatically declared by `MODULE` macro. Moreover, a `module_pre_start` function is declared too, but it is not needed by `libmodule` interface, ie: it can be left undefined. Your compiler may warn you about that though.

```
static void module_pre_start(void);
static void init(void);
static bool check(void);
static bool evaluate(void);
static void receive(const msg_t *const msg, const void *userdata);
static void destroy(void);
```

module_pre_start (void)

This function will be called before any module is registered. It is the per-module version of `modules_pre_start` function.

init (void)

Initializes module state; useful to call `module_register_fd()` for each fd this module should listen to. To create a non-pollable module, just avoid registering any fd. Non-pollable module acts much more similar to an actor, ie: they can only receive and send PubSub messages. Moreover this is the right place to eventually register any topic.

check (void)

Startup filter to check whether this module should be registered and managed by `libmodule`, as sometimes you may wish that not your modules are automatically started.

Returns true if the module should be registered, false otherwise.

evaluate (void)

Similar to `check()` function but at runtime: this function is called for each IDLE module after every state machine update and it should check whether a module is now ready to be start (ie: `init` should be called on this module).

Returns true if module is now ready to be started, else false.

receive (msg, userdata)

Poll callback, called when any event is ready on module's fd or when a PubSub message is received by a module. Use `msg->is_pubsub` to decide which internal message should be read (ie: `pubsub_msg_t` or `fd_msg_t`).

Param `const msg_t * const msg`: pointer to `msg_t` struct.

Param `const void * userdata`: pointer to userdata as set by `m_set_userdata`.

destroy (void)

Destroys module, called automatically at module deregistration. Please note that module's fds set as autoclose will be closed.

4.1 Easy API

We previously saw that every module has to expose at least 5 functions. We will now go deeper, better understanding a module's lifecycle. First of all, module lifecycle is automatically managed by libmodule; moreover, when using *Easy API*, module registration/deregistration is completely automated and transparent to developer. This means that when using easy API (or multicontext API), you will only have to declare a source file as a module and define needed functions.

Before any module is registered into libmodule, each module's `module_pre_start()` function is called. This function can be useful to set each module pre-starting state: this may be needed if any `check()` function depends on some global state (eg: as read by config file).

After every `module_pre_start()` function is called, libmodule will start checking which module needs to be registered, eventually registering them. For every module, `check()` function will be called; if and only if that function returns true, the module will be registered. An unregistered module is just dead code; none of its functions will ever be called. Once a module is registered, it will be initially set to an IDLE state. Idle means that the module is not started yet, thus it cannot receive any PubSub msg nor any event from fds.

Right after module's registration, its `evaluate()` function will be called, trying to start the module right after it was registered. Evaluate will be then called at each state machine change, for each idle module.

As soon as module's `evaluate()` returns true, the module is started. It means its `init()` function is finally called and its state is set to RUNNING. A single module can poll on multiple fds: just call `module_register_fd()` multiple times. When a module reaches RUNNING state, `modules_loop()/modules_ctx_loop()` functions will finally receive events from its fds.

Whenever an event triggers on a module's fd, or the module receives a PubSub message from another one, its `receive()` callback is called. Receive callback will receive userdata too as parameter, as set by `module_set_userdata()`.

Finally, when leaving program, each module's `destroy()` function is automatically called during the process of automatic module's deregistration.

4.2 Complex API

When dealing with libmodule's *Complex API*, no modules is automatically started for you, ie: you must manually call `module_register()/module_deregister()` on each module. When using complex API, you are responsible to register/deregister modules, and thus initing/destroying them. Note that with Complex API, `module_pre_start()` function is not available (it would be useless), and you won't need to define `check()` function. You will still have to define `evaluate()`, `init()`, `receive()` and `destroy()` functions (but you can freely name them!).

Everything else but module's (de)registration is same as Easy API.

4.3 Module States

As previously mentioned, a registered module, before being started, is in IDLE state. IDLE state means that it has still no source of events; it won't receive any PubSub message and even if it registers any fd, they won't be polled. When module is started, thus reaching RUNNING state, all its registered fds will start being polled; moreover, it can finally receive PubSub messages. Fds registered while in RUNNING state, are automatically polled. If a module is PAUSED, it will stop polling on its fds and PubSub messages, but PubSub messages will still be queued on its write end of pipe. Thus, as soon as module is resumed, all PubSub messages received during PAUSED state will trigger `receive()` callback. If a module gets STOPPED, it will stop polling on its fds and PubSub messages, and every autoclose fd will be closed. Moreover, all its registered fds are freed. STOPPED state is the same as IDLE state, but it means that module was started at least once.

`module_start()` needs to be called on a IDLE or STOPPED module. `module_pause()` needs to be called on a RUNNING module. `module_resume()` needs to be called on a PAUSED module. `module_stop()` needs to be called on a RUNNING or PAUSED module.

5.1 Concepts

Those unfamiliar with actor like messaging, may wonder what a pubsub messaging is. PubSub (Publisher-Subscriber) messaging is much like a producer/consumer architecture: an entity registers a “topic” on which it will send messages. Other entities can then subscribe to the topic to receive those messages.

5.2 Implementation

Since libmodule 2.1, pubsub implementation is async and makes use of unix pipes. When sending a message to other modules, a pubsub message is allocated and its address is written in recipient module’s writable end of pipe. The message will then get caught by `modules_loop`, the address read from readable end of pipe and callback called with the message.

Since libmodule 4.0.0, `module_tell()` makes use of module references: it means recipient should be ref’d through `module_ref()`. Note that you cannot call any function on a module’s reference as you cannot impersonate another module. Only `module_is()`, `module_get_name/context()` functions can be called passing as `self_t` handler a module’s reference.

5.3 System messages

Beside USER messages (`pubsub_msg_t.type`), there are 4 system messages, with type respectively: `LOOP_STARTED`, `LOOP_STOPPED`, `TOPIC_REGISTERED`, `TOPIC_DEREGISTERED`. These pubsub messages are automatically sent by libmodule (note that sender will be `NULL`) when matching functions are called. For example, you can use `TOPIC_REGISTERED` message (note that `pubsub_msg_t.topic` will be valued matching newly created topic) to subscribe to a topic as soon as it appears in current context.

5.4 Notes

Note that a context must be looping to receive any pubsub message. Moreover, when a context stops looping, all pubsub messages will be flushed and thus delivered to each RUNNING module. Pubsub message sent while context is not looping or module is PAUSED are buffered until context starts looping/module gets resumed. For more information, see [pipe capacity](#). Finally, please be aware that data pointer sent through pubsub messaging is trusted, ie: you should pay attention to its scope.

Module API denotes libmodule interface functions to manage each module lifecycle. It is splitted in two APIs.

6.1 Easy API

Module easy API consists of a single-context-multi-modules set of macros. It can be found in `<module/module_easy.h>`. These macros make it easy and transparent to developer all of the module's internal mechanisms, providing a very simple way to use libmodule. It enforces correct modularity too: each module must have its own source file. Where not specified, these functions return a *module_ret_code*.

MODULE (name)

Creates “name” module with a default context: declares all needed functions and creates both constructor and destructor that will automatically register/deregister this module at startup. Finally, it declares a `const self_t *_self` global variable that will be automatically used in every function call. Note that default context will be automatically created if this is the first module to bind on it.

Parameters

- **name** (`const char *`) – name of the module to be created

Returns void

MODULE_CTX (name, ctxName)

Creates “name” module in ctxName context: declares all needed functions and creates both constructor and destructor that will automatically register/deregister this module at startup. Finally, it declares a `const self_t *_self` global variable that will be automatically used in every function call. Note that ctxName context will be automatically created if this is the first module to bind on it.

Parameters

- **name** (`const char *`) – name of the module to be created
- **ctxName** (`const char *`) – name of the context in which the module has to be created

Returns void

m_is (state)

Check current module's state

Parameters

- **state** (`const enum module_states`) – state we are interested in; note that it can be an OR of states (eg: `IDLE | RUNNING`)

Returns false if module's state is not 'state', true if it is and `MOD_ERR` on error.

m_start (void)

Start module's polling

m_pause (void)

Pause module's polling

m_resume (void)

Resume module's polling

m_stop (void)

Stop module's polling by closing its fds. Note that module is not destroyed: you can add new fds and call `m_start` on it.

m_become (new_recv)

Change receive callback to `receive_new_recv`

Parameters

- **new_recv** (`untyped`) – new module's receive callback; the function has prefix `receive_` concatenated with `new_recv`

m_unbecome (void)

Reset to default receive poll callback

m_set_userdata (userdata)

Set userdata for this module; userdata will be passed as parameter to receive callback

Parameters

- **userdata** (`const void *`) – module's new userdata.

m_register_fd (fd, autoclose, userptr)

Registers a new fd to be polled by a module

Parameters

- **fd** (`const int`) – fd to be registered.
- **autoclose** (`const bool`) – whether to automatically close the fd on module stop/fd deregistering.
- **userptr** (`const void *`) – data to be passed in `receive()` callback `msg->fd_msg_t` when an event happens on this fd.

m_deregister_fd (fd)

Deregisters a fd from a module

Parameters

- **fd** (`const int`) – module's old fd.

m_log (fmt, args)

Logger function for this module. Call it the same way you'd call `printf`

Parameters

- **fmt** (const char *) – log’s format.
- **args** (variadic) – variadic argument.

m_ref (name, modref)

Takes a reference from another module; it can be used in pubsub messaging to tell a message to it. It must not be freed.

Parameters

- **name** (const char *) – name of a module.
- **modref** (const self_t **) – variable that holds reference to module

m_register_topic (topic)

Registers a new topic in module’s context.

Parameters

- **topic** (const char *) – topic to be registered. Only a not-existent topic can be registered. Note that as soon as a topic is registered, a message with type == SYSTEM will be broadcasted to all modules.

m_deregister_topic (topic)

Deregisters topic in module’s context.

Parameters

- **topic** (const char *) – topic to be deregistered. Only topic creator can deregister a topic.

m_subscribe (topic)

Subscribes the module to a topic.

Parameters

- **topic** (const char *) – topic to which subscribe. Note that topic must be registered before.

m_unsubscribe (topic)

Unsubscribes the module from a topic.

Parameters

- **topic** (const char *) – topic to which unsubscribe. Note that topic must be registered before.

m_tell (recipient, msg, size)

Tell a message to another module.

Parameters

- **recipient** (const self_t *) – module to whom deliver the message.
- **msg** (const unsigned char *) – actual data to be sent.
- **size** (const ssize_t) – size of data to be sent.

m_publish (topic, msg, size)

Publish a message on a topic.

Parameters

- **topic** (const char *) – topic on which publish message. Note that only topic creator can publish message on topic.
- **msg** (const unsigned char *) – actual data to be published.

- **size** (const ssize_t) – size of data to be published.

m_broadcast (msg, size)

Broadcast a message in module's context.

Parameters

- **msg** (const unsigned char *) – data to be delivered to all modules in a context.
- **size** (const ssize_t) – size of data to be delivered.

m_tell_str (recipient, msg)

Tell a string message to another module. Size is automatically computed through strlen.

Parameters

- **recipient** (const self_t *) – module to whom deliver the message.
- **msg** (const char *) – message to be sent.

m_publish_str (topic, msg)

Publish a string message on a topic. Size is automatically computed through strlen.

Parameters

- **topic** (const char *) – topic on which publish message. NULL to broadcast message to all modules in same context. Note that only topic creator can publish message on topic.
- **msg** (const char *) – message to be published.

m_broadcast_str (msg)

Broadcast a string message in module's context. Same as calling m_publish(NULL, msg). Size is automatically computed through strlen.

Parameters

- **msg** (const char *) – message to be delivered to all modules in a context.

6.2 Complex API

Complex (probably better to say less-easy) API consists of '**Module easy API**' internally used functions. It can be found in <module/module.h> header. Sometime you may avoid using easy API; eg: if you wish to use same source file for different modules, or if you wish to manually register a module. Again, where not specified, these functions return a *module_ret_code*.

module_register (name, ctx_name, self, hook)

Register a new module

Parameters

- **name** (const char *) – module's name.
- **ctx_name** (const char *) – module's context name. A new context will be created if it cannot be found.
- **self** (const self_t **) – handler for this module that will be created by this call.
- **hook** (const userhook *) – struct that holds this module's callbacks.

module_deregister (self)

Deregister module

Parameters

- **self** (const self_t **) – pointer to module’s handler. It is set to NULL after this call.

module_is (self, state)

Check current module’s state

Parameters

- **self** (const self_t *) – pointer to module’s handler.
- **state** (const enum module_states) – state we are interested in; note that it can be an OR of states (eg: IDLE | RUNNING)

Returns false if module’s state is not ‘state’, true if it is and MOD_ERR on error.

module_start (self)

Start module’s polling

Parameters

- **self** (const self_t *) – pointer to module’s handler

module_pause (self)

Pause module’s polling

Parameters

- **self** (const self_t *) – pointer to module’s handler

module_resume (self)

Resume module’s polling

Parameters

- **self** (const self_t *) – pointer to module’s handler

module_stop (self)

Stop module’s polling by closing its fds. Note that module is not destroyed: you can add new fds and call module_start on it.

Parameters

- **self** (const self_t *) – pointer to module’s handler

module_become (self, new_receive)

Change receive callback to new_receive

Parameters

- **self** (const self_t *) – pointer to module’s handler
- **new_receive** (const recv_cb) – new module’s receive.

module_set_userdata (self, userdata)

Set userdata for this module; userdata will be passed as parameter to receive callback.

Parameters

- **self** (const self_t *) – pointer to module’s handler
- **userdata** (const void *) – module’s new userdata.

module_register_fd (self, fd, autoclose, userptr)

Register a new fd to be polled by a module

Parameters

- **self** (const self_t *) – pointer to module’s handler

- **fd** (const int) – fd to be registered.
- **autoclose** (const bool) – whether to automatically close the fd on module stop/fd deregistering.
- **userptr** (const void *) – data to be passed in receive() callback msg->fd_msg_t when an event happens on this fd.

module_deregister_fd (self, fd)

Deregister a fd from a module

Parameters

- **self** (const self_t *) – pointer to module’s handler
- **fd** (const int) – module’s old fd.

module_get_name (self, name)

Get module’s name from his self pointer.

Parameters

- **self** (const self_t *) – pointer to module’s handler
- **name** (char **) – pointer to storage for module’s name. Note that this must be freed by user.

module_get_context (self, ctx)

Get module’s name from his self pointer.

Parameters

- **self** (const self_t *) – pointer to module’s handler
- **ctx** (char **) – pointer to storage for module’s ctx. Note that this must be freed by user.

module_log (self, fmt, args)

Module’s logger

Parameters

- **self** (const self_t *) – pointer to module’s handler
- **fmt** (const char *) – log’s format.
- **args** (variadic) – variadic argument.

module_ref (self, name, modref)

Takes a reference from another module; it can be used in pubsub messaging to tell a message to it. It must not be freed.

Parameters

- **self** (const self_t *) – pointer to module’s handler
- **name** (const char *) – name of a module.
- **modref** (const self_t **) – variable that holds reference to module

module_register_topic (self, topic)

Registers a new topic in module’s context.

Parameters

- **self** (const self_t *) – pointer to module’s handler

- **topic** (`const char *`) – topic to be registered. Only a not-existent topic can be registered. Note that as soon as a topic is registered, a message with `type == SYSTEM` will be broadcasted to all modules.

module_deregister_topic (`self, topic`)

Deregisters topic in module's context.

Parameters

- **self** (`const self_t *`) – pointer to module's handler
- **topic** (`const char *`) – topic to be deregistered. Only topic creator can deregister a topic.

module_subscribe (`self, topic`)

Subscribes the module to a topic.

Parameters

- **self** (`const self_t *`) – pointer to module's handler
- **topic** (`const char *`) – topic to which subscribe. Note that topic must be registered before.

module_unsubscribe (`self, topic`)

Unsubscribes the module from a topic.

Parameters

- **self** (`const self_t *`) – pointer to module's handler
- **topic** (`const char *`) – topic to which unsubscribe. Note that topic must be registered before.

module_tell (`self, recipient, msg, size`)

Tell a message to another module.

Parameters

- **self** (`const self_t *`) – pointer to module's handler
- **recipient** (`const self_t *`) – module to whom deliver the message.
- **msg** (`const unsigned char *`) – actual data to be sent.
- **size** (`const ssize_t`) – size of data to be sent.

module_publish (`self, topic, msg, size`)

Publish a message on a topic.

Parameters

- **self** (`const self_t *`) – pointer to module's handler
- **topic** (`const char *`) – topic on which publish message. Note that only topic creator can publish message on topic.
- **msg** (`const unsigned char *`) – actual data to be published.
- **size** (`const ssize_t`) – size of data to be published.

module_broadcast (`self, msg, size`)

Broadcast a message to all modules inside context.

Parameters

- **self** (`const self_t *`) – pointer to module's handler

- **msg** (const unsigned char *) – actual data to be published.
- **size** (const ssize_t) – size of data to be published.

Modules API denotes libmodule interface functions to manage context loop. Like Module API, it has an easy, single-context API. Moreover, it has an equivalent multi-context API. All these functions but `modules_pre_start()` return a *module_ret_code*.

Moreover, there is a single function that is common to every context (thus does not need `ctx_name` param).

modules_set_memalloc_hook (hook)

Set memory management functions. By default: `malloc`, `realloc`, `calloc` and `free` are used.

Parameters

- **hook** (`const memalloc_hook *`) – new memory management hook.

7.1 Easy API

Modules easy API should be used in conjunction with *Easy API*. It abstracts all of libmodule internals mechanisms to provide an easy-to-use and simple API. It can be found in `<module/modules_easy.h>` header.

modules_pre_start (void)

This function will be called by libmodule before creating any module. It can be useful to set some global state/read config that are needed to decide whether to start a module. You only need to define this function and it will be automatically called by libmodule.

modules_set_logger (logger)

Set a logger. By default, module's log prints to `stdout`.

Parameters

- **logger** (`const log_cb`) – logger function.

modules_loop (void)

Start looping on events from modules. Note that as soon as `modules_loop` is called, a message with type `== LOOP_STARTED` will be broadcasted to all context's modules.

modules_quit (quit_code)

Leave libmodule's events loop. Note that as soon as it is called, a message with type == LOOP_STOPPED will be broadcasted to all context's modules.

Parameters

- **quit_code** (const uint8_t) – exit code that should be returned by modules_loop.

7.2 Multi-context API

Modules multi-context API let you manage your contexts in a very simple way. It is exposed by <module/modules.h> header. It exposes very similar functions to single-context API (again, single-context is only a particular case of multi-context), that now take a "context_name" parameter.

modules_ctx_set_logger (ctx_name, logger)

Set a logger for a context. By default, module's log prints to stdout.

Parameters

- **ctx_name** (const char *) – context name.
- **logger** (const log_cb) – logger function.

modules_ctx_loop (ctx_name)

Start looping on events from modules. Note that this is just a macro that calls modules_ctx_loop_events with MODULE_MAX_EVENTS (64) events.

Parameters

- **ctx_name** (const char *) – context name.

modules_ctx_loop_events (ctx_name, maxevents)

Start looping on events from modules, on at most maxevents events at the same time. Note that as soon as modules_loop is called, a message with type == LOOP_STARTED will be broadcasted to all context's modules.

Parameters

- **ctx_name** (const char *) – context name.
- **maxevents** (const int) – max number of fds wakeup that will be managed at the same time.

modules_ctx_quit (ctx_name, quit_code)

Leave libmodule's events loop. Note that as soon as it is called, a message with type == LOOP_STOPPED will be broadcasted to all context's modules.

Parameters

- **ctx_name** (const char *) – context name.
- **quit_code** (const uint8_t) – exit code that should be returned by modules_loop.

Libmodule offers an easy to use hashmap implementation, provided by <module/map.h> header. It is used internally to store context's modules and modules' subscriptions/topics.

8.1 Structures

```
typedef enum {
    MAP_WRONG_PARAM = -5,
    MAP_ERR,
    MAP_MISSING,
    MAP_FULL,
    MAP_OMEM,
    MAP_OK
} map_ret_code;

/* Callback for map_iterate */
typedef map_ret_code (*map_cb) (void *, void *);

/* Incomplete struct declaration for hashmap */
typedef struct _map map_t;
```

8.2 API

Where not specified, these functions return a `map_ret_code`.

map_new ()

Create a new `map_t` object.

Returns pointer to newly allocated `map_t`.

map_iterate (m, fn, userptr)

Iterate an hashmap calling cb on each element until MAP_OK is returned (or end of hashmap is reached). Returns MAP_MISSING if map is NULL.

Parameters

- **m** (map_t *) – pointer to map_t
- **fn** (const map_cb) – callback to be called
- **userptr** (void *) – userdata to be passed to callback as first parameter

map_put (m, key, val, dupkey, autofree)

Put a value inside hashmap. Note that if dupkey is true, key will be strduplicated; it will also be automatically freed upon deletion.

Parameters

- **m** (map_t *) – pointer to map_t
- **key** (const char *) – key for this value
- **val** (void *) – value to be put inside map
- **dupkey** (const bool) – whether to strdup key
- **autofree** (const bool) – whether to automatically free val upon map_remove/map_clear/map_free

map_get (m, key)

Get an hashmap value.

Parameters

- **m** (map_t *) – pointer to map_t
- **key** (const char *) – key for this value

Returns void pointer to value, on NULL on error.

map_has_key (m, key)

Check if key exists in map.

Parameters

- **m** (map_t *) – pointer to map_t
- **key** (const char *) – desired key

Returns true if key exists, false otherwise.

map_remove (m, key)

Remove a key from hashmap.

Parameters

- **m** (map_t *) – pointer to map_t
- **key** (const char *) – key to be removed

map_clear (m)

Clears a map object by deleting any object inside map, and eventually freeing it too if marked with autofree.

Parameters

- **s** (map_t *) – pointer to map_t

map_free (m)

Free a map object (it internally calls map_clear too).

Parameters

- **m** (map_t *) – pointer to map_t

map_length (m)

Get map length.

Parameters

- **m** (map_t *) – pointer to map_t

Returns map length or a map_ret_code if any error happens (map_t is null).

Libmodule offers an easy to use stack implementation, provided by `<module/stack.h>` header. It is used internally to store module's stack for become/unbecome methods.

9.1 Structures

```
typedef enum {
    STACK_WRONG_PARAM = -4,
    STACK_MISSING,
    STACK_ERR,
    STACK_OMEM,
    STACK_OK
} stack_ret_code;

/* Callback for stack_iterate */
typedef stack_ret_code (*stack_cb)(void *, void *);

/* Incomplete struct declaration for stack */
typedef struct _stack stack_t;
```

9.2 API

Where not specified, these functions return a `stack_ret_code`.

stack_new()

Create a new `stack_t` object.

Returns pointer to newly allocated `stack_t`.

stack_iterate(s, fn, userptr)

Iterate a stack calling `cb` on each element until `STACK_OK` is returned (or end of stack is reached). Returns `STACK_MISSING` if stack is `NULL`.

Parameters

- **s** (`stack_t *`) – pointer to `stack_t`
- **fn** (`const stack_cb`) – callback to be called
- **userptr** (`void *`) – userdata to be passed to callback as first parameter

stack_push (`s, val, autofree`)

Push a value on top of stack. Note that if `autofree` is true, data will be automatically freed when calling `stack_free()` on the stack.

Parameters

- **s** (`stack_t *`) – pointer to `stack_t`
- **val** (`void *`) – value to be put inside stack
- **autofree** (`const bool`) – whether to autofree `val` upon `stack_pop/stack_clear/stack_free`

stack_pop (`s`)

Pop a value from top of stack, removing it from stack.

Parameters

- **s** (`stack_t *`) – pointer to `stack_t`

Returns void pointer to value, on NULL on error.

stack_peek (`s`)

Return top-of-stack element, without removing it.

Parameters

- **s** (`stack_t *`) – pointer to `stack_t`

Returns void pointer to value, on NULL on error.

stack_clear (`s`)

Clears a stack object by deleting any object inside stack, and eventually freeing it too if marked with `autofree`.

Parameters

- **s** (`stack_t *`) – pointer to `stack_t`

stack_free (`s`)

Free a stack object (it internally calls `stack_clear` too).

Parameters

- **s** (`stack_t *`) – pointer to `stack_t`

stack_length (`s`)

Get stack length.

Parameters

- **s** (`stack_t *`) – pointer to `stack_t`

Returns stack length or a `stack_ret_code` if any error happens (`stack_t` is null).

CHAPTER 10

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