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# **Calliope Documentation**

*Release 0.6.2*

**Calliope contributors**

**Jun 04, 2018**



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v0.6.2 (*Release history*)

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This is the documentation for version 0.6.2. See the [main project website](#) for contact details and other useful information.

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Calliope focuses on flexibility, high spatial and temporal resolution, the ability to execute many runs based on the same base model, and a clear separation of framework (code) and model (data).

A model based on Calliope consists of a collection of text files (in YAML and CSV formats) that define the technologies, locations and resource potentials. Calliope takes these files, constructs an optimisation problem, solves it, and reports results in the form of [xarray Datasets](#) which in turn can easily be converted into [Pandas](#) data structures, for easy analysis with Calliope's built-in tools or the standard Python data analysis stack.

Calliope's built-in tools allow interactive exploration of results, as shown in the following example of a model that includes three energy carriers (electricity, heat, and gas):

Calliope is developed in the open [on GitHub](#) and contributions are very welcome (see the [Development guide](#)). See the list of [open issues](#) and planned [milestones](#) for an overview of where development is heading, and [join us on Gitter](#) to ask questions or discuss code.

Key features of Calliope include:

- Model specification in an easy-to-read and machine-processable YAML format
- Generic technology definition allows modelling any mix of production, storage and consumption
- Resolved in space: define locations with individual resource potentials
- Resolved in time: read time series with arbitrary resolution
- Able to run on high-performance computing (HPC) clusters
- Uses a state-of-the-art Python toolchain based on [Pyomo](#), [xarray](#), and [Pandas](#)
- Freely available under the Apache 2.0 license



## 1.1 Introduction

The basic process of modelling with Calliope is based on three steps:

1. Create a model from scratch or by adjusting an existing model (*Building a model*)
2. Run your model (*Running a model*)
3. Analyse and visualise model results (*Analysing a model*)

### 1.1.1 Energy system models

Energy system models allow analysts to form internally coherent scenarios of how energy is extracted, converted, transported, and used, and how these processes might change in the future. These models have been gaining renewed importance as methods to help navigate the climate policy-driven transformation of the energy system.

Calliope is an attempt to design an energy system model from the ground of up with specific design goals in mind (see below). Therefore, the model approach and data format layout may be different from approaches used in other models. The design of the nodes approach used in Calliope was influenced by the power nodes modelling framework by [\[Heussen2010\]](#).

Calliope was designed to address questions around the transition to renewable energy, so there are tools that are likely to be more suitable for other types of questions. In particular, the following related energy modelling systems are available under open source or free software licenses:

- **SWITCH**: A power system model focused on renewables integration, using multi-stage stochastic linear optimisation, as well as hourly resource potential and demand data. Written in the commercial AMPL language and GPL-licensed [\[Fripp2012\]](#).
- **Temoa**: An energy system model with multi-stage stochastic optimisation functionality which can be deployed to computing clusters, to address parametric uncertainty. Written in Python/Pyomo and AGPL-licensed [\[Hunter2013\]](#).

- **OSeMOSYS**: A simplified energy system model similar to the MARKAL/TIMES model families, which can be used as a stand-alone tool or integrated in the **LEAP energy model**. Written in GLPK, a free subset of the commercial AMPL language, and Apache 2.0-licensed [*Howells2011*].

Additional energy models that are partially or fully open can be found on the [Open Energy Modelling Initiative's wiki](#).

### 1.1.2 Rationale

Calliope was designed with the following goals in mind:

- Designed from the ground up to analyze energy systems with high shares of renewable energy or other variable generation
- Formulated to allow arbitrary spatial and temporal resolution, and equipped with the necessary tools to deal with time series input data
- Allow easy separation of model code and data, and modular extensibility of model code
- Make models easily modifiable, archiveable and auditable (e.g. in a Git repository), by using well-defined and human-readable text formats
- Simplify the definition and deployment of large numbers of model runs to high-performance computing clusters
- Able to run stand-alone from the command-line, but also provide an API for programmatic access and embedding in larger analyses
- Be a first-class citizen of the Python world (installable with `conda` and `pip`, with properly documented and tested code that mostly conforms to PEP8)
- Have a free and open-source code base under a permissive license

### 1.1.3 Acknowledgments

Initial development was partially funded by the [Grantham Institute](#) at Imperial College London and the European Institute of Innovation & Technology's [Climate-KIC](#) program.

### 1.1.4 License

Calliope is released under the Apache 2.0 license, which is a permissive open-source license much like the MIT or BSD licenses. This means that Calliope can be incorporated in both commercial and non-commercial projects.

```
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```

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```



## 1.1.5 References

# 1.2 Download and installation

## 1.2.1 Requirements

Calliope has been tested on Linux, macOS, and Windows.

Running Calliope requires four things:

1. The Python programming language, version 3.6 or higher.
2. A number of Python add-on modules (see *below for the complete list*).
3. A solver: Calliope has been tested with GLPK, CBC, Gurobi, and CPLEX. Any other solver that is compatible with Pyomo should also work.
4. The Calliope software itself.

## 1.2.2 Recommended installation method

The easiest way to get a working Calliope installation is to use the free `conda` package manager, which can install all of the four things described above in a single step.

To get `conda`, download and install the “Miniconda” distribution for your operating system (using the version for Python 3).

With Miniconda installed, you can create a new Python 3.6 environment called "calliope" with all the necessary modules, including the free and open source GLPK solver, by running the following command in a terminal or command-line window:

```
$ conda create -c conda-forge -n calliope python=3.6 calliope
```

To use Calliope, you need to activate the `calliope` environment each time. On Linux and macOS:

```
$ source activate calliope
```

On Windows:

```
$ activate calliope
```

You are now ready to use Calliope together with the free and open source GLPK solver. Read the next section for more information on alternative solvers.

## 1.2.3 Updating an existing installation

If following the recommended installation method above, the following command, assuming the `conda` environment is active, will update Calliope to the newest version:

```
$ conda update -c conda-forge calliope
```

## 1.2.4 Solvers

You need at least one of the solvers supported by Pyomo installed. CPLEX or Gurobi are recommended for large problems, and have been confirmed to work with Calliope. Refer to the documentation of your solver on how to install it.

### GLPK

GLPK is free and open-source, but can take too much time and/or too much memory on larger problems. If using the recommended installation approach above, GLPK is already installed in the `calliope` environment. To install GLPK manually, refer to the [GLPK website](#).

### CBC

CBC is another free and open-source option. CBC can be installed via conda on Linux and macOS by running `conda install -c conda-forge coinbc`. Windows binary packages and further documentation are available at the [CBC website](#).

### Gurobi

Gurobi is commercial but significantly faster than GLPK and CBC, which is relevant for larger problems. It needs a license to work, which can be obtained for free for academic use by creating an account on [gurobi.com](#).

While Gurobi can be installed via conda (`conda install -c gurobi gurobi`) we recommend downloading and installing the installer from the [Gurobi website](#), as the conda package has repeatedly shown various issues.

After installing, log on to the [Gurobi website](#) and obtain a (free academic or paid commercial) license, then activate it on your system via the instructions given online (using the `grbgetkey` command).

### CPLEX

Another commercial alternative is CPLEX. IBM offer academic licenses for CPLEX. Refer to the [IBM website](#) for details.

## 1.2.5 Python module requirements

Refer to [requirements/base.yml](#) in the Calliope repository for a full and up-to-date listing of required third-party packages.

Some of the key packages Calliope relies on are:

- [Pyomo](#)
- [Pandas](#)
- [Xarray](#)
- [Plotly](#)
- [Jupyter](#) (optional, but highly recommended, and used for the example notebooks in the tutorials)

## 1.3 New in v0.6.0

Version 0.6 is backwards incompatible with version 0.5. If you are familiar with how Calliope functions then this page will act as a reference for moving to version 0.6.

### 1.3.1 Converting a 0.5.x model to 0.6.0

Version 0.6 provides a conversion script to models created with Calliope 0.5 into 0.6-compatible models:

```
calliope convert run.yaml model.yaml output_dir
```

`run.yaml` and `model.yaml` are the main run and model configuration files of the 0.5 model to be converted, while `output_dir` is a directory into which the converted model will be saved.

The file structure of the input model is preserved (all YAML and CSV input files and their folder structure), but all information from the run configuration file is merged into the main model configuration file.

Time series are handled by the script: the `set_t.csv` required in Calliope 0.5 models is removed, with the time step information inserted directly into each of the remaining time series CSV files.

The conversion script has some important limitations:

- Comments in YAML files are lost
- Parallel run configurations are not converted to the new override group configuration format
- The `group_fraction` constraint is not converted, as its formulation has changed substantially in 0.6.0
- `carrier_ratios` are not converted
- Operational mode configuration is not converted

Functionality which is not converted, has been removed in version 0.6.0, or keys not known to the script, are moved into a `__disabled` key in the output YAML files, so they remain visible for the user to remove or to manually convert if needed.

The script also adds `interest_rate` and `lifetime` for each technology, using the implicit default values from Calliope 0.5 (25 years lifetime, a 0.10 interest rate for the monetary cost class and 0 for other cost classes).

**See also:**

### 0.6.0 model configuration changes

This page lists the full contents of `calliope/config/conversion_0.6.0.yaml`, which documents the changes in model configuration from 0.5.x to 0.6.0:

```
# Structure of this file:
# Each major section of model / run configuration has its own top-level key.
# Within each top-level section, changes are given as ``old name: new name``,
# and if the specific setting has been removed, the new name is ``null``,
# possibly with a comment indicating

run_config:
  import: null # use import statements in model configuration file instead
  subset_y: null
  subset_x: null
  subset_t: model.subset_time
  solver: run.solver
```

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```

solver_options: run.solver_options
name: null
model: null # since there is no separate run configuration file any more, there_
↳is no need to specify a model configuration file
mode: run.mode
output.format: null
output.path: null
debug.keep_temp_files: run.save_logs
debug.symbolic_solver_labels: null
override: null # now achieved with override groups, see override.yaml in examples
parallel: null
random_seed: model.random_seed
debug: null # no longer available

model_config:
  opmode: null
  startup_time: null
  name: model.name
  data_path: model.timeseries_data_path
  objective: null # custom objective not implemented yet
  constraints: null # custom constraints not implemented yet
  system_margin: model.reserve_margin
  group_fraction: null # major change to structure of this constraint, not_
↳automatically converted
  metadata: null ### SPECIAL LOGIC: move coordinates over to location configuration

tech_config:
  parent: essentials.parent
  group: null # Use tech_groups to specify groups
  name: essentials.name
  stack_weight: null # stack_weight is no longer supported
  color: essentials.color
  x_map: null # now achieved by directly specifying file=filename.csv:column
  carrier: essentials.carrier
  primary_carrier: essentials.primary_carrier_out
  carrier_in: essentials.carrier_in # If conversion_plus, now a list of carrier_
↳names. Ratios between carriers found in constraints.carrier_ratios
  carrier_in_2: essentials.carrier_in_2 # If conversion_plus, now a list of carrier_
↳names. Ratios between carriers found in constraints.carrier_ratios
  carrier_in_3: essentials.carrier_in_3 # If conversion_plus, now a list of carrier_
↳names. Ratios between carriers found in constraints.carrier_ratios
  carrier_out: essentials.carrier_out # If conversion_plus, now a list of carrier_
↳names. Ratios between carriers found in constraints.carrier_ratios
  carrier_out_2: essentials.carrier_out_2 # If conversion_plus, now a list of_
↳carrier names. Ratios between carriers found in constraints.carrier_ratios
  carrier_out_3: essentials.carrier_out_3 # If conversion_plus, now a list of_
↳carrier names. Ratios between carriers found in constraints.carrier_ratios
  export: constraints.export_carrier
  constraints.r: constraints.resource
  constraints.force_r: constraints.force_resource
  constraints.r_unit: constraints.resource_unit
  constraints.r_eff: constraints.resource_eff
  constraints.r_area.min: constraints.resource_area_min
  constraints.r_area.max: constraints.resource_area_max
  constraints.r_area.equals: constraints.resource_area_equals

```

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```

constraints.r_area_per_e_cap: constraints.resource_area_per_energy_cap
constraints.r_cap.min: constraints.resource_cap_min
constraints.r_cap.max: constraints.resource_cap_max
constraints.r_cap.equals: constraints.resource_cap_equals
constraints.r_cap_equals_e_cap: constraints.resource_cap_equals_energy_cap
constraints.r_scale: constraints.resource_scale
constraints.r_scale_to_peak: constraints.resource_scale_to_peak
constraints.s_init: constraints.storage_initial
constraints.s_cap.min: constraints.storage_cap_min
constraints.s_cap.max: constraints.storage_cap_max
constraints.s_cap.equals: constraints.storage_cap_equals
constraints.s_cap_per_unit: constraints.storage_cap_per_unit
constraints.c_rate: constraints.charge_rate
constraints.s_time.max: null
constraints.use_s_time: null
constraints.s_loss: constraints.storage_loss
constraints.e_prod: constraints.energy_prod
constraints.e_con: constraints.energy_con
constraints.p_eff: constraints.parasitic_eff
constraints.e_eff: constraints.energy_eff
constraints.e_eff_per_distance: constraints.energy_eff_per_distance
constraints.e_cap.min: constraints.energy_cap_min
constraints.e_cap.max: constraints.energy_cap_max
constraints.e_cap.equals: constraints.energy_cap_equals
constraints.e_cap_total.max: constraints.energy_cap_max_systemwide
constraints.e_cap_total.equals: constraints.energy_cap_equals_systemwide
constraints.e_cap_scale: constraints.energy_cap_scale
constraints.e_cap.min_use: constraints.energy_cap_min_use
constraints.e_cap_min_use: constraints.energy_cap_min_use
constraints.e_cap_per_unit: constraints.energy_cap_per_unit
constraints.e_ramping: constraints.energy_ramping
constraints.export_cap: constraints.export_cap
constraints.export_carrier: constraints.export_carrier
constraints.units.min: constraints.units_min
constraints.units.max: constraints.units_max
constraints.units.equals: constraints.units_equals
constraints.r_scale_to_peak: null
constraints.allow_r2: null
constraints.r2_startup_only: null
constraints.r2_eff: null
constraints.r2_cap.min: null
constraints.r2_cap.max: null
constraints.r2_cap.equals: null
constraints.r2_cap_follow: null
constraints.r2_cap_follow_mode: null
constraints.s_time.max: null
weight: null
per_distance: null

```

```

tech_constraints_per_distance_config:
  e_loss: constraints.energy_eff_per_distance

```

```

tech_costs_config:
  s_cap: storage_cap
  r_area: resource_area

```

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```

r_cap: resource_cap
r2_cap: null
e_cap: energy_cap
om_frac: om_annual_investment_fraction
om_fixed: om_annual
om_var: om_prod
om_fuel: om_con
export: export
purchase: purchase

tech_costs_per_distance_config:
    e_cap: energy_cap_per_distance

location_config:
    override: techs
    techs: null # List as keys of the subdict 'techs'
    within: null

###

depreciation_config: # manually processed in convert.py, listed here for completeness
    plant_life: constraints.lifetime
    interest: costs.{cost_class}.interest_rate

```

### 1.3.2 Removed functionality

If you require any of the removed functionality, we recommend you [open an issue on GitHub](#) for it to be built into a later revision of 0.6.

#### Technology constraints

- *s\_time* (providing a minimum/maximum/exact time of stored energy available for discharge) no longer exists. This constraint was relatively unpredictable in its effects when providing any combination of *s\_cap*, *e\_cap*, *c\_rate* and time clustering.
- The variable *r2* (providing a secondary resource that could be used by a supply/supply\_plus technology), along with all its constraints, have been removed. To utilise multiple resource inputs, *conversion\_plus* can be used instead.
- *r\_scale\_to\_peak* (allowing a user to provide a value for the peak resource to which the entire time series would be scaled accordingly) has been removed. *resource\_scale* (previously *r\_scale*) can still be used for scaling resource values by the given scale factor.
- *weight* (giving a technology a disproportionate weight in the objective function calculation) has been removed.

#### Custom objectives

The ability to load additional constraints or objectives has been removed. It is still possible to define a custom objective, but to load it, a modeller needs to use a development installation of Calliope and load the function manually.

**See also:**

*Development guide*

### 1.3.3 Updated functionality

#### Verbosity

Almost all sets, constraints, costs, and variables have been updated to be more verbose, making models more readable. The primary updates are:

#### Sets

- *y* -> *techs*
- *x* -> *locs*
- *c* -> *carriers*
- *k* -> *costs*

#### Constraints/Costs

- *e* -> *energy*, e.g. *e\_cap* -> *energy\_cap*
- *r* -> *resource*, e.g. *r\_cap* -> *resource\_cap*
- *s* -> *storage*, e.g. *s\_cap* -> *storage\_cap*
- *c\_rate* -> *charge\_rate*
- *p\_eff* -> *parasitic\_eff*

#### Variables

- *r* -> *resource\_con*: an output from the model giving how much of a resource was consumed
- *r* -> *resource*: the available resource as an input parameter to the model
- *c\_prodlc\_con* -> *carrier\_prodlcarrier\_con*: The produced/consumed carrier energy in each time storage\_cap

#### Model and run configuration

*run.yaml* no longer exists. Instead, all information needed to run a model is now stored in *model.yaml* under the headings *model* and *run*.

*run* only contains information about the solver: which one to use and any specific solver options to apply.

*model* contains all other information: time subsetting, model mode, output format, parallel runs, and time clustering.

To solve a model, point to the *model.yaml* file, e.g.: `calliope run path/to/model.yaml`.

### Overrides

Overrides are no longer applied within *run.yaml* (or even *model.yaml*). Instead, overrides are grouped and placed into a separate YAML file, called for example *overrides.yaml*.

Each group defines any number of overrides to the technology, location, link, model, or run definitions. One or several such groups can then be applied when solving a model, e.g.:

*overrides.yaml*:

```
higher_costs:
  techs.ccgt.costs.monetary.energy_cap: 10
  locations.region2.techs.csp.costs.monetary.energy_cap: 100
winter:
  model.subset_time: ['2005-01-01', '2005-02-28']
```

Running in the command line:

```
calliope run model.yaml --override_file=overrides.yaml:higher_costs
calliope run model.yaml --override_file=overrides.yaml:higher_costs,winter
```

Running interactively:

```
# only apply the 'higher_costs' override group
model = calliope.Model(
    'model.yaml',
    override_file='overrides.yaml:higher_costs'
)

# apply both the 'higher_costs' and 'winter' override groups
model2 = calliope.Model(
    'model.yaml',
    override_file='overrides.yaml:higher_costs,winter'
)
```

As in version 0.5, overrides can be applied when creating a *Model* object, via the argument *override\_dict*. A dictionary can then be given:

```
higher_costs = {
    'techs.ccgt.costs.monetary.energy_cap': 10,
    'locations.region2.techs.csp.costs.monetary.energy_cap': 100
}

model = calliope.Model('model.yaml', override_dict=higher_costs)
```

### Parallel runs

Building on the simplified way to define overrides (see above) and on lessons learnt during the development of Calliope so far, the functionality to generate multiple runs to run either on a single machine or in parallel on a high-performance cluster has been greatly simplified and improved.

**See also:**

*Generating scripts to run a model many times*



## Location and technology subsets

In model configuration, *subset\_x* and *subset\_y* (subsetting the used locations and technologies, respectively) no longer exist. *subset\_t*, now called *subset\_time*, does still exist.

To remove specific technologies or locations from a model, the new and much more powerful `exists` option can be used.

### See also:

*Removing techs, locations and links*

## Technology definition

A technology is now defined in three parts: *essentials*, *constraints*, and *costs*. All top-level definitions (*parent*, *carrier\_out*, etc.) are now given under *essentials* and cannot be defined per-location – they are defined only once for a given technology and apply model-wide. Both *constraints* and *costs* remain the same as in 0.5, but with more verbose naming:

Old:

```
supply_grid_power:
  name: 'National grid import'
  parent: supply
  carrier: power
  constraints:
    r: inf
    e_cap.max: 2000
  costs:
    monetary:
      e_cap: 15
      om_fuel: 0.1
```

New:

```
supply_grid_power:
  essentials:
    name: 'National grid import'
    parent: supply
    carrier: electricity
  constraints:
    resource: inf
    energy_cap_max: 2000
    lifetime: 25
  costs:
    monetary:
      interest_rate: 0.10
      energy_cap: 15
      om_con: 0.1
```

Carrier ratios and export carriers have also been moved from essentials into constraints:

Old:

```
chp:
  name: 'Combined heat and power'
  stack_weight: 100
  parent: conversion_plus
```

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```

export: true
primary_carrier_out: power
carrier_in: gas
carrier_out: power
carrier_out_2:
  heat: 0.8
constraints:
  e_cap.max: 1500
  e_eff: 0.405
costs:
  monetary:
    e_cap: 750
    om_var: 0.004
    export: file=export_power.csv

```

New:

```

chp:
  essentials:
    name: 'Combined heat and power'
    parent: conversion_plus
    primary_carrier_out: electricity
    carrier_in: gas
    carrier_out: electricity
    carrier_out_2: heat
  constraints:
    export_carrier: electricity
    energy_cap_max: 1500
    energy_eff: 0.405
    carrier_ratios.carrier_out_2.heat: 0.8
    lifetime: 25
  costs:
    monetary:
      interest_rate: 0.10
      energy_cap: 750
      om_prod: 0.004
      export: file=export_power.csv

```

Per distance constraints and costs have now been incorporated under the constraints and costs keys, with a ‘\_per\_distance’ suffix:

Old:

```

heat_pipes:
  name: 'District heat distribution'
  parent: transmission
  carrier: heat
  constraints:
    e_cap.max: 2000
  constraints_per_distance:
    e_loss: 0.025
  costs_per_distance:
    monetary:
      e_cap: 0.3

```

New:

```

heat_pipes:
  essentials:
    name: 'District heat distribution'
    parent: transmission
    carrier: heat
  constraints:
    energy_cap_max: 2000
    energy_eff_per_distance: 0.975
    lifetime: 25
  costs:
    monetary:
      interest_rate: 0.10
      energy_cap_per_distance: 0.3

```

### Interest rates and life times

As seen in the above examples, technology lifetime and interest rate must now be defined for each technology, under *costs*. In version 0.5, technologies not defining these would silently use implicit default values of 0.10 for interest rate and 25 years for life time. Setting these explicitly for any technology which has investment costs (i.e. those which are not *om\_...* or *export*) is now mandatory; no default values exist any more.

### Location definition

In version 0.5, location definitions included a list of technologies to permit at that location(s). An additional *overrides* key permitted per-location changes to model-wide technology definitions.

In 0.6, “overriding” refers only to model-wide overrides applied *as described above*. At each location, *techs* simply lists all allowed technologies and any possible changes to model-wide configuration values to apply at this location only, as shown below:

Old:

```

locations:
  region1:
    techs: [ccgt, csp]
    overrides:
      ccgt:
        constraints:
          energy_cap: 100

```

New:

```

locations:
  region1:
    techs:
      ccgt:
        constraints:
          energy_cap: 100
      # Note that csp must be listed to be permitted here,
      # even though it has no location-specific configuration.
      csp:

```

## Loading time series data from CSV files

*x\_map* (mapping a technology name to a column in a CSV file) has been removed. Instead, a user can define the time series file column when defining the file name, separated from the file name by a `:`. If no column name is provided, Calliope will look for a column with the location name.

Old:

```
# will look for the column `demand` in the file `demand_heat_r.csv`
locations:
  region1:
    techs: [demand_power]
    overrides:
      demand_power:
        x_map: demand
    constraints:
      r: file
```

New:

```
# will look for the column `demand` in the file `demand_heat_r.csv`
locations:
  region1:
    techs:
      demand_power:
        constraints:
          resource: file=demand_heat.csv:demand
```

## Link definition

Links have remained much the same as before. However, there is a slightly different structure in defining technologies, bringing the definition of link technologies more in line with the rest of the model configuration format.

Old:

```
links:
  region1,region2:
    ac_transmission:
      constraints:
        e_cap: 1000
```

New:

```
links:
  region1,region2:
    techs:
      ac_transmission:
        constraints:
          energy_cap: 1000
```

## Location metadata

Location coordinates, previously given under the *metadata* key, are now given directly per location:

Old:

```

metadata:
  # metadata given in cartesian coordinates, not lat, lon.
  map_boundary:
    lower_left:
      x: 0
      y: 0
    upper_right:
      x: 1
      y: 1
  location_coordinates:
    region1: {x: 2, y: 7}
    region2: {x: 8, y: 7}

```

New:

```

locations:
  region1:
    techs:
      ccgt:
      csp:
    coordinates: {x: 2, y: 7}
  region2:
    techs:
      demand_power:
    coordinates: {x: 8, y: 7}

```

### group\_share constraint

The `group_fraction` constraint is now called `group_share` and has a different formulation more in line with the rest of the tech-specific constraints:

```

group_share:
  csp,ccgt:
    energy_cap_min: 0.5
    energy_cap_max: 0.9
    carrier_prod_min:
    power: 0.5

```

In the process of making these updates, the `demand_power_peak` and (undocumented) `ignored_techs` options were removed from `group_share`.

### charge\_rate

When first introduced, charge rate was used to hard-link `energy_cap` and `storage_cap` for a `storage/supply_plus` technology. This meant that on defining `energy_cap_max` and `charge_rate`, a user was implicitly defining `storage_cap_max`. This hard-link has now been removed, replaced with only one constraint concerning charge rate:  $storage_{cap}(loc :: tech) \geq energy_{cap}(loc : tech) \times charge\_rate(loc : tech)$ .

**See also:**

[Capacity](#)

### Pre-processed data

Version 0.5 kept pre-processed data in either a dictionary (static data), pandas dataframe (location data) or an `xarray Dataset` (timeseries data). To view a value that would be used in optimisation, the user would call `model.get_option()`. Similarly, to edit a value before running the model, a user could use `model.set_option()`.

Now, all pre-processed data is held in a single unified `xarray Dataset`: `model.inputs`.

To view and edit this data before it is sent to the solver, a user need only use standard `xarray` functionality (see their [documentation](#) for more information).

### Plotting data

---

**Note:** Advanced plotting is still under construction. In case our current functionality is insufficient, input and output data can be plotted by the user using their preferred Python plotting tools, or any other language that can access either NetCDF or CSV data.

---

Plotting functions can now be called directly on the model and now use `Plotly` instead of 0.5's `matplotlib`.

Changes are:

- `calliope.analysis.plot_capacity(model.solution)` to `model.plot.capacity()`
- `calliope.analysis.plot_transmission(model.solution, carrier='power', tech='ac_transmission')` to `model.plot.transmission()`
- `calliope.analysis.plot_carrier_production(model.solution, carrier='power')` to `model.plot.timeseries()`

All available data is plotted, with dropdown menus available for a user to move between plots. A summary of all plotting can also be produced using `model.plot.summary()`, a function that is also available via the command line interface.

**See also:**

*Model class*

### Operational mode

In 0.6, running in operational mode changes capacities from decision variables to parameters, preventing various issues that plagued operational mode in prior versions. Additional sense checks were added to ensure that functionality incompatible with operational mode, such as time clustering, is not accidentally used together with it.

**See also:**

*Operational mode*

## 1.3.4 New functionality

### Debugging & checks

A user can now output a data structure of all model input data (the `model_run` dictionary) after Calliope's internal pre-processing, into a YAML file, for debugging. This debug file includes comments as to where constraint/cost values have originated (e.g. having been set by a location-specific configuration, or from a model-wide override group).

Similarly, sense checks are undertaken at several points during pre-processing to ensure the model being built is robust. This includes checks for missing data, possibly misspelled constraints, incompatible inputs, and much more.

This functionality will not find all possible user input errors, as this is an impossible task. However, it flags common mistakes, and the format of implementation allows for further checks to be applied in the future.

### Pre-processed model

Having the pre-processed model available in one `xarray Dataset` allows a model to be saved to file *before* being run. Although pre-processing is quick, this allows a user to avoid pre-processing the same file multiple times. Instead, they can read in a previously saved NetCDF file which fully describes the model.

### Multiple backends

Our primary solver backend is `Pyomo`. However, we have now extracted all pre-processing stages from the backend, with all data for a model run being stored in a single `xarray Dataset`. This permits the implementation of additional backends.

One such backend currently in an experimental state is based on `JuMP` in the Julia programming language. Linking Calliope to Julia is a long-term project, for which we welcome any contributions.

### Pyomo warmstart

Warmstart functionality can be used in solvers other than GLPK. They allow a previously constructed model to be changed slightly without having to be fully rebuilt. This can speed up re-running a model when you have just a few input parameters you would like to change (the cost of a technology, for instance).

Although the use of warmstart existed in operational mode in version *0.5*, now it extends to all possible parameters in all models. This functionality is currently undocumented in Calliope, but the `Pyomo` documentation provides some information and the `Pyomo` model built by Calliope can be accessed by `model._backend_model`.

### Backend interface

Once the backend model has been built, it can be accessed by a user, via Calliope. Parameters can be checked and changed, constraints can be activated/deactivated and a model can be re run, all without having to build the backend again. User who are familiar with building large models with `Pyomo` will be aware of the time penalty associated with processing the model in `Pyomo`. This additional functionality helps mitigate this, as changing a few parameters need not require complete model rebuild.

#### See also:

*Pyomo backend interface*

### Logging

In an interactive Python session (e.g. using Jupyter notebook), output from Calliope can be triggered at different levels of verbosity. By default on building the model (`calliope.Model()`) and running it (`model.run()`), there is no logging displayed unless it is at least a *WARNING*. For helpful information on where the model is in its pre-processing and running in the solver, verbosity can be increased using `calliope.set_log_level()`.

#### See also:

*Utility classes: AttrDict, Exceptions, Logging*

## 1.4 Building a model

In short, a Calliope model works like this: **supply technologies** can take a **resource** from outside of the modeled system and turn it into a specific energy **carrier** in the system. The model specifies one or more **locations** along with the technologies allowed at those locations. **Transmission technologies** can move energy of the same carrier from one location to another, while **conversion technologies** can convert one carrier into another at the same location. **Demand technologies** remove energy from the system, while **storage technologies** can store energy at a specific location. Putting all of these possibilities together allows a modeller to specify as simple or as complex a model as necessary to answer a given research question.

In more technical terms, Calliope allows a modeller to define technologies with arbitrary characteristics by “inheriting” basic traits from a number of included base tech groups – `supply`, `supply_plus`, `demand`, `conversion`, `conversion_plus`, and `transmission`. These groups are described in more detail in *List of abstract base technology groups*.

### 1.4.1 Terminology

The terminology defined here is used throughout the documentation and the model code and configuration files:

- **Technology:** a technology that produces, consumes, converts or transports energy
- **Location:** a site which can contain multiple technologies and which may contain other locations for energy balancing purposes
- **Resource:** a source or sink of energy that can (or must) be used by a technology to introduce into or remove energy from the system
- **Carrier:** an energy carrier that groups technologies together into the same network, for example electricity or heat.

As more generally in constrained optimisation, the following terms are also used:

- **Parameter:** a fixed coefficient that enters into model equations
- **Variable:** a variable coefficient (decision variable) that enters into model equations
- **Set:** an index in the algebraic formulation of the equations
- **Constraint:** an equality or inequality expression that constrains one or several variables

### 1.4.2 Files that define a model

Calliope models are defined through YAML files, which are both human-readable and computer-readable, and CSV files (a simple tabular format) for time series data.

It makes sense to collect all files belonging to a model inside a single model directory. The layout of that directory typically looks roughly like this (+ denotes directories, – files):

```
+ example_model
  + model_config
    - locations.yaml
    - techs.yaml
  + timeseries_data
    - solar_resource.csv
    - electricity_demand.csv
  - model.yaml
  - overrides.yaml
```



In the above example, the files `model.yaml`, `locations.yaml` and `techs.yaml` together are the model definition. This definition could be in one file, but it is more readable when split into multiple. We use the above layout in the example models and in our research!

Inside the `timeseries_data` directory, timeseries are stored as CSV files. The location of this directory can be specified in the model configuration, e.g. in `model.yaml`.

**Note:** The easiest way to create a new model is to use the `calliope new` command, which makes a copy of one of the built-in examples models:

```
$ calliope new my_new_model
```

This creates a new directory, `my_new_model`, in the current working directory.

By default, `calliope new` uses the national-scale example model as a template. To use a different template, you can specify the example model to use, e.g.: `--template=urban_scale`.

**See also:**

*YAML configuration file format, Built-in example models, Time series data*

### 1.4.3 Model configuration (`model`)

The model configuration specifies all aspects of the model to run. It is structured into several top-level headings (keys in the YAML file): `model`, `techs`, `locations`, `links`, and `run`. We will discuss each of these in turn, starting with `model`:

```
model:
  name: 'My energy model'
  timeseries_data_path: 'timeseries_data'
  reserve_margin:
    power: 0
  subset_time: ['2005-01-01', '2005-01-05']
```

Besides the model's name (`name`) and the path for CSV time series data (`timeseries_data_path`), model-wide constraints can be set, like `reserve_margin`.

To speed up model runs, the above example specifies a time subset to run the model over only five days of time series data (`subset_time: ['2005-01-01', '2005-01-05']`)— this is entirely optional. Usually, a full model will contain at least one year of data, but subsetting time can be useful to speed up a model for testing purposes.

**See also:**

*National scale example model, List of model settings*

### 1.4.4 Technologies (`techs`)

The `techs` section in the model configuration specifies all of the model's technologies. In our current example, this is in a separate file, `model_config/techs.yaml`, which is imported into the main `model.yaml` file alongside the file for locations described further below:

```
import:
  - 'model_config/techs.yaml'
  - 'model_config/locations.yaml'
```

**Note:** The `import` statement can specify a list of paths to additional files to import (the imported files, in turn, may include further files, so arbitrary degrees of nested configurations are possible). The `import` statement can either give an absolute path or a path relative to the importing file.

---

The following example shows the definition of a `ccgt` technology, i.e. a combined cycle gas turbine that delivers electricity:

```
ccgt:
  essentials:
    name: 'Combined cycle gas turbine'
    color: '#FDC97D'
    parent: supply
    carrier_out: power
  constraints:
    resource: inf
    energy_eff: 0.5
    energy_cap_max: 40000 # kW
    energy_cap_max_systemwide: 100000 # kW
    energy_ramping: 0.8
    lifetime: 25
  costs:
    monetary:
      interest_rate: 0.10
      energy_cap: 750 # USD per kW
      om_con: 0.02 # USD per kWh
```

Each technology must specify some essentials, most importantly a name, the abstract base technology it is inheriting from (`parent`), and its energy carrier (`carrier_out` in the case of a supply technology). Specifying a `color` is optional but useful for using the built-in visualisation tools (see [Analysing a model](#)).

The `constraints` section gives all constraints for the technology, such as allowed capacities, conversion efficiencies, the life time (used in levelised cost calculations), and the resource it consumes (in the above example, the resource is set to infinite via `inf`).

The `costs` section gives costs for the technology. Calliope uses the concept of “cost classes” to allow accounting for more than just monetary costs. The above example specifies only the `monetary` cost class, but any number of other classes could be used, for example `co2` to account for emissions.

By default the `monetary` cost class is used in the objective function, which seeks to minimize total costs. Additional cost classes can be created simply by adding them to the definition of costs for a technology. To use an alternative cost class and/or sense (minimize/maximize) in the objective function, the `objective_options` parameter can be set in the run configuration, e.g. `objective_options: {'cost_class': 'emissions', 'sense': 'minimize'}`.

### See also:

[List of possible constraints](#), [List of possible costs](#), [tutorials](#), [built-in examples](#)

## Allowing for unmet demand

For a model to find a feasible solution, supply must always be able to meet demand. To avoid the solver failing to find a solution, you can ensure feasibility:

```
run:
  ensure_feasibility: true
```

This will create an `unmet_demand` decision variable in the optimisation, which can pick up any mismatch between supply and demand, across all energy carriers. It has a very high cost associated with its use, so it will only appear when absolutely necessary.

**Note:** When ensuring feasibility, you can also set a **big M value** (`run.bigM`). This is the “cost” of unmet demand. It is possible to make model convergence very slow if `bigM` is set too high. default `bigM` is  $1 \times 10^9$ , but should be close to the maximum total system cost that you can imagine. This is perhaps closer to  $1 \times 10^6$  for urban scale models.

### 1.4.5 Locations and links (`locations`, `links`)

A model can specify any number of locations. These locations are linked together by transmission technologies. By consuming an energy carrier in one location and outputting it in another, linked location, transmission technologies allow resources to be drawn from the system at a different location from where they are brought into it.

The `locations` section specifies each location:

```
locations:
  region1:
    coordinates: {lat: 40, lon: -2}
    techs:
      unmet_demand_power:
      demand_power:
      ccgt:
        constraints:
          energy_cap_max: 30000
```

Locations can optionally specify `coordinates` (used in visualisation or to compute distance between them) and must specify `techs` allowed at that location. As seen in the example above, each allowed tech must be listed, and can optionally specify additional location-specific constraints. If given, location-specific constraints supersede any model-wide constraints a technology defines in the `techs` section for that location.

The `links` section specifies possible transmission links between locations in the form `location1, location2`:

```
links:
  region1, region2:
    techs:
      ac_transmission:
        constraints:
          energy_cap_max: 10000
```

In the above example, an high-voltage AC transmission line is specified to connect `region1` with `region2`. For this to work, a transmission technology called `ac_transmission` must have previously been defined in the model’s `techs` section. There, it can be given model-wide constraints such as costs. As in the case of locations, the `links` section can specify per-link constraints that supersede any model-wide constraints.

The modeller can also specify a distance for each link, and use per-distance constraints and costs for transmission technologies.

#### See also:

*List of possible constraints, List of possible costs.*

### 1.4.6 Run configuration (`run`)

The only required setting in the run configuration is the solver to use:

```
run:
  solver: glpk
  model: plan
```

the most important parts of the `run` section are `solver` and `mode`. A model can run either in planning mode (`plan`) or operational mode (`operate`). In planning mode, capacities are determined by the model, whereas in operational mode, capacities are fixed and the system is operated with a receding horizon control algorithm.

Possible options for `solver` include `glpk`, `gurobi`, `cplex`, and `cbc`. The interface to these solvers is done through the Pyomo library. Any [solver compatible with Pyomo](#) should work with Calliope.

For solvers with which Pyomo provides more than one way to interface, the additional `solver_io` option can be used. In the case of Gurobi, for example, it is usually fastest to use the direct Python interface:

```
run:
  solver: gurobi
  solver_io: python
```

---

**Note:** The opposite is currently true for CPLEX, which runs faster with the default `solver_io`.

---

Further optional settings, including debug settings, can be specified in the run configuration.

**See also:**

*List of run settings, Debugging failing runs, Solver options, documentation on operational mode.*

### 1.4.7 Overrides

To make it easier to run a given model multiple times with slightly changed settings or constraints, for example, varying the cost of a key technology, it is possible to define and apply “override groups” in a separate file (in the above example, `overrides.yaml`):

```
run1:
  model.subset_time: ['2005-01-01', '2005-01-31']
run2:
  model.subset_time: ['2005-02-01', '2005-02-31']
```

Each group is given by a name (above, `run1` and `run2`) and any number of model settings – anything in the model configuration can be overridden by an override group. In the above example, the two runs specify different time subsets, so would run an otherwise identical model over two different periods of time series data.

One or several override groups can be applied when running a model, as described in [Running a model](#). They can also be used to generate scripts that run a Calliope model with slightly changed settings many times, either sequentially, or in parallel on a high-performance cluster.

**See also:**

*Generating scripts to run a model many times*

## 1.5 Running a model

There are essentially three ways to run a Calliope model:

1. With the `calliope run` command-line tool.

2. By programmatically creating and running a model from within other Python code, or in an interactive Python session.
3. By generating and then executing scripts with the `calliope generate_runs` command-line tool, which is primarily designed for running many scenarios on a high-performance cluster.

### 1.5.1 Running with the command-line tool

We can easily run a model after creating it (see *Building a model*), saving results to a single NetCDF file for further processing:

```
$ calliope run testmodel/model.yaml --save_netcdf=results.nc
```

The `calliope run` command takes the following options:

- `--save_netcdf={filename.nc}`: Save complete model, including results, to the given NetCDF file. This is the recommended way to save model input and output data into a single file, as it preserves all data fully, and allows later reconstruction of the Calliope model for further analysis.
- `--save_csv={directory name}`: Save results as a set of CSV files to the given directory. This can be handy if the modeler needs results in a simple text-based format for further processing with a tool like Microsoft Excel.
- `--save_plots={filename.html}`: Save interactive plots to the given HTML file (see *Analysing a model* for further details on the plotting functionality).
- `--debug`: Run in debug mode, which prints more internal information, and is useful when troubleshooting failing models.
- `--override_file={filename.yaml} : {override_groups}`: Specify override groups to apply to the model (see below for more information).
- `--help`: Show all available options.

Multiple options can be specified, for example, saving NetCDF, CSV, and HTML plots simultaneously:

```
$ calliope run testmodel/model.yaml --save_netcdf=results.nc --save_csv=outputs --
↪save_plots=plots.html
```

**Warning:** Unlike in versions prior to 0.6.0, the command-line tool in Calliope 0.6.0 and upward does not save results by default – the modeller must specify one of the `-save` options.

### Overrides

Assuming we have specified an override group called `milp` in a file called `overrides.yaml`, we can apply it to our model with:

```
$ calliope run testmodel/model.yaml --override_file=overrides.yaml:milp --save_
↪netcdf=results.nc
```

Multiple overrides from the YAML file can be applied at once. For example, we may want to change some of the costs through an additional override group called `high_cost_scenario`. We could then use `--override_file=overrides.yaml:milp,high_cost_scenario` to apply both overrides simultaneously.

**See also:**

*Analysing a model, Overrides*

## 1.5.2 Running interactively with Python

The most basic way to run a model programmatically from within a Python interpreter is to create a `Model` instance with a given `model.yaml` configuration file, and then call its `run()` method:

```
import calliope
model = calliope.Model('path/to/model.yaml')
model.run()
```

---

**Note:** If `config` is not specified (i.e. `model = Model()`), an error is raised. See [Built-in example models](#) for information on instantiating a simple example model without specifying a custom model configuration.

---

**Note:** Calliope logs useful progress information to the INFO log level, but does not change the default log level from WARNING. To see progress information when running interactively, call `calliope.set_log_level('INFO')` immediately after importing Calliope.

---

Other ways to load a model interactively are:

- Passing an `AttrDict` or standard Python dictionary to the `Model` constructor, with the same nested format as the YAML model configuration (top-level keys: `model`, `run`, `locations`, `techs`).
- Loading a previously saved model from a NetCDF file with `model = calliope.read_netcdf('path/to/saved_model.nc')`. This can either be a pre-processed model saved before its `run` method was called, which will include input data only, or a completely solved model, which will include input and result data.

After instantiating the `Model` object, and before calling the `run()` method, it is possible to manually inspect and adjust the configuration of the model. The pre-processed inputs are all held in the xarray `Dataset` `model.inputs`.

After the model has been solved, an xarray `Dataset` containing results (`model.results`) can be accessed. At this point, the model can be saved with either `to_csv()` or `to_netcdf()`, which saves all inputs and results, and is equivalent to the corresponding `--save` options of the command-line tool.

### See also:

An example of interactive running in a Python session, which also demonstrates some of the analysis possibilities after running a model, is given in the [tutorials](#). You can download and run the embedded notebooks on your own machine (if both Calliope and the Jupyter Notebook are installed).

## Overrides

There are two ways to apply override groups interactively:

1. By setting the `override_file` argument analogously to use in the command-line tool, e.g.:

```
model = calliope.Model(
    'model.yaml',
    override_file='overrides.yaml:milp'
)
```

2. By passing the `override_dict` argument, which is a Python dictionary or `AttrDict` of overrides:

```

model = calliope.Model(
    'model.yaml',
    override_dict={'run.solver': 'gurobi'})

```

## Tracking progress

When running Calliope in command line, logging of model pre-processing and solving occurs automatically. Interactively, for example in a Jupyter notebook, you can enable verbose logging by running the following code before instantiating and running a Calliope model:

```

import logging

logging.basicConfig(
    level=logging.INFO,
    format='%(levelname)s: %(message)s',
)

logger = logging.getLogger()

```

This will include model processing output, as well as the output of the chosen solver.

### 1.5.3 Generating scripts for many model runs

Scripts to simplify the creation and execution of a large number of Calliope model runs are generated with the `calliope generate_runs` command-line tool. More detail on this is available in [Generating scripts to run a model many times](#).

### 1.5.4 Improving solution times

Large models will take time to solve. The most basic advice is to just let it run on a remote device (another computer or a high performance computing cluster) and forget about it until it is done. However, if you need results *now*, there are ways to improve solution time, invariably at the expense of model ‘accuracy’.

#### Number of variables

The sets `locs`, `techs`, `timesteps`, `carriers`, and `costs` all contribute to model complexity. A reduction of any of these sets will reduce the number of resulting decision variables in the optimisation, which in turn will improve solution times.

---

**Note:** By reducing the number of locations (e.g. merging nearby locations) you also remove the technologies linking those locations to the rest of the system, which is additionally beneficial.

---

Currently, we only provide automatic set reduction for timesteps. Timesteps can be resampled (e.g. 1hr -> 2hr intervals), masked (e.g. 1hr -> 12hr intervals except one week of particular interest), or clustered (e.g. 365 days to 5 days, each representing 73 days of the year, with 1hr resolution). In so doing, significant solution time improvements can be achieved.

**See also:**

*Time resolution adjustment*, Stefan Pfenninger (2017). Dealing with multiple decades of hourly wind and PV time series in energy models: a comparison of methods to reduce time resolution and the planning implications of inter-annual variability. Applied Energy.

### Complex technologies

Calliope is primarily an LP framework, but application of certain constraints will trigger binary or integer decision variables. When triggered, a MILP model will be created.

In both cases, there will be a time penalty, as linear programming solvers are less able to converge on solutions of problems which include binary or integer decision variables. But, the additional functionality can be useful. A purchasing cost allows for a cost curve of the form  $y = Mx + C$  to be applied to a technology, instead of the LP costs which are all of the form  $y = Mx$ . Integer units also trigger per-timestep decision variables, which allow technologies to be “on” or “off” at each timestep.

Additionally, in LP models, interactions between timesteps (in storage technologies) can lead to longer solution time. The exact extent of this is as-yet untested.

### Model mode

Solution time increases more than linearly with the number of decision variables. As it splits the model into ~daily chunks, operational mode can help to alleviate solution time of big problems. This is clearly at the expense of fixing technology capacities. However, one solution is to use a heavily time clustered `plan` mode to get indicative model capacities. Then run `operate` mode with these capacities to get a higher resolution operation strategy. If necessary, this process could be iterated.

#### See also:

*Operational mode*

### Solver choice

The open-source solvers (GLPK and CBC) are slower than the commercial solvers. If you are an academic researcher, it is recommended to acquire a free licence for Gurobi or CPLEX to very quickly improve solution times. GLPK in particular is slow when solving MILP models. CBC is an improvement, but can still be several orders of magnitude slower at reaching a solution than Gurobi or CPLEX.

#### See also:

*Solver options*

### Rerunning a model

After running, if there is an infeasibility you want to address, or simply a few values you dont think were quite right, you can change them and rerun your model. If you change them in `model.inputs`, just rerun the model as `model.run(force_rerun=True)`.

---

**Note:** `model.run(force_rerun=True)` will replace you current `model.results` and rebuild he entire model backend. You may want to save your model before doing this.

---

Particularly if your problem is large, you may not want to rebuild the backend to change a few small values. Instead you can interface directly with the backend using the `model.backend` functions, to update individual parameter



values and switch constraints on/off. By rerunning the backend specifically, you can optimise your problem with these backend changes, without rebuilding the backend entirely.

---

**Note:** `model.inputs` and `model.results` will not be changed when updating and rerunning the backend. Instead, a new xarray Dataset is returned.

---

**See also:**

*Interfacing with the solver backend*

## 1.5.5 Debugging failing runs

What will typically go wrong, in order of decreasing likelihood:

- The model is improperly defined or missing data. Calliope will attempt to diagnose some common errors and raise an appropriate error message.
- The model is consistent and properly defined but infeasible. Calliope will be able to construct the model and pass it on to the solver, but the solver (after a potentially long time) will abort with a message stating that the model is infeasible.
- There is a bug in Calliope causing the model to crash either before being passed to the solver, or after the solver has completed and when results are passed back to Calliope.

Calliope provides help in diagnosing model issues. See the section on *debugging failing runs*.

## 1.6 Analysing a model

Calliope inputs and results are designed for easy handling. Whatever software you prefer to use for data processing, either the NetCDF or CSV output options should provide a path to importing your Calliope results. If you prefer to not worry about writing your own scripts, then we have that covered too! The built-in plotting functions in `plot` are built on `Plotly`'s interactive visualisation tools to bring your data to life.

### 1.6.1 Accessing model data and results

A model which solved successfully has two primary Datasets with data of interest:

- `model.inputs`: contains all input data, such as renewable resource capacity factors
- `model.results`: contains all results data, such as dispatch decisions and installed capacities

In both of these, variables are indexed over concatenated sets of locations and technologies, over a dimension we call `loc_techs`. For example, if a technology called `boiler` only exists in location `X1` and not in locations `X2` or `X3`, then it will have a single entry in the `loc_techs` dimension called `X1::boiler`. For parameters which also consider different energy carriers, we use a `loc_tech_carrier` dimension, such that we would have, in the case of the prior boiler example, `X1::boiler::heat`.

This concatenated set formulation is memory-efficient but cumbersome to deal with, so the `model.get_formatted_array(name_of_variable)` function can be used to retrieve a `DataArray` indexed over separate dimensions (any of *techs*, *locs*, *carriers*, *costs*, *timesteps*, depending on the desired variable).

---

**Note:** On saving to CSV (see the *command-line interface documentation*), all variables are saved to a single file each, which are always indexed over all dimensions rather than just the concatenated dimensions.

---

## 1.6.2 Visualising results

In an interactive Python session, there are four primary visualisation functions: `capacity`, `timeseries`, `transmission`, and `summary`. To gain access to result visualisation without the need to interact with Python, the `summary` plot can also be accessed from the command line interface (*see below*).

Refer to the *API documentation for the analysis module* for an overview of available analysis functionality.

Refer to the *tutorials* for some basic analysis techniques.

### Plotting time series

The following example shows a `timeseries` plot of the built-in urban scale example model:

In Python, we get this function by calling `model.plot.timeseries()`. It includes all relevant timeseries information, from both inputs and results. We can force it to only have particular results in the dropdown menu:

```
# Only inputs or only results
model.plot.timeseries(array='inputs')
model.plot.timeseries(array='results')

# Only consumed resource
model.plot.timeseries(array='resource_con')

# Only consumed resource and `power` carrier flow
model.plot.timeseries(array=['power', `resource_con` ])
```

The data used to build the plots can also be subset and ordered by using the `subset` argument. This uses `xarray`'s `'loc'` indexing functionality to access subsets of data:

```
# Only show region1 data (rather than the default, which is a sum of all locations)
model.plot.timeseries(subset={'locs': ['region1']})

# Only show a subset of technologies
model.plot.timeseries(subset={'techs': ['ccgt', 'csp']})

# Assuming our model has three techs, 'ccgt', 'csp', and 'battery',
# specifying `subset` lets us order them in the stacked barchart
model.plot.timeseries(subset={'techs': ['ccgt', 'battery', 'csp']})
```

When aggregating model timesteps with clustering methods, the `timeseries` plots are adjusted accordingly (example from the built-in `time_clustering` example model):

#### See also:

*API documentation for the analysis module*

### Plotting capacities

The following example shows a capacity plot of the built-in urban scale example model:

Functionality is similar to `timeseries`, this time called by `model.plot.capacity()`. Here we show capacity limits set at input and chosen capacities at output. Choosing dropdowns and subsetting works in the same way as for `timeseries` plots

## Plotting transmission

The following example shows a transmission plot of the built-in urban scale example model:

By calling `model.plot.transmission()` you will see installed links, their capacities (on hover), and the locations of the nodes. This functionality only works if you have physically pinpointed your locations using the `coordinates` key for your location.

The above plot uses [Mapbox](#) to overlay our transmission plot on Openstreetmap. By creating an account at Mapbox and acquiring a Mapbox access token, you can also create similar visualisations by giving the token to the plotting function: `model.plot.transmission(mapbox_access_token='your token here')`.

Without the token, the plot will fall back on simple country-level outlines. In this urban scale example, the background is thus just grey (zoom out to see the UK!):

---

**Note:** If the coordinates were in  $x$  and  $y$ , not  $lat$  and  $lon$ , the transmission trace would be given on a cartesian plot.

---

## Summary plots

If you want all the data in one place, you can run `model.plot.summary(out_file='path/to/file.html')`, which will build a HTML file of all the interactive plots (maintaining the interactivity) and save it to `out_file`. This HTML file can be opened in a web browser to show all the plots. This functionality is made available in the command line interface by using the command `--save_plots=filename.html` when running the model.

See an example of such a HTML plot [here](#).

### See also:

*Running with the command-line tool*

## Saving publication-quality SVG figures

On calling any of the three primary plotting functions, you can also set `save_svg=True` for a high quality vector graphic to be saved. This file can be prepared for publication in programs like [Inkscape](#).

---

**Note:** For similar results in the command line interface, you'll currently need to save your model to netcdf (`--save_netcdf={filename.nc}`) then load it into a Calliope Model object in Python. Once there, you can use the above functions to get your SVGs.

---

## 1.6.3 Reading solutions

Calliope provides functionality to read a previously-saved model from a single NetCDF file:

```
solved_model = calliope.read_netcdf('my_saved_model.nc')
```

In the above example, the model's input data will be available under `solved_model.inputs`, while the results (if the model had previously been solved) are available under `solved_model.results`.

Both of these are `xarray.Datasets` and can be further processed with Python.

### See also:

The [xarray documentation](#) should be consulted for further information on dealing with Datasets. Calliope's NetCDF files follow the [CF conventions](#) and can easily be processed with any other tool that can deal with NetCDF.

## 1.7 Tutorials

The tutorials are based on the built-in example models, they explain the key steps necessary to set up and run simple models. Refer to the other parts of the documentation for more detailed information on configuring and running more complex models. The built-in examples are simple on purpose, to show the key components of a Calliope model with which models of arbitrary complexity can be built.

The *first tutorial* builds a model for part of a national grid, exhibiting the following Calliope functionality:

- Use of supply, supply\_plus, demand, storage and transmission technologies
- Nested locations
- Multiple cost types

The *second tutorial* builds a model for part of a district network, exhibiting the following Calliope functionality:

- Use of supply, demand, conversion, conversion\_plus, and transmission technologies
- Use of multiple energy carriers
- Revenue generation, by carrier export

The *third tutorial* extends the second tutorial, exhibiting binary and integer decision variable functionality (extended an LP model to a MILP model)

### 1.7.1 Tutorial 1: national scale

This example consists of two possible power supply technologies, a power demand at two locations, the possibility for battery storage at one of the locations, and a transmission technology linking the two. The diagram below gives an overview:

Fig. 1: Overview of the built-in national-scale example model

#### Supply-side technologies

The example model defines two power supply technologies.

The first is `ccgt` (combined-cycle gas turbine), which serves as an example of a simple technology with an infinite resource. Its only constraints are the cost of built capacity (`energy_cap`) and a constraint on its maximum built capacity.

Fig. 2: The layout of a supply node, in this case `ccgt`, which has an infinite resource, a carrier conversion efficiency (`energy_eff`), and a constraint on its maximum built `energy_cap` (which puts an upper limit on `energy_prod`).

The definition of this technology in the example model's configuration looks as follows:

```

cagt:
  essentials:
    name: 'Combined cycle gas turbine'
    color: '#E37A72'
    parent: supply
    carrier_out: power
  constraints:
    resource: inf
    energy_eff: 0.5
    energy_cap_max: 40000 # kW
    energy_cap_max_systemwide: 100000 # kW
    energy_ramping: 0.8
    lifetime: 25
  costs:
    monetary:
      interest_rate: 0.10
      energy_cap: 750 # USD per kW
      om_con: 0.02 # USD per kWh

```

There are a few things to note. First, `cagt` defines essential information: a name, a color (given as an HTML color code, for later visualisation), its parent, `supply`, and its `carrier_out`, `power`. It has set itself up as a power supply technology. This is followed by the definition of constraints and costs (the only cost class used is `monetary`, but this is where other “costs”, such as emissions, could be defined).

---

**Note:** There are technically no restrictions on the units used in model definitions. Usually, the units will be kW and kWh, alongside a currency like USD for costs. It is the responsibility of the modeler to ensure that units are correct and consistent. Some of the analysis functionality in the `analysis` module assumes that kW and kWh are used when drawing figure and axis labels, but apart from that, there is nothing preventing the use of other units.

---

The second technology is `csp` (concentrating solar power), and serves as an example of a complex `supply_plus` technology making use of:

- a finite resource based on time series data
- built-in storage
- plant-internal losses (`parasitic_eff`)

Fig. 3: The layout of a more complex node, in this case `csp`, which makes use of most node-level functionality available.

This definition in the example model’s configuration is more verbose:

```

csp:
  essentials:
    name: 'Concentrating solar power'
    color: '#F9CF22'
    parent: supply_plus
    carrier_out: power
  constraints:
    storage_cap_max: 614033
    charge_rate: 1
    storage_loss: 0.002
    resource: file=csp_resource.csv
    energy_eff: 0.4

```

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```

parasitic_eff: 0.9
resource_area_max: inf
energy_cap_max: 10000
lifetime: 25
costs:
  monetary:
    interest_rate: 0.10
    storage_cap: 50
    resource_area: 200
    resource_cap: 200
    energy_cap: 1000
    om_prod: 0.002

```

Again, `csp` has the definitions for `name`, `color`, `parent`, and `carrier_out`. Its constraints are more numerous: it defines a maximum storage capacity (`storage_cap_max`), an hourly storage loss rate (`storage_loss`), then specifies that its resource should be read from a file (more on that below). It also defines a carrier conversion efficiency of 0.4 and a parasitic efficiency of 0.9 (i.e., an internal loss of 0.1). Finally, the resource collector area and the installed carrier conversion capacity are constrained to a maximum.

The costs are more numerous as well, and include monetary costs for all relevant components along the conversion from resource to carrier (power): storage capacity, resource collector area, resource conversion capacity, energy conversion capacity, and variable operational and maintenance costs. Finally, it also overrides the default value for the monetary interest rate.

## Storage technologies

The second location allows a limited amount of battery storage to be deployed to better balance the system. This technology is defined as follows:

Fig. 4: A storage node with an *energy\_eff* and *storage\_loss*.

```

battery:
  essentials:
    name: 'Battery storage'
    color: '#3B61E3'
    parent: storage
    carrier: power
  constraints:
    energy_cap_max: 1000 # kW
    storage_cap_max: inf
    charge_rate: 4
    energy_eff: 0.95 # 0.95 * 0.95 = 0.9025 round trip efficiency
    storage_loss: 0 # No loss over time assumed
    lifetime: 25
  costs:
    monetary:
      interest_rate: 0.10
      storage_cap: 200 # USD per kWh storage capacity

```

The constraints give a maximum installed generation capacity for battery storage together with a charge rate (`charge_rate`) of 4, which in turn limits the storage capacity. The charge rate is the charge/discharge rate / storage capacity (a.k.a the battery *reservoir*). In the case of a storage technology, `energy_eff` applies twice: on charging and discharging. In addition, storage technologies can lose stored energy over time – in this case, we set this loss to zero.

## Other technologies

Three more technologies are needed for a simple model. First, a definition of power demand:

Fig. 5: A simple demand node.

```
demand_power:
  essentials:
    name: 'Power demand'
    color: '#072486'
    parent: demand
    carrier: power
```

Power demand is a technology like any other. We will associate an actual demand time series with the demand technology later.

What remains to set up is a simple transmission technologies. Transmission technologies (like conversion technologies) look different than other nodes, as they link the carrier at one location to the carrier at another (or, in the case of conversion, one carrier to another at the same location):

Fig. 6: A simple transmission node with an *energy\_eff*.

```
ac_transmission:
  essentials:
    name: 'AC power transmission'
    color: '#8465A9'
    parent: transmission
    carrier: power
  constraints:
    energy_eff: 0.85
    lifetime: 25
  costs:
    monetary:
      interest_rate: 0.10
      energy_cap: 200
      om_prod: 0.002

free_transmission:
  essentials:
    name: 'Local power transmission'
    color: '#6783E3'
    parent: transmission
    carrier: power
  constraints:
    energy_cap_max: inf
    energy_eff: 1.0
  costs:
    monetary:
      om_prod: 0
```

`ac_transmission` has an efficiency of 0.85, so a loss during transmission of 0.15, as well as some cost definitions.

`free_transmission` allows local power transmission from any of the csp facilities to the nearest location. As the name suggests, it applies no cost or efficiency losses to this transmission.

## Locations

In order to translate the model requirements shown in this section's introduction into a model definition, five locations are used: `region-1`, `region-2`, `region1-1`, `region1-2`, and `region1-3`.

The technologies are set up in these locations as follows:

Fig. 7: Locations and their technologies in the example model

Let's now look at the first location definition:

```
region1:
  coordinates: {lat: 40, lon: -2}
  techs:
    demand_power:
      constraints:
        resource: file=demand-1.csv:demand
    ccgt:
      constraints:
        energy_cap_max: 30000 # increased to ensure no unmet_demand in first_
↪ timestep
```

There are several things to note here:

- The location specifies a dictionary of technologies that it allows (`techs`), with each key of the dictionary referring to the name of technologies defined in our `techs.yaml` file. Note that technologies listed here must have been defined elsewhere in the model configuration.
- It also overrides some options for both `demand_power` and `ccgt`. For the latter, it simply sets a location-specific maximum capacity constraint. For `demand_power`, the options set here are related to reading the demand time series from a CSV file. CSV is a simple text-based format that stores tables by comma-separated rows. Note that we did not define any `resource` option in the definition of the `demand_power` technology. Instead, this is done directly via a location-specific override. For this location, the file `demand-1.csv` is loaded and the column `demand` is taken (the text after the colon). If no column is specified, Calliope will assume that the column name matches the location name `region1-1`. Note that in Calliope, a supply is positive and a demand is negative, so the stored CSV data will be negative.
- Coordinates are defined by latitude (`lat`) and longitude (`lon`), which will be used to calculate distance of transmission lines (unless we specify otherwise later on) and for location-based visualisation.

The remaining location definitions look like this:

```
region2:
  coordinates: {lat: 40, lon: -8}
  techs:
    demand_power:
      constraints:
        resource: file=demand-2.csv:demand
    battery:

region1-1.coordinates: {lat: 41, lon: -2}
region1-2.coordinates: {lat: 39, lon: -1}
region1-3.coordinates: {lat: 39, lon: -2}

region1-1, region1-2, region1-3:
  techs:
    csp:
```



`region2` is very similar to `region1`, except that it does not allow the `cogt` technology. The three `region1-` locations are defined together, except for their location coordinates, i.e. they each get the exact same configuration. They allow only the `csp` technology, this allows us to model three possible sites for CSP plants.

For transmission technologies, the model also needs to know which locations can be linked, and this is set up in the model configuration as follows:

```
region1,region2:
  techs:
    ac_transmission:
      constraints:
        energy_cap_max: 10000
region1,region1-1:
  techs:
    free_transmission:
region1,region1-2:
  techs:
    free_transmission:
region1,region1-3:
  techs:
    free_transmission:
```

We are able to override constraints for transmission technologies at this point, such as the maximum capacity of the specific `region1` to `region2` link shown here.

## Running the model

We now take you through running the model in a Jupyter notebook, which is included fully below. To download and run the notebook yourself, you can find it [here](#). You will need to have Calliope installed.

### 1.7.2 Tutorial 2: urban scale

This example consists of two possible sources of electricity, one possible source of heat, and one possible source of simultaneous heat and electricity. There are three locations, each describing a building, with transmission links between them. The diagram below gives an overview:

Fig. 8: Overview of the built-in urban-scale example model

## Supply technologies

This example model defines three supply technologies.

The first two are `supply_gas` and `supply_grid_power`, referring to the supply of gas (natural gas) and electricity, respectively, from the national distribution system. These ‘ininitely’ available national commodities can become energy carriers in the system, with the cost of their purchase being considered at supply, not conversion.

Fig. 9: The layout of a simple supply technology, in this case `supply_gas`, which has a resource input and a carrier output. A carrier conversion efficiency ( $energy_{eff}$ ) can also be applied (although isn’t considered for our supply technologies in this problem).

The definition of these technologies in the example model’s configuration looks as follows:

```

supply_grid_power:
  essentials:
    name: 'National grid import'
    color: '#C5ABE3'
    parent: supply
    carrier: electricity
  constraints:
    resource: inf
    energy_cap_max: 2000
    lifetime: 25
  costs:
    monetary:
      interest_rate: 0.10
      energy_cap: 15
      om_con: 0.1 # 10p/kWh electricity price #ppt

supply_gas:
  essentials:
    name: 'Natural gas import'
    color: '#C98AAD'
    parent: supply
    carrier: gas
  constraints:
    resource: inf
    energy_cap_max: 2000
    lifetime: 25
  costs:
    monetary:
      interest_rate: 0.10
      energy_cap: 1
      om_con: 0.025 # 2.5p/kWh gas price #ppt

```

The final supply technology is `pv` (solar photovoltaic power), which serves as an inflexible supply technology. It has a time-dependant resource availability, loaded from file, a maximum area over which it can capture its resource (`resource_area_max`) and a requirement that all available resource must be used (`force_resource: True`). This emulates the reality of solar technologies: once installed, their production matches the availability of solar energy.

The efficiency of the DC to AC inverter (which occurs after conversion from resource to energy carrier) is considered in `parasitic_eff` and the `resource_area_per_energy_cap` gives a link between the installed area of solar panels to the installed capacity of those panels (i.e. kWp).

In most cases, domestic PV panels are able to export excess energy to the national grid. We allow this here by specifying an `export_carrier`. Revenue for export will be considered on a per-location basis.

The definition of this technology in the example model's configuration looks as follows:

```

pv:
  essentials:
    name: 'Solar photovoltaic power'
    color: '#F9D956'
    parent: supply_power_plus
  constraints:
    export_carrier: electricity
    resource: file=pv_resource.csv # Already accounts for panel efficiency - kWh/
↪m2. Source: Renewables.ninja Solar PV Power - Version: 1.1 - License: https://
↪creativecommons.org/licenses/by-nc/4.0/ - Reference: https://doi.org/10.1016/j.
↪energy.2016.08.060

```

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```

parasitic_eff: 0.85 # inverter losses
energy_cap_max: 250
resource_area_max: 1500
force_resource: true
resource_area_per_energy_cap: 7 # 7m2 of panels needed to fit 1kWp of panels
lifetime: 25
costs:
  monetary:
    interest_rate: 0.10
    energy_cap: 1350

```

Finally, the parent of the PV technology is not `supply_plus`, but rather `supply_power_plus`. We use this to show the possibility of an intermediate technology group, which provides the information on the energy carrier (electricity) and the ultimate abstract base technology (`supply_plus`):

```

tech_groups:
  supply_power_plus:
    essentials:
      parent: supply_plus
      carrier: electricity

```

Intermediate technology groups allow us to avoid repetition of technology information, be it in essentials, constraints, or costs, by linking multiple technologies to the same intermediate group.

## Conversion technologies

The example model defines two conversion technologies.

The first is `boiler` (natural gas boiler), which serves as an example of a simple conversion technology with one input carrier and one output carrier. Its only constraints are the cost of built capacity (`costs.monetary.energy_cap`), a constraint on its maximum built capacity (`constraints.energy_cap.max`), and an energy conversion efficiency (`energy_eff`).

Fig. 10: The layout of a simple node, in this case `boiler`, which has one carrier input, one carrier output, a carrier conversion efficiency ( $energy_{eff}$ ), and a constraint on its maximum built  $energy_{cap}$  (which puts an upper limit on  $carrier_{prod}$ ).

The definition of this technology in the example model's configuration looks as follows:

```

boiler:
  essentials:
    name: 'Natural gas boiler'
    color: '#8E2999'
    parent: conversion
    carrier_out: heat
    carrier_in: gas
  constraints:
    energy_cap_max: 600
    energy_eff: 0.85
    lifetime: 25
  costs:
    monetary:
      interest_rate: 0.10
      om_con: 0.004 # .4p/kWh

```

There are a few things to note. First, `boiler` defines a name, a color (given as an HTML color code), and a `stack_weight`. These are used by the built-in analysis tools when analyzing model results. Second, it specifies its parent, `conversion`, its `carrier_in` `gas`, and its `carrier_out` `heat`, thus setting itself up as a gas to heat conversion technology. This is followed by the definition of constraints and costs (the only cost class used is `monetary`, but this is where other “costs”, such as emissions, could be defined).

The second technology is `chp` (combined heat and power), and serves as an example of a possible `conversion_plus` technology making use of two output carriers.

Fig. 11: The layout of a more complex node, in this case `chp`, which makes use of multiple output carriers.

This definition in the example model’s configuration is more verbose:

```
chp:
  essentials:
    name: 'Combined heat and power'
    color: '#E4AB97'
    parent: conversion_plus
    primary_carrier_out: electricity
    carrier_in: gas
    carrier_out: electricity
    carrier_out_2: heat
  constraints:
    export_carrier: electricity
    energy_cap_max: 1500
    energy_eff: 0.405
    carrier_ratios.carrier_out_2.heat: 0.8
    lifetime: 25
  costs:
    monetary:
      interest_rate: 0.10
      energy_cap: 750
      om_prod: 0.004 # .4p/kWh for 4500 operating hours/year
      export: file=export_power.csv
```

### See also:

#### *The `conversion_plus` tech*

Again, `chp` has the definitions for name, color, parent, and `carrier_in/out`. It now has an additional carrier (`carrier_out_2`) defined in its essential information, allowing a second carrier to be produced *at the same time* as the first carrier (`carrier_out`). The carrier ratio constraint tells us the ratio of `carrier_out_2` to `carrier_out` that we can achieve, in this case 0.8 units of heat are produced every time a unit of electricity is produced. to produce these units of energy, gas is consumed at a rate of  $\text{carrier\_prod}(\text{carrier\_out}) / \text{energy\_eff}$ , so gas consumption is only a function of power output.

As with the `pv`, the `chp` an export electricity. The revenue gained from this export is given in the file `export_power.csv`, in which negative values are given per time step.

## Demand technologies

Electricity and heat demand are defined here:

```
demand_electricity:
  essentials:
    name: 'Electrical demand'
```

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```

    color: '#072486'
    parent: demand
    carrier: electricity

demand_heat:
  essentials:
    name: 'Heat demand'
    color: '#660507'
    parent: demand
    carrier: heat

```

Electricity and heat demand are technologies like any other. We will associate an actual demand time series with each demand technology later.

### Transmission technologies

In this district, electricity and heat can be distributed between locations. Gas is made available in each location without consideration of transmission.

Fig. 12: A simple transmission node with an  $energy_{eff}$ .

```

power_lines:
  essentials:
    name: 'Electrical power distribution'
    color: '#6783E3'
    parent: transmission
    carrier: electricity
  constraints:
    energy_cap_max: 2000
    energy_eff: 0.98
    lifetime: 25
  costs:
    monetary:
      interest_rate: 0.10
      energy_cap_per_distance: 0.01

heat_pipes:
  essentials:
    name: 'District heat distribution'
    color: '#823739'
    parent: transmission
    carrier: heat
  constraints:
    energy_cap_max: 2000
    energy_eff_per_distance: 0.975
    lifetime: 25
  costs:
    monetary:
      interest_rate: 0.10
      energy_cap_per_distance: 0.3

```

`power_lines` has an efficiency of 0.95, so a loss during transmission of 0.05. `heat_pipes` has a loss rate per unit distance of 2.5%/unit distance (or `energy_eff_per_distance` of 97.5%). Over the distance between the two locations of 0.5km (0.5 units of distance), this translates to  $2.5^{0.5} = 1.58\%$  loss rate.

## Locations

In order to translate the model requirements shown in this section’s introduction into a model definition, four locations are used: X1, X2, X3, and N1.

The technologies are set up in these locations as follows:

Fig. 13: Locations and their technologies in the urban-scale example model

Let’s now look at the first location definition:

```
X1:
  techs:
    chp:
    pv:
    supply_grid_power:
      costs.monetary.energy_cap: 100 # cost of transformers
    supply_gas:
    demand_electricity:
      constraints.resource: file=demand_power.csv
    demand_heat:
      constraints.resource: file=demand_heat.csv
  available_area: 500
  coordinates: {x: 2, y: 7}
```

There are several things to note here:

- The location specifies a dictionary of technologies that it allows (`techs`), with each key of the dictionary referring to the name of technologies defined in our `techs.yaml` file. Note that technologies listed here must have been defined elsewhere in the model configuration.
- It also overrides some options for both `demand_electricity`, `demand_heat`, and `supply_grid_power`. For the latter, it simply sets a location-specific cost. For demands, the options set here are related to reading the demand time series from a CSV file. CSV is a simple text-based format that stores tables by comma-separated rows. Note that we did not define any `resource` option in the definition of these demands. Instead, this is done directly via a location-specific override. For this location, the files `demand_heat.csv` and `demand_power.csv` are loaded. As no column is specified (see *national scale example model*) Calliope will assume that the column name matches the location name X1. Note that in Calliope, a supply is positive and a demand is negative, so the stored CSV data will be negative.
- Coordinates are defined by cartesian coordinates `x` and `y`, which will be used to calculate distance of transmission lines (unless we specify otherwise later on) and for location-based visualisation. These coordinates are abstract, unlike latitude and longitude, and can be used when we don’t know (or care) about the geographical location of our problem.
- An `available_area` is defined, which will limit the maximum area of all `resource_area` technologies to the e.g. roof space available at our location. In this case, we just have `pv`, but the case where solar thermal panels compete with photovoltaic panels for space, this would the sum of the two to the available area.

The remaining location definitions look like this:

```
X2:
  techs:
    boiler:
      costs.monetary.energy_cap: 43.1 # different boiler costs
    pv:
      costs.monetary:
```

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```

        om_prod: -0.0203 # revenue for just producing electricity
        export: -0.0491 # FIT return for PV export
    supply_gas:
    demand_electricity:
        constraints.resource: file=demand_power.csv
    demand_heat:
        constraints.resource: file=demand_heat.csv
    available_area: 1300
    coordinates: {x: 8, y: 7}
X3:
    techs:
        boiler:
            costs.monetary.energy_cap: 78 # different boiler costs
        pv:
            constraints:
                energy_cap_max: 50 # changing tariff structure below 50kW
            costs.monetary:
                om_annual: -80.5 # reimbursement per kWp from FIT
            supply_gas:
            demand_electricity:
                constraints.resource: file=demand_power.csv
            demand_heat:
                constraints.resource: file=demand_heat.csv
    available_area: 900
    coordinates: {x: 5, y: 3}

```

X2 and X3 are very similar to X1, except that they do not connect to the national electricity grid, nor do they contain the chp technology. Specific pv cost structures are also given, emulating e.g. commercial vs. domestic feed-in tariffs.

N1 differs to the others by virtue of containing no technologies. It acts as a branching station for the heat network, allowing connections to one or both of X2 and X3 without double counting the pipeline from X1 to N1. Its definition look like this:

```

N1: # location for branching heat transmission network
    coordinates: {x: 5, y: 7}

```

For transmission technologies, the model also needs to know which locations can be linked, and this is set up in the model configuration as follows:

```

X1,X2:
    techs:
        power_lines:
            distance: 10
X1,X3:
    techs:
        power_lines:
X1,N1:
    techs:
        heat_pipes:
N1,X2:
    techs:
        heat_pipes:
N1,X3:
    techs:
        heat_pipes:

```

The distance measure for the power line is larger than the straight line distance given by the coordinates of X1 and X2, so we can provide more information on non-direct routes for our distribution system. These distances will override any automatic straight-line distances calculated by coordinates.

### Revenue by export

Defined for both PV and CHP, there is the option to accrue revenue in the system by exporting electricity. This export is considered as a removal of the energy carrier `electricity` from the system, in exchange for negative cost (i.e. revenue). To allow this, `carrier_export: electricity` has been given under both technology definitions and an `export` value given under costs.

The revenue from PV export varies depending on location, emulating the different feed-in tariff structures in the UK for commercial and domestic properties. In domestic properties, the revenue is generated by simply having the installation (per kW installed capacity), as export is not metered. Export is metered in commercial properties, thus revenue is generated directly from export (per kWh exported). The revenue generated by CHP depends on the electricity grid wholesale price per kWh, being 80% of that. These revenue possibilities are reflected in the technologies' and locations' definitions.

### Running the model

We now take you through running the model in a Jupyter notebook, which is included fully below. To download and run the notebook yourself, you can find it [here](#). You will need to have Calliope installed.

## 1.7.3 Tutorial 3: Mixed Integer Linear Programming

This example is based on the *urban scale example model*, but with an override. An override file exists in which binary and integer decision variables are triggered, creating a MILP model, rather than the conventional Calliope LP model.

**Warning:** Integer and Binary variables are still experimental and may not cover all edge cases as intended. Please [raise an issue on GitHub](#) if you see unexpected behaviour.

### Units

The capacity of a technology is usually a continuous decision variable, which can be within the range of 0 and `energy_cap_max` (the maximum capacity of a technology). In this model, we introduce a unit limit on the CHP instead:

```
chp:
  constraints:
    units_max: 4
    energy_cap_per_unit: 300
    energy_cap_min_use: 0.2
  costs:
    monetary:
      energy_cap: 700
      purchase: 40000
```

A unit maximum allows a discrete, integer number of CHP to be purchased, each having a capacity of `energy_cap_per_unit`. Any of `energy_cap_max`, `energy_cap_min`, or `energy_cap_equals` are now ignored, in favour of `units_max`, `units_min`, or `units_equals`. A useful feature unlocked by introducing this is the ability to set a minimum operating capacity which is *only* enforced when the technology is operating.



In the LP model, `energy_cap_min_use` would force the technology to operate at least at that proportion of its maximum capacity at each time step. In this model, the newly introduced `energy_cap_min_use` of 0.2 will ensure that the output of the CHP is 20% of its maximum capacity in any time step in which it has a non-zero output.

## Purchase cost

The boiler does not have a unit limit, it still utilises the continuous variable for its capacity. However, we have introduced a purchase cost:

```
boiler:
  costs:
    monetary:
      energy_cap: 35
      purchase: 2000
```

By introducing this, the boiler now has a binary decision variable associated with it, which is 1 if the boiler has a non-zero `energy_cap` (i.e. the optimisation results in investment in a boiler) and 0 if the capacity is 0. The purchase cost is applied to the binary result, providing a fixed cost on purchase of the technology, irrespective of the technology size. In physical terms, this may be associated with the cost of pipework, land purchase, etc. The purchase cost is also imposed on the CHP, which is applied to the number of integer CHP units in which the solver chooses to invest.

MILP functionality can be easily applied, but convergence is slower as a result of integer/binary variables. It is recommended to use a commercial solver (e.g. Gurobi, CPLEX) if you wish to utilise these variables outside this example model.

## Running the model

We now take you through running the model in a Jupyter notebook, which is included fully below. To download and run the notebook yourself, you can find it [here](#). You will need to have Calliope installed.

## 1.8 More info

This section, as the title suggests, contains more info and more details, and in particular, information on some of Calliope's more advanced functionality.

We suggest you read the *Building a model*, *Running a model* and *Analysing a model* sections first.

### 1.8.1 Advanced functionality

#### Per-distance constraints and costs

Transmission technologies can additionally specify per-distance efficiency (loss) with `energy_eff_per_distance` and per-distance costs with `energy_cap_per_distance`:

```
techs:
  my_transmission_tech:
    essentials:
      ...
    constraints:
      # "efficiency" (1-loss) per unit of distance
      energy_eff_per_distance: 0.99
```

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```
costs:
  monetary:
    # cost per unit of distance
    energy_cap_per_distance: 10
```

The distance is specified in transmission links:

```
links:
  location1,location2:
    my_transmission_tech:
      distance: 500
      constraints:
        e_cap.max: 10000
```

If no distance is given, but the locations have been given lat and lon coordinates, Calliope will compute distances automatically (based on the length of a straight line connecting the locations).

### One-way transmission links

Transmission links are bidirectional by default. To force unidirectionality for a given technology along a given link, you have to set the `one_way` constraint in the constraint definition of that technology, for that link:

```
links:
  location1,location2:
    transmission-tech:
      constraints:
        one_way: true
```

This will only allow transmission from `location1` to `location2`. To swap the direction, the link name must be inverted, i.e. `location2,location1`.

### Time series data

---

**Note:** If a parameter is not explicit in time and space, it can be specified as a single value in the model definition (or, using location-specific definitions, be made spatially explicit). This applies both to parameters that never vary through time (for example, cost of installed capacity) and for those that may be time-varying (for example, a technology's available resource).

---

For parameters that vary in time, time series data can be read from CSV files, by specifying `resource: file=filename.csv` to pick the desired CSV file from within the configured timeseries data path (`model.timeseries_data_path`).

By default, Calliope looks for a column in the CSV file with the same name as the location. It is also possible to specify a column too use when setting `resource` per location, by giving the column name with a colon following the filename: `resource: file=filename.csv:column`

All time series data in a model must be indexed by ISO 8601 compatible time stamps (usually in the format `YYYY-MM-DD hh:mm:ss`, e.g. `2005-01-01 00:00:00`), i.e., the first column in the CSV file must be time stamps.

For example, the first few lines of a CSV file giving a resource potential for two locations might look like this:

```
,location1,location2
2005-01-01 00:00:00,0,0
2005-01-01 01:00:00,0,11
2005-01-01 02:00:00,0,18
2005-01-01 03:00:00,0,49
2005-01-01 04:00:00,11,110
2005-01-01 05:00:00,45,300
2005-01-01 06:00:00,90,458
```

## Time resolution adjustment

Models have a default timestep length (defined implicitly by the timesteps of the model's time series data). This default resolution can be adjusted over parts of the dataset by specifying time resolution adjustment in the model configuration, for example:

```
model:
  time:
    function: resample
    function_options: {'resolution': '6H'}
```

In the above example, this would resample all time series data to 6-hourly timesteps.

Calliope's time resolution adjustment functionality allows running a function that can perform arbitrary adjustments to the time series data in the model.

The available options include:

1. Uniform time resolution reduction through the `resample` function, which takes a [pandas-compatible rule describing the target resolution](#) (see above example).
2. Deriving representative days from the input time series, by applying the clustering method implemented in `calliope.time.clustering`, for example:

```
model:
  time:
    function: apply_clustering
    function_options:
      clustering_func: kmeans
      how: mean
      k: 20
```

When using representative days, a number of additional constraints are added, based on the study undertaken by [Kotzur et al.](#) These constraints require a new decision variable `storage_inter_cluster`, which tracks storage between all the dates of the original timeseries. This particular functionality can be disabled by including `storage_inter_cluster: false` in the `function_options` given above.

**Note:** It is also possible to load user-defined representative days, by pointing to a file in `clustering_func` in the same format as pointing to timeseries files in constraints, e.g. `clustering_func: file=clusters.csv:column_name`. Clusters are unique per datestep, so the clustering file is most readable if the index is at datestep resolution. But, the clustering file index can be in timesteps (e.g. if sharing the same file as a constraint timeseries), with the cluster number repeated per timestep in a day. Cluster values should be integer, starting at zero.

3. Heuristic selection of time steps, that is, the application of one or more of the masks defined in `calliope.time.masks`, which will mark areas of the time series to retain at maximum resolution (unmasked) and areas where resolution can be lowered (masked). Options can be passed to the masking functions by specifying

options. A `time.function` can still be specified and will be applied to the masked areas (i.e. those areas of the time series not selected to remain at the maximum resolution), as in this example, which looks for the week of minimum and maximum potential wind generation (assuming a `wind` technology was specified), then reduces the rest of the input time series to 6-hourly resolution:

```
model:
  time:
    masks:
      - {function: extreme, options: {padding: 'calendar_week', tech: 'wind',
↪how: 'max'}}
      - {function: extreme, options: {padding: 'calendar_week', tech: 'wind',
↪how: 'min'}}
    function: resample
    function_options: {'resolution': '6H'}
```

**Warning:** When using time clustering or time masking, the resulting timesteps will be assigned different weights depending on how long a period of time they represent. Weights are used for example to give appropriate weight to the operational costs of aggregated typical days in comparison to individual extreme days, if both exist in the same processed time series. The weighting is accessible in the model data, e.g. through `Model.inputs.timestep_weights`. The interpretation of results when weights are not 1 for all timesteps requires caution. Production values are not scaled according to weights, but costs are multiplied by weight, in order to weight different timesteps appropriately in the objective function. This means that costs and production values are not consistent without manually post-processing them by either multiplying production by weight (production would then be inconsistent with capacity) or dividing costs by weight. The computation of levelised costs and of capacity factors takes weighting into account, so these values are consistent and can be used as usual.

#### See also:

See the implementation of constraints in `calliope.backend.pyomo.constraints` for more detail on timestep weights and how they affect model constraints.

### The `supply_plus` tech

The `plus` tech groups offer complex functionality, for technologies which cannot be described easily. `Supply_plus` allows a supply technology with internal storage of resource before conversion to the carrier happens. This could be emulated with dummy carriers and a combination of supply, storage, and conversion techs, but the `supply_plus` tech allows for concise and mathematically more efficient formulation.

Fig. 14: Representation of the `supply_plus` technology

An example use of `supply_plus` is to define a concentrating solar power (CSP) technology which consumes a solar resource, has built-in thermal storage, and produces electricity. See the [national-scale built-in example model](#) for an application of this.

See the [listing of supply\\_plus configuration](#) in the abstract base tech group definitions for the additional constraints that are possible.

**Warning:** When analysing results from `supply_plus`, care must be taken to correctly account for the losses along the transformation from resource to carrier. For example, charging of storage from the resource may have a `resource_eff`-associated loss with it, while discharging storage to produce the carrier may have a different

loss resulting from a combination of `energy_eff` and `parasitic_eff`. Such intermediate conversion losses need to be kept in mind when comparing discharge from storage with `carrier_prod` in the same time step.

## Cyclic storage

With `storage` and `supply_plus` techs, it is possible to link the storage at either end of the timeseries. This allows the user to better represent multiple years by just modelling one year. By activating cyclic storage (`run.cyclic_storage: true`), the initial stored energy for each storage technology at each location passed to the model's first timestep will be equal to the stored energy at the end of the model's last timestep.

For example, for a model running over a full year at hourly resolution, the initial storage at *Jan 1st 00:00:00* will be forced equal to the storage at the end of the timestep *Dec 31st 23:00:00*. By setting `storage_initial` for a technology, it is also possible to fix the value in the last timestep. For instance, with `run.cyclic_storage: true` and a `storage_initial` of zero, the stored energy *must* be zero by the end of the time horizon.

Without cyclic storage in place (as was the case prior to v0.6.2), the storage tech can have any amount of stored energy by the end of the timeseries. This may prove useful in some cases, but has less physical meaning than assuming cyclic storage.

---

**Note:** Cyclic storage also functions when time clustering, if allowing storage to be tracked between clusters (see *Time resolution adjustment*). However, it cannot be used in `operate` run mode.

---

## The `conversion_plus` tech

The `plus` tech groups offer complex functionality, for technologies which cannot be described easily. `Conversion_plus` allows several carriers to be converted to several other carriers. Describing such a technology requires that the user understands the `carrier_ratios`, i.e. the interactions and relative efficiencies of carrier inputs and outputs.

Fig. 15: Representation of the most complex `conversion_plus` technology available

The `conversion_plus` technologies allows for up to three **carrier groups** as inputs (`carrier_in`, `carrier_in_2` and `carrier_in_3`) and up to three carrier groups as outputs (`carrier_out`, `carrier_out_2` and `carrier_out_3`). A carrier group can contain any number of carriers.

The efficiency of a `conversion_plus` tech dictates how many units of `carrier_out` are produced per unit of consumed `carrier_in`. A unit of `carrier_out_2` and of `carrier_out_3` is produced each time a unit of `carrier_out` is produced. Similarly, a unit of `Carrier_in_2` and of `carrier_in_3` is consumed each time a unit of `carrier_in` is consumed. Within a given carrier group (e.g. `carrier_out_2`) any number of carriers can meet this one unit. The `carrier_ratio` of any carrier compares it either to the production of one unit of `carrier_out` or to the consumption of one unit of `carrier_in`.

In this section, we give examples of a few `conversion_plus` technologies alongside the YAML formulation required to construct them:

## Combined heat and power

A combined heat and power plant produces electricity, in this case from natural gas. Waste heat that is produced can be used to meet nearby heat demand (e.g. via district heating network). For every unit of electricity produced, 0.8 units of heat are always produced. This is analogous to the heat to power ratio (HTP). Here, the HTP is 0.8.

```
chp:
  essentials:
    name: Combined heat and power
    carrier_in: gas
    carrier_out: electricity
    carrier_out_2: heat
    primary_carrier_out: electricity
  constraints:
    energy_eff: 0.45
    energy_cap_max: 100
    carrier_ratios.carrier_out_2.heat: 0.8
```

### Air source heat pump

The output energy from the heat pump can be *either* heat or cooling, simulating a heat pump that can be useful in both summer and winter. For each unit of electricity input, one unit of output is produced. Within this one unit of `carrier_out`, there can be a combination of heat and cooling. Heat is produced with a COP of 5, cooling with a COP of 3. If only heat were produced in a timestep, 5 units of it would be available in `carrier_out`; similarly 3 units for cooling. In another timestep, both heat and cooling might be produced with e.g. 2.5 units heat + 1.5 units cooling = 1 unit of `carrier_out`.

```
ahp:
  essentials:
    name: Air source heat pump
    carrier_in: electricity
    carrier_out: [heat, cooling]
    primary_carrier_out: heat

  constraints:
    energy_eff: 1
    energy_cap_max: 100
    carrier_ratios:
      carrier_out:
        heat: 5
        cooling: 3
```

### Combined cooling, heat and power (CCHP)

A CCHP plant can use generated heat to produce cooling via an absorption chiller. As with the CHP plant, electricity is produced at 45% efficiency. For every unit of electricity produced, 1 unit of `carrier_out_2` must be produced, which can be a combination of 0.8 units of heat and 0.5 units of cooling. Some example ways in which the model could decide to operate this unit in a given time step are:

- 1 unit of gas (`carrier_in`) is converted to 0.45 units of electricity (`carrier_out`) and  $(0.8 * 0.45)$  units of heat (`carrier_out_2`)
- 1 unit of gas is converted to 0.45 units electricity and  $(0.5 * 0.45)$  units of cooling
- 1 unit of gas is converted to 0.45 units electricity,  $(0.3 * 0.8 * 0.45)$  units of heat, and  $(0.7 * 0.5 * 0.45)$  units of cooling

```

cchp:
  essentials:
    name: Combined cooling, heat and power
    carrier_in: gas
    carrier_out: electricity
    carrier_out_2: [heat, cooling]
    primary_carrier_out: electricity

  constraints:
    energy_eff: 0.45
    energy_cap_max: 100
    carrier_ratios.carrier_out_2: {heat: 0.8, cooling: 0.5}

```

### Advanced gas turbine

This technology can choose to burn methane (CH<sub>4</sub>) or send hydrogen (H<sub>2</sub>) through a fuel cell to produce electricity. One unit of `carrier_in` can be met by any combination of methane and hydrogen. If all methane, 0.5 units of `carrier_out` would be produced for 1 unit of `carrier_in` (`energy_eff`). If all hydrogen, 0.25 units of `carrier_out` would be produced for the same amount of `carrier_in` (`energy_eff` \* hydrogen carrier ratio).

```

gt:
  essentials:
    name: Advanced gas turbine
    carrier_in: [methane, hydrogen]
    carrier_out: electricity

  constraints:
    energy_eff: 0.5
    energy_cap_max: 100
    carrier_ratios:
      carrier_in: {methane: 1, hydrogen: 0.5}

```

### Complex fictional technology

There are few instances where using the full capacity of a `conversion_plus` tech is physically possible. Here, we have a fictional technology that combines fossil fuels with biomass/waste to produce heat, cooling, and electricity. Different ‘grades’ of heat can be produced, the higher grades having an alternative. High grade heat (`high_T_heat`) is produced and can be used directly, or used to produce electricity (via e.g. organic rankine cycle). `carrier_out` is thus a combination of these two. `carrier_out_2` can be 0.3 units mid grade heat for every unit `carrier_out` or 0.2 units cooling. Finally, 0.1 units `carrier_out_3`, low grade heat, is produced for every unit of `carrier_out`.

```

complex:
  essentials:
    name: Complex fictional technology
    carrier_in: [coal, gas, oil]
    carrier_in_2: [biomass, waste]
    carrier_out: [high_T_heat, electricity]
    carrier_out_2: [mid_T_heat, cooling]
    carrier_out_3: low_T_heat
    primary_carrier_out: electricity

```

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```
constraints:
  energy_eff: 1
  energy_cap_max: 100
  carrier_ratios:
    carrier_in: {coal: 1.2, gas: 1, oil: 1.6}
    carrier_in_2: {biomass: 1, waste: 1.25}
    carrier_out: {high_T_heat: 0.8, electricity: 0.6}
    carrier_out_2: {mid_T_heat: 0.3, cooling: 0.2}
    carrier_out_3.low_T_heat: 0.15
```

A `primary_carrier_out` must be defined when there are multiple `carrier_out` values defined, similarly `primary_carrier_in` can be defined for `carrier_in`. *primary\_carriers* can be defined as any carrier in a technology's input/output carriers (including secondary and tertiary carriers). The chosen output carrier will be the one to which production costs are applied (reciprocally, input carrier for consumption costs).

---

**Note:** `Conversion_plus` technologies can also export any one of their output carriers, by specifying that carrier as `carrier_export`.

---

## Revenue and export

It is possible to specify revenues for technologies simply by setting a negative cost value. For example, to consider a feed-in tariff for PV generation, it could be given a negative operational cost equal to the real operational cost minus the level of feed-in tariff received.

Export is an extension of this, allowing an energy carrier to be removed from the system without meeting demand. This is analogous to e.g. domestic PV technologies being able to export excess electricity to the national grid. A cost (or negative cost: revenue) can then be applied to export.

---

**Note:** Negative costs can be applied to capacity costs, but the user must ensure a capacity limit has been set. Otherwise, optimisation will be unbounded.

---

## Using `tech_groups` to group configuration

In a large model, several very similar technologies may exist, for example, different kinds of PV technologies with slightly different cost data or with different potentials at different model locations.

To make it easier to specify closely related technologies, `tech_groups` can be used to specify configuration shared between multiple technologies. The technologies then give the `tech_group` as their parent, rather than one of the abstract base technologies.

For example:

```
tech_groups:
  pv:
    essentials:
      parent: supply
      carrier: power
    constraints:
      resource: file=pv_resource.csv
      lifetime: 30
```

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```

costs:
  monetary:
    om_annual_investment_fraction: 0.05
    depreciation_rate: 0.15
techs:
  pv_large_scale:
    essentials:
      parent: pv
      name: 'Large-scale PV'
    constraints:
      energy_cap_max: 2000
    costs:
      monetary:
        e_cap: 750
  pv_rooftop:
    essentials:
      parent: pv
      name: 'Rooftop PV'
    constraints:
      energy_cap_max: 10000
    costs:
      monetary:
        e_cap: 1000

```

None of the `tech_groups` appear in model results, they are only used to group model configuration values.

### Using the `group_share` constraint

The `group_share` constraint can be used to force groups of technologies to fulfill certain shares of supply or capacity.

For example, assuming a model containing a `csp` and a `cold_fusion` power generation technology, we could force at least 85% of power generation in the model to come from these two technologies with the following constraint definition in the model settings:

```

model:
  group_share:
    csp,cold_fusion:
      carrier_prod_min:
        power: 0.85

```

Possible `group_share` constraints with carrier-specific settings are:

- `carrier_prod_min`
- `carrier_prod_max`
- `carrier_prod_equals`

Possible `group_share` constraints with carrier-independent settings are:

- `energy_cap_min`
- `energy_cap_max`
- `energy_cap_equals`

These can be implemented as, for example, to force at most 20% of `energy_cap` to come from the two listed technologies:

```
model:
  group_share:
    csp,cold_fusion:
      energy_cap_max: 0.20
```

---

**Note:** The share given in the `carrier_prod` constraints refer to the use of generation from `supply` and `supply_plus` technologies only. The share given in the `energy_cap` constraints refers to the combined capacity from `supply`, `supply_plus`, `conversion`, and `conversion_plus` technologies.

---

### See also:

The above examples are supplied override groups in the *built-in national-scale example*'s overrides. yaml (`cold_fusion` to define that tech, and `group_share_cold_fusion_prod` or `group_share_cold_fusion_cap` to apply the group share constraints).

## Removing techs, locations and links

By specifying `exists: false` in the model configuration, which can be done through override groups, model components can be removed for debugging or scenario analysis.

This works for:

- Techs: `techs.tech_name.exists: false`
- Locations: `locations.location_name.exists: false`
- Links: `links.location1,location2.exists: false`
- Techs at a specific location: `locations.location_name.techs.tech_name.exists: false`
- Transmission techs at a specific location: `links.location1,location2.techs.transmission_tech.exists: false`

## Operational mode

In planning mode, constraints are given as upper and lower boundaries and the model decides on an optimal system configuration. In operational mode, all capacity constraints are fixed and the system is operated with a receding horizon control algorithm.

To specify a runnable operational model, capacities for all technologies at all locations must have been defined. This can be done by specifying `energy_cap_equals`. In the absence of `energy_cap_equals`, constraints given as `energy_cap_max` are assumed to be fixed in operational mode.

Operational mode runs a model with a receding horizon control algorithm. This requires two additional settings:

```
run:
  operation:
    horizon: 48 # hours
    window: 24 # hours
```

`horizon` specifies how far into the future the control algorithm optimises in each iteration. `window` specifies how many of the hours within `horizon` are actually used. In the above example, decisions on how to operate for each 24-hour window are made by optimising over 48-hour horizons (i.e., the second half of each optimisation run is discarded). For this reason, `horizon` must always be larger than `window`.

## Generating scripts to run a model many times

*Override groups* can be used to run a given model multiple times with slightly changed settings or constraints.

This functionality can be used together with the `calliope generate_runs` command-line tool to generate scripts that run a model many times over in a fully automated way, for example, to explore the effect of different technology costs on model results.

`calliope generate_runs`, at a minimum, must be given the following arguments:

- the model configuration file to use
- the name of the script to create
- `--kind`: Currently, three options are available. `windows` creates a Windows batch (`.bat`) script that runs all models sequentially, `bash` creates an equivalent script to run on Linux or macOS, and `bsub` creates a submission script for a `bsub`-based high-performance cluster.
- `--override_file`: The file that specifies override groups.
- `--groups`: A semicolon-separated list of override groups to generate scripts for, for example, `run1;run2`. A comma is used to group override groups together into a single model – for example, `run1,high_costs;run1,low_costs` would run the model twice, once applying the `run1` and `high_costs` override groups, and once applying `run1` and `low_costs`.

A fully-formed command generating a Windows batch script to run a model four times with each of the override groups “run1”, “run2”, “run3”, and “run4”:

```
calliope generate_runs model.yaml run_model.bat --kind=windows --override_
↪file=overrides.yaml --groups "run1;run2;run3;run4"
```

Optional arguments are:

- `--cluster_threads`: specifies the number of threads to request on a HPC cluster
- `--cluster_mem`: specifies the memory to request on a HPC cluster
- `--cluster_time`: specifies the run time to request on a HPC cluster
- `--additional_args`: A text string of any additional arguments to pass directly through to `calliope run` in the generated scripts, for example, `--additional_args="--debug"`.
- `--debug`: Print additional debug information when running the run generation script.

An example generating a script to run on a `bsub`-type high-performance cluster, with additional arguments to specify the resources to request from the cluster:

```
calliope generate_runs model.yaml submit_runs.sh --kind=bsub --cluster_mem=1G --
↪cluster_time=100 --cluster_threads=5 --override_file=overrides.yaml --groups "run1,
↪run2,run3,run4"
```

Running this will create two files:

- `submit_runs.sh`: The cluster submission script to pass to `bsub` on the cluster.
- `submit_runs.array.sh`: The accompanying script defining the runs for the cluster to execute.

In all cases, results are saved into the same directory as the script, with filenames of the form `out_{run_number}_{groups}.nc` (model results) and `plots_{run_number}_{groups}.html` (HTML plots), where `{run_number}` is the run number and `{groups}` is the specified set of groups. On a cluster, log files are saved to files with names starting with `log_` in the same directory.

## Binary and mixed-integer models

Calliope models are purely linear by default. However, several constraints can turn a model into a binary or mixed-integer model. Because solving problems with binary or integer variables takes considerably longer than solving purely linear models, it usually makes sense to carefully consider whether the research question really necessitates going beyond a purely linear model.

By applying a `purchase` cost to a technology, that technology will have a binary variable associated with it, describing whether or not it has been “purchased”.

By applying `units.max`, `units.min`, or `units.equals` to a technology, that technology will have an integer variable associated with it, describing how many of that technology have been “purchased”. If a `purchase` cost has been applied to this same technology, the purchasing cost will be applied per unit.

**Warning:** Integer and binary variables are a recent addition to Calliope and may not cover all edge cases as intended. Please [raise an issue on GitHub](#) if you see unexpected behavior.

See also:

*Tutorial 3: Mixed Integer Linear Programming*

## Interfacing with the solver backend

On loading a model, there is no solver backend, only the input dataset. The backend is generated when a user calls `run()` on their model. Currently this will call back to Pyomo to build the model and send it off to the solver, given by the user in the run configuration `run.solver`. Once built, solved, and returned, the user has access to the results dataset `model.results` and interface functions with the backend `model.backend`.

You can use this interface to:

1. **Get the raw data on the inputs used in the optimisation.** By running `model.backend.get_input_params()` a user get an xarray Dataset which will look very similar to `model.inputs`, except that assumed default values will be included. You may also spot a bug, where a value in `model.inputs` is different to the value returned by this function.
2. **Update a parameter value.** If you are interested in updating a few values in the model, you can run `model.backend.update_param()`. For example, to update your the energy efficiency of your `ccgt` technology in location `region1` from 0.5 to 0.1, you can run `model.backend.update_param('energy_eff', 'region1:ccgt', 0.1)`. This will not affect results at this stage, you'll need to rerun the backend (point 4) to optimise with these new values.
3. **Activate / Deactivate a constraint or objective.** Constraints can be activated and deactivate such that they will or will not have an impact on the optimisation. All constraints are active by default, but you might like to remove, for example, a capacity constraint if you don't want there to be a capacity limit for any technologies. Similarly, if you had multiple objectives, you could deactivate one and activate another. The result would be to have a different objective when rerunning the backend.

---

**Note:** Currently Calliope does not allow you to build multiple objectives, you will need to [understand Pyomo](#) and add an additional objective yourself to make use of this functionality. The Pyomo `ConcreteModel()` object can be accessed at `model._backend_model`.

---

4. **Rerunning the backend.** If you have edited parameters or constraint activation, you will need to rerun the optimisation to propagate the effects. By calling `model.backend.rerun()`, the optimisation will run again, with the updated backend. This will not affect your model, but instead will return a dataset

of the inputs/results associated with that *specific* rerun. It is up to you to store this dataset as you see fit. `model.results` will remain to be the initial run, and can only be overwritten by `model.run(force_rerun=True)`.

---

**Note:** By calling `model.run(force_rerun=True)` any updates you have made to the backend will be overwritten.

---

**See also:**

*Pyomo backend interface*

## Debugging failing runs

A Calliope model provides a method to save a fully built and commented model to a single YAML file with `Model.save_commented_model_yaml(path)`. Comments in the resulting YAML file indicate where values were overridden.

Because this is Calliope’s internal representation of a model directly before the `model_data xarray.Dataset` is built, it can be useful for debugging possible issues in the model formulation, for example, undesired constraints that exist at specific locations because they were specified model-wide without having been superseded by location-specific settings.

Two configuration settings can further aid in debugging failing models:

`model.subset_time` allows specifying a subset of timesteps to be used. This can be useful for debugging purposes as it can dramatically speed up model solution times. The timestep subset can be specified as `[startdate, enddate]`, e.g. `['2005-01-01', '2005-01-31']`, or as a single time period, such as `2005-01` to select January only. The subsets are processed before building the model and applying time resolution adjustments, so time resolution reduction functions will only see the reduced set of data.

`run.save_logs` Off by default, if given, sets the directory into which to save logs and temporary files from the backend, to inspect solver logs and solver-generated model files. This also turns on symbolic solver labels in the Pyomo backend, so that all model components in the backend model are named according to the corresponding Calliope model components (by default, Pyomo uses short random names for all generated model components).

**See also:**

If using Calliope interactively in a Python session, we recommend reading up on the [Python debugger](#) and (if using Jupyter notebooks) making use of the `%debug` magic.

## Solver options

### Gurobi

Refer to the [Gurobi manual](#), which contains a list of parameters. Simply use the names given in the documentation (e.g. “NumericFocus” to set the numerical focus value). For example:

```
run:
  solver: gurobi
  solver_options:
    Threads: 3
    NumericFocus: 2
```

## CPLEX

Refer to the [CPLEX parameter list](#). Use the “Interactive” parameter names, replacing any spaces with underscores (for example, the memory reduction switch is called “emphasis memory”, and thus becomes “emphasis\_memory”). For example:

```
run:
  solver: cplex
  solver_options:
    mipgap: 0.01
    mip_polishafter_absmipgap: 0.1
    emphasis_mip: 1
    mip_cuts: 2
    mip_cuts_cliques: 3
```

### 1.8.2 Built-in example models

This section gives a listing of all the YAML configuration files included in the built-in example models. Refer to the [tutorials section](#) for a brief overview of how these parts together provide a working model.

The example models are accessible in the `calliope.examples` module. To create an instance of an example model, call its constructor function, e.g.:

```
urban_model = calliope.examples.urban_scale()
```

The available example models and their constructor functions are:

`calliope.examples.national_scale(*args, **kwargs)`

Returns the built-in national-scale example model.

`calliope.examples.time_clustering(*args, **kwargs)`

Returns the built-in national-scale example model with time clustering.

`calliope.examples.time_resampling(*args, **kwargs)`

Returns the built-in national-scale example model with time resampling.

`calliope.examples.urban_scale(*args, **kwargs)`

Returns the built-in urban-scale example model.

`calliope.examples.milp(*args, **kwargs)`

Returns the built-in urban-scale example model with MILP constraints enabled.

`calliope.examples.operate(*args, **kwargs)`

Returns the built-in urban-scale example model in operate mode.

`calliope.examples.time_masking(*args, **kwargs)`

Returns the built-in urban-scale example model with time masking.

#### National-scale example

Available as `calliope.examples.national_scale`.

#### Model settings

The layout of the model directory is as follows (+ denotes directories, – files):

```

- model.yaml
- overrides.yaml
+ timeseries_data
  - csp_resource.csv
  - demand-1.csv
  - demand-2.csv
+ model_config
  - locations.yaml
  - techs.yaml

```

model.yaml:

```

import: # Import other files from paths relative to this file, or absolute paths
  - 'model_config/techs.yaml' # This file specifies the model's technologies
  - 'model_config/locations.yaml' # This file specifies the model's locations

# Model configuration: all settings that affect the built model
model:
  name: National-scale example model

  # What version of Calliope this model is intended for
  calliope_version: 0.6.2

  # Time series data path - can either be a path relative to this file, or an
  ↪absolute path
  timeseries_data_path: 'timeseries_data'

  subset_time: ['2005-01-01', '2005-01-05'] # Subset of timesteps

# Run configuration: all settings that affect how the built model is run
run:
  solver: glpk

  ensure_feasibility: true # Switches on the "unmet demand" constraint

  bigM: 1e6 # Sets the scale of unmet demand, which cannot be too high, otherwise
  ↪the optimisation will not converge

  zero_threshold: 1e-10 # Any value coming out of the backend that is smaller than
  ↪this (due to floating point errors, probably) will be set to zero

  mode: plan # Choices: plan, operate

```

overrides.yaml:

```

##
# Overrides for different example model configurations
##

profiling:
  model.name: 'National-scale example model (profiling run)'
  model.subset_time: ['2005-01-01', '2005-01-15']
  run.solver: glpk

time_resampling:
  model.name: 'National-scale example model with time resampling'
  model.subset_time: '2005-01'

```

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```

# Resample time resolution to 6-hourly
model.time: {function: resample, function_options: {'resolution': '6H'}}

time_clustering:
  model.random_seed: 23
  model.name: 'National-scale example model with time clustering'
  model.subset_time: null # No time subsetting
  # Cluster timesteps using k-means
  model.time: {function: apply_clustering, function_options: {clustering_func:
↪ 'kmeans', how: 'closest', k: 10}}

operate_mode:
  run.mode: operate
  run.operation:
    window: 12
    horizon: 24
  techs.csp.constraints.charge_rate: 0.0162857697 # energy_cap_max / storage_cap_max
  techs.csp.constraints.energy_cap_max: null
  techs.battery.constraints.storage_cap_max: null

check_feasibility:
  run:
    ensure_feasibility: False
    objective: 'check_feasibility'
  model:
    subset_time: '2005-01-04'

reserve_margin:
  model:
    # Model-wide settings for the system-wide reserve margin
    # Even setting a reserve margin of zero activates the constraint,
    # forcing enough installed capacity to cover demand in
    # the maximum demand timestep
  reserve_margin:
    power: 0.10 # 10% reserve margin for power

##
# Overrides to demonstrate the run generator ("calliope generate_runs")
##

run1:
  model.subset_time: ['2005-01-01', '2005-01-31']
run2:
  model.subset_time: ['2005-02-01', '2005-02-31']
run3:
  model.subset_time: ['2005-01-01', '2005-01-31']
  locations.region1.techs.ccg_t.constraints.energy_cap_max: 0 # Disallow CCGT
run4:
  subset_time: ['2005-02-01', '2005-02-31']
  locations.region1.techs.ccg_t.constraints.energy_cap_max: 0 # Disallow CCGT

##
# Overrides to demonstrate the group_share constraints
##

cold_fusion: # Defines a hypothetical cold fusion tech to use in group_share
  techs:

```

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```

cold_fusion:
  essentials:
    name: 'Cold fusion'
    color: '#233B39'
    parent: supply
    carrier_out: power
  constraints:
    energy_cap_max: 10000
    lifetime: 50
  costs:
    monetary:
      interest_rate: 0.20
      energy_cap: 100
locations.region1.techs.cold_fusion: null
locations.region2.techs.cold_fusion: null

group_share_cold_fusion_prod:
  model:
    group_share:
      # At least 85% of power supply must come from CSP and cold fusion together
      csp,cold_fusion:
        carrier_prod_min:
          power: 0.85

group_share_cold_fusion_cap:
  model:
    group_share:
      # At most 20% of total energy_cap can come from CSP and cold fusion,
      ↪together
      csp,cold_fusion:
        energy_cap_max: 0.20
  locations:
    region1:
      techs:
        ccgt:
          constraints:
            energy_cap_max: 100000 # Increased to keep model feasible

minimize_emissions_costs:
  run:
    objective_options:
      cost_class: emissions
  techs:
    ccgt:
      costs:
        emissions:
          om_prod: 100 # kgCO2/kWh
    csp:
      costs:
        emissions:
          om_prod: 10 # kgCO2/kWh

maximize_utility_costs:
  run:
    objective_options:
      cost_class: utility
      sense: maximize

```

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```

techs:
  ccgt:
    costs:
      utility:
        om_prod: 10 # arbitrary utility value
  csp:
    costs:
      utility:
        om_prod: 100 # arbitrary utility value

```

techs.yaml:

```

##
# TECHNOLOGY DEFINITIONS
##

# Note: '-start' and '-end' is used in tutorial documentation only

techs:

  ##
  # Supply
  ##

  # ccgt-start
  ccgt:
    essentials:
      name: 'Combined cycle gas turbine'
      color: '#E37A72'
      parent: supply
      carrier_out: power
    constraints:
      resource: inf
      energy_eff: 0.5
      energy_cap_max: 40000 # kW
      energy_cap_max_systemwide: 100000 # kW
      energy_ramping: 0.8
      lifetime: 25
    costs:
      monetary:
        interest_rate: 0.10
        energy_cap: 750 # USD per kW
        om_con: 0.02 # USD per kWh
  # ccgt-end

  # csp-start
  csp:
    essentials:
      name: 'Concentrating solar power'
      color: '#F9CF22'
      parent: supply_plus
      carrier_out: power
    constraints:
      storage_cap_max: 614033
      charge_rate: 1
      storage_loss: 0.002
      resource: file=csp_resource.csv

```

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```

    energy_eff: 0.4
    parasitic_eff: 0.9
    resource_area_max: inf
    energy_cap_max: 10000
    lifetime: 25
  costs:
    monetary:
      interest_rate: 0.10
      storage_cap: 50
      resource_area: 200
      resource_cap: 200
      energy_cap: 1000
      om_prod: 0.002
# csp-end

##
# Storage
##
# battery-start
battery:
  essentials:
    name: 'Battery storage'
    color: '#3B61E3'
    parent: storage
    carrier: power
  constraints:
    energy_cap_max: 1000 # kW
    storage_cap_max: inf
    charge_rate: 4
    energy_eff: 0.95 # 0.95 * 0.95 = 0.9025 round trip efficiency
    storage_loss: 0 # No loss over time assumed
    lifetime: 25
  costs:
    monetary:
      interest_rate: 0.10
      storage_cap: 200 # USD per kWh storage capacity
# battery-end

##
# Demand
##
# demand-start
demand_power:
  essentials:
    name: 'Power demand'
    color: '#072486'
    parent: demand
    carrier: power
# demand-end

##
# Transmission
##

# transmission-start
ac_transmission:
  essentials:

```

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```

    name: 'AC power transmission'
    color: '#8465A9'
    parent: transmission
    carrier: power
  constraints:
    energy_eff: 0.85
    lifetime: 25
  costs:
    monetary:
      interest_rate: 0.10
      energy_cap: 200
      om_prod: 0.002

  free_transmission:
    essentials:
      name: 'Local power transmission'
      color: '#6783E3'
      parent: transmission
      carrier: power
    constraints:
      energy_cap_max: inf
      energy_eff: 1.0
    costs:
      monetary:
        om_prod: 0
# transmission-end

```

locations.yaml:

```

##
# LOCATIONS
##

locations:
  # region-1-start
  region1:
    coordinates: {lat: 40, lon: -2}
    techs:
      demand_power:
        constraints:
          resource: file=demand-1.csv:demand
      ccgt:
        constraints:
          energy_cap_max: 30000 # increased to ensure no unmet_demand in_
↪first timestep
  # region-1-end
  # other-locs-start
  region2:
    coordinates: {lat: 40, lon: -8}
    techs:
      demand_power:
        constraints:
          resource: file=demand-2.csv:demand
      battery:

  region1-1.coordinates: {lat: 41, lon: -2}
  region1-2.coordinates: {lat: 39, lon: -1}

```

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```

region1-3.coordinates: {lat: 39, lon: -2}

region1-1, region1-2, region1-3:
  techs:
    csp:
      # other-locs-end

##
# TRANSMISSION CAPACITIES
##

links:
  # links-start
  region1,region2:
    techs:
      ac_transmission:
        constraints:
          energy_cap_max: 10000
  region1,region1-1:
    techs:
      free_transmission:
  region1,region1-2:
    techs:
      free_transmission:
  region1,region1-3:
    techs:
      free_transmission:
  # links-end

```

## Urban-scale example

Available as `calliope.examples.urban_scale`.

## Model settings

model.yaml:

```

import: # Import other files from paths relative to this file, or absolute paths
  - 'model_config/techs.yaml'
  - 'model_config/locations.yaml'

model:
  name: Urban-scale example model

  # What version of Calliope this model is intended for
  calliope_version: 0.6.2

  # Time series data path - can either be a path relative to this file, or an_
  ↪absolute path
  timeseries_data_path: 'timeseries_data'

  subset_time: ['2005-07-01', '2005-07-02'] # Subset of timesteps

run:

```

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```

mode: plan # Choices: plan, operate

solver: glpk

ensure_feasibility: true # Switching on unmet demand

bigM: 1e6 # setting the scale of unmet demand, which cannot be too high,
↳otherwise the optimisation will not converge

```

overrides.yaml:

```

##
# Overrides for different example model configuratiions
##

milp:
  model.name: 'Urban-scale example model with MILP'
  techs:
    # chp-start
    chp:
      constraints:
        units_max: 4
        energy_cap_per_unit: 300
        energy_cap_min_use: 0.2
      costs:
        monetary:
          energy_cap: 700
          purchase: 40000
    # chp-end
    # boiler-start
    boiler:
      costs:
        monetary:
          energy_cap: 35
          purchase: 2000
    # boiler-end

mapbox_ready:
  locations:
    X1.coordinates: {lat: 51.4596158, lon: -0.1613446}
    X2.coordinates: {lat: 51.4652373, lon: -0.1141548}
    X3.coordinates: {lat: 51.4287016, lon: -0.1310635}
    N1.coordinates: {lat: 51.4450766, lon: -0.1247183}
  links:
    X1,X2.techs.power_lines.distance: 10
    X1,X3.techs.power_lines.istance: 5
    X1,N1.techs.heat_pipes.distance: 3
    N1,X2.techs.heat_pipes.distance: 3
    N1,X3.techs.heat_pipes.distance: 4

operate:
  run.mode: operate
  run.operation:
    window: 24
    horizon: 48
  model.subset_time: ['2005-07-01', '2005-07-10']
  locations:

```

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```

X1:
  techs:
    chp.constraints.energy_cap_max: 300
    pv.constraints.energy_cap_max: 0
    supply_grid_power.constraints.energy_cap_max: 40
    supply_gas.constraints.energy_cap_max: 700

X2:
  techs:
    boiler.constraints.energy_cap_max: 200
    pv.constraints.energy_cap_max: 70
    supply_gas.constraints.energy_cap_max: 250

X3:
  techs:
    boiler.constraints.energy_cap_max: 0
    pv.constraints.energy_cap_max: 50
    supply_gas.constraints.energy_cap_max: 0

links:
  X1,X2.techs.power_lines.constraints.energy_cap_max: 300
  X1,X3.techs.power_lines.constraints.energy_cap_max: 60
  X1,N1.techs.heat_pipes.constraints.energy_cap_max: 300
  N1,X2.techs.heat_pipes.constraints.energy_cap_max: 250
  N1,X3.techs.heat_pipes.constraints.energy_cap_max: 320

time_masking:
  model.name: 'Urban-scale example model with time masking'
  model.subset_time: '2005-01'
  # Resample time resolution to 6-hourly
  model.time:
    masks:
      - {function: extreme_diff, options: {tech0: demand_heat, tech1: demand_
→electricity, how: max, n: 2}}
      function: resample
      function_options: {resolution: 6H}

```

techs.yaml:

```

##
# TECHNOLOGY DEFINITIONS
##

# Note: '-start' and '-end' is used in tutorial documentation only

# supply_power_plus-start
tech_groups:
  supply_power_plus:
    essentials:
      parent: supply_plus
      carrier: electricity
# supply_power_plus-end

techs:

##-GRID SUPPLY-##
# supply-start

```

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```

supply_grid_power:
  essentials:
    name: 'National grid import'
    color: '#C5ABE3'
    parent: supply
    carrier: electricity
  constraints:
    resource: inf
    energy_cap_max: 2000
    lifetime: 25
  costs:
    monetary:
      interest_rate: 0.10
      energy_cap: 15
      om_con: 0.1 # 10p/kWh electricity price #ppt

supply_gas:
  essentials:
    name: 'Natural gas import'
    color: '#C98AAD'
    parent: supply
    carrier: gas
  constraints:
    resource: inf
    energy_cap_max: 2000
    lifetime: 25
  costs:
    monetary:
      interest_rate: 0.10
      energy_cap: 1
      om_con: 0.025 # 2.5p/kWh gas price #ppt
# supply-end

##-Renewables-##
# pv-start
pv:
  essentials:
    name: 'Solar photovoltaic power'
    color: '#F9D956'
    parent: supply_power_plus
  constraints:
    export_carrier: electricity
    resource: file=pv_resource.csv # Already accounts for panel efficiency -
↳ kWh/m2. Source: Renewables.ninja Solar PV Power - Version: 1.1 - License: https://
↳ creativecommons.org/licenses/by-nc/4.0/ - Reference: https://doi.org/10.1016/j.
↳ energy.2016.08.060
    parasitic_eff: 0.85 # inverter losses
    energy_cap_max: 250
    resource_area_max: 1500
    force_resource: true
    resource_area_per_energy_cap: 7 # 7m2 of panels needed to fit 1kWp of
↳ panels
    lifetime: 25
  costs:
    monetary:
      interest_rate: 0.10
      energy_cap: 1350

```

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```

# pv-end

# Conversion
# boiler-start
boiler:
  essentials:
    name: 'Natural gas boiler'
    color: '#8E2999'
    parent: conversion
    carrier_out: heat
    carrier_in: gas
  constraints:
    energy_cap_max: 600
    energy_eff: 0.85
    lifetime: 25
  costs:
    monetary:
      interest_rate: 0.10
      om_con: 0.004 # .4p/kWh
# boiler-end

# Conversion_plus
# chp-start
chp:
  essentials:
    name: 'Combined heat and power'
    color: '#E4AB97'
    parent: conversion_plus
    primary_carrier_out: electricity
    carrier_in: gas
    carrier_out: electricity
    carrier_out_2: heat
  constraints:
    export_carrier: electricity
    energy_cap_max: 1500
    energy_eff: 0.405
    carrier_ratios.carrier_out_2.heat: 0.8
    lifetime: 25
  costs:
    monetary:
      interest_rate: 0.10
      energy_cap: 750
      om_prod: 0.004 # .4p/kWh for 4500 operating hours/year
      export: file=export_power.csv
# chp-end

##-DEMAND-##
# demand-start
demand_electricity:
  essentials:
    name: 'Electrical demand'
    color: '#072486'
    parent: demand
    carrier: electricity

demand_heat:
  essentials:

```

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```

        name: 'Heat demand'
        color: '#660507'
        parent: demand
        carrier: heat
    # demand-end

##-DISTRIBUTION-##
    # transmission-start
    power_lines:
        essentials:
            name: 'Electrical power distribution'
            color: '#6783E3'
            parent: transmission
            carrier: electricity
        constraints:
            energy_cap_max: 2000
            energy_eff: 0.98
            lifetime: 25
        costs:
            monetary:
                interest_rate: 0.10
                energy_cap_per_distance: 0.01

    heat_pipes:
        essentials:
            name: 'District heat distribution'
            color: '#823739'
            parent: transmission
            carrier: heat
        constraints:
            energy_cap_max: 2000
            energy_eff_per_distance: 0.975
            lifetime: 25
        costs:
            monetary:
                interest_rate: 0.10
                energy_cap_per_distance: 0.3
    # transmission-end

```

locations.yaml:

```

locations:
    # X1-start
    X1:
        techs:
            chp:
            pv:
            supply_grid_power:
                costs.monetary.energy_cap: 100 # cost of transformers
            supply_gas:
            demand_electricity:
                constraints.resource: file=demand_power.csv
            demand_heat:
                constraints.resource: file=demand_heat.csv
        available_area: 500
        coordinates: {x: 2, y: 7}
    # X1-end

```

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```

# other-locs-start
X2:
  techs:
    boiler:
      costs.monetary.energy_cap: 43.1 # different boiler costs
    pv:
      costs.monetary:
        om_prod: -0.0203 # revenue for just producing electricity
        export: -0.0491 # FIT return for PV export
      supply_gas:
      demand_electricity:
        constraints.resource: file=demand_power.csv
      demand_heat:
        constraints.resource: file=demand_heat.csv
  available_area: 1300
  coordinates: {x: 8, y: 7}

X3:
  techs:
    boiler:
      costs.monetary.energy_cap: 78 # different boiler costs
    pv:
      constraints:
        energy_cap_max: 50 # changing tariff structure below 50kW
      costs.monetary:
        om_annual: -80.5 # reimbursement per kWp from FIT
      supply_gas:
      demand_electricity:
        constraints.resource: file=demand_power.csv
      demand_heat:
        constraints.resource: file=demand_heat.csv
  available_area: 900
  coordinates: {x: 5, y: 3}
# other-locs-end
# N1-start
N1: # location for branching heat transmission network
  coordinates: {x: 5, y: 7}
# N1-end

links:
# links-start
X1,X2:
  techs:
    power_lines:
      distance: 10
X1,X3:
  techs:
    power_lines:
X1,N1:
  techs:
    heat_pipes:
N1,X2:
  techs:
    heat_pipes:
N1,X3:
  techs:
    heat_pipes:

```

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```
# links-end
```

## 1.8.3 Listing of configuration options

### Configuration layout

There must always be at least one model configuration YAML file, probably called `model.yaml` or similar. This file can import any number of additional files.

This file or this set of files must specify the following top-level configuration keys:

- `name`: the name of the model
- `model`: model settings
- `run`: run settings
- `techs`: technology definitions
- (optionally) `tech_groups`: tech group definitions
- `locations`: location definitions
- (optionally) `links`: transmission link definitions

**Note:** Model settings (`model`) affect how the model and its data are built by Calliope, while run settings (`run`) only take effect once a built model is run (e.g. interactively via `model.run()`). This means that run settings, unlike model settings, can be updated after a model is built and before it is run, by modifying attributes in the built model dataset.

### List of model settings

Setting	Default	Comments
<code>name</code>		Model name
<code>calliope_version</code>		Calliope framework version this model is intended for
<code>timeseries_data_path</code>		Path to time series data
<code>timeseries_dateformat</code>	<code>%Y-%m-%d %H:%M:%S</code>	Timestamp format of all time series data when read from file
<code>timeseries_data</code>		Dict of dataframes with time series data (when passing in dicts rather than YAML files to Model constructor)
<code>subset_time</code>		Subset of timesteps as a two-element list giving the range, e.g. <code>['2005-01-01', '2005-01-05']</code> , or a single string, e.g. <code>'2005-01'</code>
<code>reserve_margin</code>	<code>{}</code>	Per-carrier system-wide reserve margins
<code>random_seed</code>		Seed for random number generator used during clustering
<code>time</code>	<code>{}</code>	Optional settings to adjust time resolution, see <i>Time resolution adjustment</i> for the available options
<code>group_share</code>	<code>{}</code>	Optional settings for the <code>group_share</code> constraint

## List of run settings

Setting	Default	Comments
backend	pyomo	Backend to use to build and solve the model. As of v0.6.0, only <i>pyomo</i> is available
solver	glpk	Which solver to use
solver_options		A list of options, which are passed on to the chosen solver, and are therefore solver-dependent
solver_io		What method the Pyomo backend should use to communicate with the solver
save_logs		Directory into which to save logs and temporary files. Also turns on symbolic solver labels in the Pyomo backend
bigM	1000000000.0	Used for unmet demand, but should be of a similar order of magnitude as the largest cost that the model could achieve. Too high and the model will not converge
ensure_feasibility	False	If true, unmet_demand will be a decision variable, to account for an ability to meet demand with the available supply. If False and a mismatch occurs, the optimisation will fail due to infeasibility
operation	{}	Settings for operational mode
objective	minmax_cost_optimization	Name of internal objective function to use, currently only min/max cost-based optimisation is available
objective_options	{}	Arguments to pass to objective function. If cost-based objective function in use, should include 'cost_class' and 'sense' (maximize/minimize)
mode	plan	Which mode to run the model in: 'plan' or 'operation'
zero_threshold	1e-10	Any value coming out of the backend that is smaller than this threshold (due to floating point errors, probably) will be set to zero
cyclic_storage	False	If true, storage in the last timestep of the timeseries is considered to be the 'previous timestep' in the first timestep of the timeseries

## List of possible constraints

The following table lists all available technology constraint settings and their default values. All of these can be set by `tech_identifier.constraints.constraint_name`, e.g. `nuclear.constraints.e_cap.max`.

Setting	Default	Name	Unit	Comments
lifetime		Technology lifetime	years	Must be defined if fixed capital costs are defined. A reasonable value for many technologies is around 20-25 years.
carrier_ratios	{}	Carrier ratios	fraction	Ratio of summed output of carriers in ['out_2', 'out_3'] / ['in_2', 'in_3'] to the summed output of carriers in 'out' / 'in'. given in a nested dictionary.

Continued on next page

Table 1 – continued from previous page

Setting	Default	Name	Unit	Comments
resource	0	Available resource	kWh/m <sup>2</sup>   kW/m <sup>2</sup>	Maximum available resource (static, or from file as timeseries). Unit dictated by <code>resource_unit</code>
force_resource	False	Force resource	boolean	Forces this technology to use all available <code>resource</code> , rather than making it a maximum upper boundary (for production) or minimum lower boundary (for consumption). Static boolean, or from file as time-series
resource_unit	power	Resource unit	N/A	Sets the unit of <code>resource</code> to either <code>power</code> (i.e. kW) or <code>energy</code> (i.e. kWh), which affects how resource time series are processed when performing time resolution adjustments
resource_eff	1.0	Resource efficiency	fraction	Efficiency (static, or from file as timeseries) in capturing resource before it reaches storage (if storage is present) or conversion to carrier.
resource_area_min	0	Minimum installed collector area	m <sup>2</sup>	
resource_area_max	False	Maximum installed collector area	m <sup>2</sup>	Set to false by default in order to disable this constraint
resource_area_equals	False	Specific installed collector area	m <sup>2</sup>	
resource_area_per_energy_cap	False	Energy capacity per unit collector area	boolean	If set, forces <code>resource_area</code> to follow <code>energy_cap</code> with the given numerical ratio (e.g. setting to 1.5 means that <code>resource_area == 1.5 * energy_cap</code> )
resource_cap_min	0	Minimum installed resource consumption capacity	kW	
resource_cap_max	inf	Maximum installed resource consumption capacity	kW	
resource_cap_equals	False	Specific installed resource consumption capacity	kW	overrides <code>_max</code> and <code>_min</code> constraints.
resource_cap_equals_energy_cap	False	Resource capacity equals energy capacity	boolean	If true, <code>resource_cap</code> is forced to equal <code>energy_cap</code>
resource_min_use	False	Minimum resource consumption	fraction	Set to a value between 0 and 1 to force minimum resource consumption for production technologies
resource_scale	1.0	Resource scale	fraction	Scale resource (either static value or all values in timeseries) by this value
storage_initial	0	Initial storage level	kWh	Set stored energy in device at the first timestep
storage_cap_min	0	Minimum storage capacity	kWh	

Continued on next page

Table 1 – continued from previous page

Setting	Default	Name	Unit	Comments
storage_cap_max	inf	Maximum storage capacity	kWh	If not defined, energy_cap_max * charge_rate will be used as the capacity.
storage_cap_equals	False	Specific storage capacity	kWh	If not defined, energy_cap_equals * charge_rate will be used as the capacity and overrides _max and _min constraints.
storage_cap_per_unit	False	Storage capacity per purchased unit	kWh/unit	Set the storage capacity of each integer unit of a technology purchased.
charge_rate	False	Charge rate	hour <sup>-1</sup>	ratio of maximum charge/discharge (kW) for a given maximum storage capacity (kWh)
storage_loss	0	Storage loss rate	hour <sup>-1</sup>	rate of storage loss per hour (static, or from file as timeseries), used to calculate lost stored energy as $(1 - \text{storage\_loss})^{\text{hours\_per\_timestep}}$
energy_prod	False	Energy production	boolean	Allow this technology to supply energy to the carrier (static boolean, or from file as timeseries).
energy_con	False	Energy consumption	boolean	Allow this technology to consume energy from the carrier (static boolean, or from file as timeseries).
parasitic_eff	1.0	Plant parasitic efficiency	fraction	Additional losses as energy gets transferred from the plant to the carrier (static, or from file as timeseries), e.g. due to plant parasitic consumption
energy_eff	1.0	Energy efficiency	fraction	conversion efficiency (static, or from file as timeseries), from resource/storage/carrier_in (tech dependent) to carrier_out.
energy_eff_per_distance	1.0	Energy efficiency per distance	distance <sup>-1</sup>	Set as value between 1 (no loss) and 0 (all energy lost)
energy_cap_min	0	Minimum installed energy capacity	kW	Limits decision variables carrier_prod/carrier_con to a minimum/maximum.
energy_cap_max	inf	Maximum installed energy capacity	kW	Limits decision variables carrier_prod/carrier_con to a maximum/minimum.
energy_cap_equals	False	Specific installed energy capacity	kW	fixes maximum/minimum if decision variables carrier_prod/carrier_con and overrides _max and _min constraints.

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Table 1 – continued from previous page

Setting	Default	Name	Unit	Comments
energy_cap_max_systemwide	inf	System-wide maximum installed energy capacity	kW	Limits the sum to a maximum/minimum, for a particular technology, of the decision variables <code>carrier_prod/carrier_con</code> over all locations.
energy_cap_equals_systemwide	False	System-wide specific installed energy capacity	kW	fixes the sum to a maximum/minimum, for a particular technology, of the decision variables <code>carrier_prod/carrier_con</code> over all locations.
energy_cap_scale	1.0	Energy capacity scale	float	Scale all <code>energy_cap_min/max/equals/total_max/total_equals</code> constraints by this value
energy_cap_min_use	False	Minimum carrier production	fraction	Set to a value between 0 and 1 to force minimum carrier production as a fraction of the technology maximum energy capacity. If non-zero and technology is not defined by <code>units</code> , this will force the technology to operate above its minimum value at every timestep.
energy_cap_per_unit	False	Energy capacity per purchased unit	kW/unit	Set the capacity of each integer unit of a technology purchased
energy_ramping	False	Ramping rate	fraction / hour	Set to <code>false</code> to disable ramping constraints, otherwise limit maximum carrier production to a fraction of maximum capacity, which increases by that fraction at each timestep.
export_cap	inf	Export capacity	kW	Maximum allowed export of produced energy carrier for a technology.
export_carrier		Export carrier	N/A	Name of carrier to be exported. Must be an output carrier of the technology
units_min	False	Minimum number of purchased units	integer	Turns the model from LP to MILP.
units_max	False	Maximum number of purchased units	integer	Turns the model from LP to MILP.
units_equals	False	Specific number of purchased units	integer	Turns the model from LP to MILP.
units_max_systemwide	inf	System-wide maximum installed energy capacity	kW	Limits the sum to a maximum/minimum, for a particular technology, of the decision variables <code>carrier_prod/carrier_con</code> over all locations.
units_equals_systemwide	False	System-wide specific installed energy capacity	kW	fixes the sum to a



## List of possible costs

These are all the available costs, which are set to 0 by default for every defined cost class. Costs are set by `tech_identifier.costs.cost_class.cost_name`, e.g. `nuclear.costs.monetary.e_cap`.

Setting	Default	Name	Unit	Comments
<code>interest_rate</code>	0	Interest rate	fraction	Used when computing leveled costs
<code>storage_cap</code>	0	Cost of storage capacity	$\text{kWh}^{-1}$	
<code>resource_area</code>	0	Cost of resource collector area	$\text{m}^2$	
<code>resource_cap</code>	0	Cost of resource consumption capacity	$\text{kW}^{-1}$	
<code>energy_cap</code>	0	Cost of energy capacity	$\text{kW}_{\text{gross}}^{-1}$	
<code>energy_cap_per_distance</code>	0	Cost of energy capacity, per unit distance	$\text{kW}_{\text{gross}}^{-1} / \text{distance}$	Applied to transmission links only
<code>om_annual_investment_fraction</code>	fraction	Fractional yearly O&M costs	fraction / total investment	
<code>om_annual</code>	0	Yearly O&M costs	$\text{kW}_{\text{energy\_cap}}^{-1}$	
<code>om_prod</code>	0	Carrier production cost	$\text{kWh}^{-1}$	Applied to carrier production of a technology
<code>om_con</code>	0	Carrier consumption cost	$\text{kWh}^{-1}$	Applied to carrier consumption of a technology
<code>export</code>	0	Carrier export cost	$\text{kWh}^{-1}$	Usually used in the negative sense, as a subsidy.
<code>purchase</code>	0	Purchase cost	$\text{unit}^{-1}$	Triggers a binary variable for that technology to say that it has been purchased or is applied to integer variable <code>units</code>

Technology depreciation settings apply when calculating leveled costs. The interest rate and life times must be set for each technology with investment costs.

## List of abstract base technology groups

Technologies must always define a parent, and this can either be one of the pre-defined abstract base technology groups or a user-defined group (see [Using tech\\_groups to group configuration](#)). The pre-defined groups are:

- `supply`: Supplies energy to a carrier, has a positive resource.
- `supply_plus`: Supplies energy to a carrier, has a positive resource. Additional possible constraints, including efficiencies and storage, distinguish this from `supply`.
- `demand`: Demands energy from a carrier, has a negative resource.
- `storage`: Stores energy.
- `transmission`: Transmits energy from one location to another.

- `conversion`: Converts energy from one carrier to another.
- `conversion_plus`: Converts energy from one or more carrier(s) to one or more different carrier(s).

A technology inherits the configuration that its parent group specifies (which, in turn, may inherit from its own parent).

---

**Note:** The identifiers of the abstract base tech groups are reserved and cannot be used for a user-defined technology or tech group.

---

The following lists the pre-defined base tech groups and the defaults they provide.

### supply

Default constraints provided by the parent tech group:

```
constraints:
  resource: inf
  resource_unit: power
  energy_prod: true
costs: {}
essentials:
  parent:
```

Required constraints, allowed constraints, and allowed costs:

```
allowed_constraints:
- energy_prod
- lifetime
- resource
- force_resource
- resource_min_use
- resource_unit
- resource_area_min
- resource_area_max
- resource_area_equals
- resource_area_per_energy_cap
- resource_scale
- energy_eff
- energy_cap_min
- energy_cap_max
- energy_cap_equals
- energy_cap_max_systemwide
- energy_cap_equals_systemwide
- energy_cap_scale
- energy_cap_min_use
- energy_cap_per_unit
- energy_ramping
- energy_eff_per_distance
- export_cap
- export_carrier
- units_min
- units_max
- units_equals
- units_max_systemwide
```

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```

- units_equals_systemwide
required_constraints:
- [energy_cap_max, energy_cap_equals, energy_cap_per_unit]
allowed_costs:
- interest_rate
- resource_area
- energy_cap
- om_annual_investment_fraction
- om_annual
- om_prod
- om_con
- export
- purchase
- depreciation_rate

```

## supply\_plus

Default constraints provided by the parent tech group:

```

constraints:
  resource: inf
  resource_unit: power
  resource_eff: 1.0
  energy_prod: true
costs: {}
essentials:
  parent:

```

Required constraints, allowed constraints, and allowed costs:

```

allowed_constraints:
- energy_prod
- lifetime
- resource
- force_resource
- resource_min_use
- resource_unit
- resource_eff
- resource_area_min
- resource_area_max
- resource_area_equals
- resource_area_per_energy_cap
- resource_cap_min
- resource_cap_max
- resource_cap_equals
- resource_cap_equals_energy_cap
- resource_scale
- parasitic_eff
- energy_eff
- energy_cap_min
- energy_cap_max
- energy_cap_equals
- energy_cap_max_systemwide

```

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```

- energy_cap_equals_systemwide
- energy_cap_scale
- energy_cap_min_use
- energy_cap_per_unit
- energy_ramping
- energy_eff_per_distance
- export_cap
- export_carrier
- units_min
- units_max
- units_equals
- units_max_systemwide
- units_equals_systemwide
- storage_initial
- storage_cap_min
- storage_cap_max
- storage_cap_equals
- storage_cap_per_unit
- charge_rate
- storage_time_max
- storage_loss
required_constraints:
- [energy_cap_max, energy_cap_equals, energy_cap_per_unit]
allowed_costs:
- interest_rate
- storage_cap
- resource_area
- resource_cap
- energy_cap
- om_annual_investment_fraction
- om_annual
- om_prod
- om_con
- export
- purchase
- depreciation_rate

```

**demand**

Default constraints provided by the parent tech group:

```

constraints:
  resource_unit: power
  force_resource: true
  energy_con: true
costs: {}
essentials:
  parent:

```

Required constraints, allowed constraints, and allowed costs:

```

allowed_constraints:
- energy_con

```

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```

- resource
- force_resource
- resource_unit
- resource_scale
- resource_area_equals
required_constraints:
- resource
allowed_costs: []

```

## storage

Default constraints provided by the parent tech group:

```

constraints:
  energy_prod: true
  energy_con: true
  storage_cap_max: inf
costs: {}
essentials:
  parent:

```

Required constraints, allowed constraints, and allowed costs:

```

allowed_constraints:
- energy_prod
- energy_con
- lifetime
- energy_eff
- energy_cap_min
- energy_cap_max
- energy_cap_equals
- energy_cap_max_systemwide
- energy_cap_equals_systemwide
- energy_cap_scale
- energy_cap_min_use
- energy_cap_per_unit
- energy_ramping
- storage_initial
- storage_cap_min
- storage_cap_max
- storage_cap_equals
- storage_cap_per_unit
- charge_rate
- storage_time_max
- storage_loss
- export_cap
- export_carrier
- units_min
- units_max
- units_equals
- units_max_systemwide
- units_equals_systemwide
required_constraints:

```

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```
- [energy_cap_max, energy_cap_equals, energy_cap_per_unit]
- [storage_cap_max, storage_cap_equals]
allowed_costs:
- interest_rate
- storage_cap
- energy_cap
- om_annual_investment_fraction
- om_annual
- om_prod
- export
- purchase
- depreciation_rate
```

## transmission

Default constraints provided by the parent tech group:

```
constraints:
  energy_prod: true
  energy_con: true
costs: {}
essentials:
  parent:
```

Required constraints, allowed constraints, and allowed costs:

```
allowed_constraints:
- energy_prod
- energy_con
- lifetime
- energy_con
- energy_prod
- energy_eff_per_distance
- energy_eff
- one_way
- energy_cap_scale
required_constraints:
- [energy_cap_max, energy_cap_equals, energy_cap_per_unit]
allowed_costs:
- interest_rate
- energy_cap
- energy_cap_per_distance
- om_annual_investment_fraction
- om_annual
- om_prod
- purchase
- purchase_per_distance
- depreciation_rate
```

## conversion

Default constraints provided by the parent tech group:

```
constraints:
  energy_prod: true
  energy_con: true
costs: {}
essentials:
  parent:
```

Required constraints, allowed constraints, and allowed costs:

```
allowed_constraints:
- energy_prod
- energy_con
- lifetime
- energy_eff
- energy_cap_min
- energy_cap_max
- energy_cap_equals
- energy_cap_max_systemwide
- energy_cap_equals_systemwide
- energy_cap_scale
- energy_cap_min_use
- energy_cap_per_unit
- energy_ramping
- energy_eff_per_distance
- export_cap
- export_carrier
- units_min
- units_max
- units_equals
- units_max_systemwide
- units_equals_systemwide
required_constraints:
- [energy_cap_max, energy_cap_equals, energy_cap_per_unit]
allowed_costs:
- interest_rate
- energy_cap
- om_annual_investment_fraction
- om_annual
- om_prod
- om_con
- export
- purchase
- depreciation_rate
```

## conversion\_plus

Default constraints provided by the parent tech group:

```
constraints:
  energy_prod: true
  energy_con: true
costs: {}
```

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```
essentials:
  parent:
```

Required constraints, allowed constraints, and allowed costs:

```
allowed_constraints:
- energy_prod
- energy_con
- lifetime
- carrier_ratios
- energy_eff
- energy_cap_min
- energy_cap_max
- energy_cap_equals
- energy_cap_max_systemwide
- energy_cap_equals_systemwide
- energy_cap_scale
- energy_cap_min_use
- energy_cap_per_unit
- energy_ramping
- energy_eff_per_distance
- export_cap
- export_carrier
- units_min
- units_max
- units_equals
- units_max_systemwide
- units_equals_systemwide
required_constraints:
- [energy_cap_max, energy_cap_equals, energy_cap_per_unit]
allowed_costs:
- interest_rate
- energy_cap
- om_annual_investment_fraction
- om_annual
- om_prod
- om_con
- export
- purchase
- depreciation_rate
```

### YAML configuration file format

All configuration files (with the exception of time series data files) are in the YAML format, “a human friendly data serialisation standard for all programming languages”.

Configuration for Calliope is usually specified as `option: value` entries, where `value` might be a number, a text string, or a list (e.g. a list of further settings).

Calliope allows an abbreviated form for long, nested settings:

```
one:
  two:
    three: x
```

can be written as:



```
one.two.three: x
```

Calliope also allows a special `import:` directive in any YAML file. This can specify one or several YAML files to import. If both the imported file and the current file define the same option, the definition in the current file takes precedence.

Using quotation marks ( ' or " ) to enclose strings is optional, but can help with readability. The three ways of setting `option` to `text` below are equivalent:

```
option: "text"
option: 'text'
option: text
```

Sometimes, a setting can be either enabled or disabled, in this case, the boolean values `true` or `false` are used.

Comments can be inserted anywhere in YAML files with the `#` symbol. The remainder of a line after `#` is interpreted as a comment.

See the [YAML website](#) for more general information about YAML.

Calliope internally represents the configuration as `AttrDicts`, which are a subclass of the built-in Python dictionary data type (`dict`) with added functionality such as YAML reading/writing and attribute access to keys.

## 1.8.4 Mathematical formulation

This section details the mathematical formulation of the different components. For each component, a link to the actual implementing function in the Calliope code is given.

### Decision variables

`calliope.backend.pyomo.variables.initialize_decision_variables` (*backend\_model*)  
 Defines decision variables.

Variable	Dimensions
<code>energy_cap</code>	<code>loc_techs</code>
<code>carrier_prod</code>	<code>loc_tech_carriers_prod</code> , <code>timesteps</code>
<code>carrier_con</code>	<code>loc_tech_carriers_con</code> , <code>timesteps</code>
<code>cost</code>	<code>costs</code> , <code>loc_techs_cost</code>
<code>resource_area</code>	<code>loc_techs_area</code> ,
<code>storage_cap</code>	<code>loc_techs_store</code>
<code>storage</code>	<code>loc_techs_store</code> , <code>timesteps</code>
<code>resource_con</code>	<code>loc_techs_supply_plus</code> , <code>timesteps</code>
<code>resource_cap</code>	<code>loc_techs_supply_plus</code>
<code>carrier_export</code>	<code>loc_tech_carriers_export</code> , <code>timesteps</code>
<code>cost_var</code>	<code>costs</code> , <code>loc_techs_om_cost</code> , <code>timesteps</code>
<code>cost_investment</code>	<code>costs</code> , <code>loc_techs_investment_cost</code>
<code>purchased</code>	<code>loc_techs_purchase</code>
<code>units</code>	<code>loc_techs_milp</code>
<code>operating_units</code>	<code>loc_techs_milp</code> , <code>timesteps</code>
<code>unmet_demand</code>	<code>loc_carriers</code> , <code>timesteps</code>

## Objective functions

`calliope.backend.pyomo.objective.minmax_cost_optimization` (*backend\_model*,  
*cost\_class*, *sense*)

Minimize or maximise total system cost for specified cost class.

If `unmet_demand` is in use, then the calculated cost of `unmet_demand` is added or subtracted from the total cost in the opposite sense to the objective.

$$\min : z = \sum_{loc::tech_{cost}} cost(loc :: tech, cost = cost_k) + \sum_{loc::carrier,timestep} unmet\_demand(loc :: carrier, timestep) \times bigM$$

`calliope.backend.pyomo.objective.check_feasibility` (*backend\_model*, **\*\*kwargs**)

Dummy objective, to check that there are no conflicting constraints.

$$\min : z = 1$$

## Constraints

### Energy Balance

`calliope.backend.pyomo.constraints.energy_balance.system_balance_constraint_rule` (*backend\_model*,  
*loc\_carrier*,  
*timestep*)

System balance ensures that, within each location, the production and consumption of each carrier is balanced.

$$\sum_{loc::tech::carrier_{prod} \in loc::carrier} carrier_{prod}(loc :: tech :: carrier, timestep) + \sum_{loc::tech::carrier_{con} \in loc::carrier} carrier_{con}(loc :: tech :: carrier, timestep) = 0$$

`calliope.backend.pyomo.constraints.energy_balance.balance_supply_constraint_rule` (*backend\_model*,  
*loc\_tech*,  
*timestep*)

Limit production from supply techs to their available resource

$$\min\_use(loc :: tech) \times available\_resource(loc :: tech, timestep) \leq \frac{carrier_{prod}(loc :: tech :: carrier, timestep)}{\eta_{energy}(loc :: tech, timestep)} \geq available\_resource(loc :: tech, timestep)$$

If `force_resource(loc :: tech)` is set:

$$\frac{carrier_{prod}(loc :: tech :: carrier, timestep)}{\eta_{energy}(loc :: tech, timestep)} = available\_resource(loc :: tech, timestep) \quad \forall loc :: tech \in loc :: techs_{supply}$$

Where:

$$available\_resource(loc :: tech, timestep) = resource(loc :: tech, timestep) \times resource\_scale(loc :: tech)$$

if `loc :: tech` is in `loc :: techs_area`:

$$available\_resource(loc :: tech, timestep) = resource(loc :: tech, timestep) \times resource\_scale(loc :: tech) \times resource\_area\_scale(loc :: tech)$$

`calliope.backend.pyomo.constraints.energy_balance.balance_demand_constraint_rule` (*backend\_model*,  
*loc\_tech*,  
*timestep*)

Limit consumption from demand techs to their required resource.

$$carrier_{con}(loc :: tech :: carrier, timestep) \times \eta_{energy}(loc :: tech, timestep) \geq required\_resource(loc :: tech, timestep)$$

If  $force\_resource(loc :: tech)$  is set:

$$\mathbf{carrier\_con}(loc :: tech :: carrier, timestep) \times \eta_{energy}(loc :: tech, timestep) = \mathbf{required\_resource}(loc :: tech, timestep)$$

Where:

$$\mathbf{required\_resource}(loc :: tech, timestep) = \mathbf{resource}(loc :: tech, timestep) \times \mathbf{resource\_scale}(loc :: tech)$$

if  $loc :: tech$  is in  $loc :: techs_{area}$ :

$$\mathbf{required\_resource}(loc :: tech, timestep) = \mathbf{resource}(loc :: tech, timestep) \times \mathbf{resource\_scale}(loc :: tech) \times \mathbf{resource\_area}(loc :: tech)$$

calliope.backend.pyomo.constraints.energy\_balance.**resource\_availability\_supply\_plus\_constraint\_rule**

Limit production from supply\_plus techs to their available resource.

$$\mathbf{resource\_con}(loc :: tech, timestep) \leq \mathbf{available\_resource}(loc :: tech, timestep) \quad \forall loc :: tech \in loc :: techs_{supply+}, \forall timestep$$

If  $force\_resource(loc :: tech)$  is set:

$$\mathbf{resource\_con}(loc :: tech, timestep) = \mathbf{available\_resource}(loc :: tech, timestep) \quad \forall loc :: tech \in loc :: techs_{supply+}, \forall timestep$$

Where:

$$\mathbf{available\_resource}(loc :: tech, timestep) = \mathbf{resource}(loc :: tech, timestep) \times \mathbf{resource\_scale}(loc :: tech)$$

if  $loc :: tech$  is in  $loc :: techs_{area}$ :

$$\mathbf{available\_resource}(loc :: tech, timestep) = \mathbf{resource}(loc :: tech, timestep) \times \mathbf{resource\_scale}(loc :: tech) \times \mathbf{resource\_area}(loc :: tech)$$

calliope.backend.pyomo.constraints.energy\_balance.**balance\_transmission\_constraint\_rule** (backend.pyomo.constraints.energy\_balance)   
  $loc\_from :: tech : loc\_to :: tech$    
  $timestep$

Balance carrier production and consumption of transmission technologies

$$-1 * \mathbf{carrier\_con}(loc_{from} :: tech : loc_{to} :: carrier, timestep) \times \eta_{energy}(loc :: tech, timestep) = \mathbf{carrier\_prod}(loc_{to} :: tech, timestep)$$

Where a link is the connection between  $loc_{from} :: tech : loc_{to}$  and  $loc_{to} :: tech : loc_{from}$  for locations  $to$  and  $from$ .

calliope.backend.pyomo.constraints.energy\_balance.**balance\_supply\_plus\_constraint\_rule** (backend.pyomo.constraints.energy\_balance)   
  $loc\_tech :: tech$    
  $timestep$

Balance carrier production and resource consumption of supply\_plus technologies alongside any use of resource storage.

$$\mathbf{storage}(loc :: tech, timestep) = \mathbf{storage}(loc :: tech, timestep_{previous}) \times (1 - \mathbf{storage\_loss}(loc :: tech, timestep))^{timestep}$$

If no storage is defined for the technology, this reduces to:

$$\mathbf{resource\_con}(loc :: tech, timestep) \times \eta_{resource}(loc :: tech, timestep) = \frac{\mathbf{carrier\_prod}(loc :: tech :: carrier, timestep)}{\eta_{energy}(loc :: tech, timestep) \times \eta_{parasitic}(loc :: tech, timestep)}$$

calliope.backend.pyomo.constraints.energy\_balance.**balance\_storage\_constraint\_rule** (*backend\_model*,  
*loc\_tech*,  
*timestep*)

Balance carrier production and consumption of storage technologies, alongside any use of the stored volume.

$$\mathit{storage}(loc :: tech, timestep) = \mathit{storage}(loc :: tech, timestep_{previous}) \times (1 - \mathit{storage\_loss}(loc :: tech, timestep))^{resolution}$$

calliope.backend.pyomo.constraints.energy\_balance.**balance\_storage\_inter\_cluster\_rule** (*backend\_model*,  
*loc\_tech*,  
*datestep*)

When clustering days, to reduce the timeseries length, balance the daily stored energy across all days of the original timeseries.

Ref: DOI 10.1016/j.apenergy.2018.01.023

$$\mathit{storage}_{inter\_cluster}(loc :: tech, datestep) = \mathit{storage}_{inter\_cluster}(loc :: tech, datestep_{previous}) \times (1 - \mathit{storage\_loss}(loc :: tech, datestep_{previous}))$$

Where  $timestep_{final,cluster}(datestep_{previous})$  is the final timestep of the cluster in the clustered timeseries corresponding to the previous day

calliope.backend.pyomo.constraints.energy\_balance.**storage\_initial\_rule** (*backend\_model*,  
*loc\_tech*)

If storage is cyclic, allow an initial storage to still be set. This is applied to the storage of the final timestep/datestep of the series as that, in cyclic storage, is the 'storage\_previous\_step' for the first timestep/datestep.

If clustering and `storage_inter_cluster` exists:

$$\mathit{storage}_{inter\_cluster}(loc :: tech, datestep_{final}) \times ((1 - \mathit{storage\_loss}) * 24) = \mathit{storage}_{initial}(loc :: tech) \quad \forall loc :: tech \in loc :: techs_{store}$$

Where  $datestep_{final}$  is the last datestep of the timeseries

Else: .. container:: scrolling-wrapper

$$\mathit{storage}(loc :: tech, timestep_{final}) \times ((1 - \mathit{storage\_loss}) * 24) = \mathit{storage}_{initial}(loc :: tech) \quad \forall loc :: tech \in loc :: techs_{store}$$

Where  $timestep_{final}$  is the last timestep of the timeseries

## Capacity

calliope.backend.pyomo.constraints.capacity.**storage\_capacity\_constraint\_rule** (*backend\_model*,  
*loc\_tech*)

Set maximum storage capacity. Supply\_plus & storage techs only

The first valid case is applied:

$$\mathit{storage}_{cap}(loc :: tech) \begin{cases} = \mathit{storage}_{cap,equals}(loc :: tech), & \text{if } \mathit{storage}_{cap,equals}(loc :: tech) \\ \leq \mathit{storage}_{cap,max}(loc :: tech), & \text{if } \mathit{storage}_{cap,max}(loc :: tech) \\ \text{unconstrained,} & \text{otherwise} \end{cases} \quad \forall loc :: tech \in loc :: techs_{store}$$

and (if equals not enforced):

$$\mathit{storage}_{cap}(loc :: tech) \geq \mathit{storage}_{cap,min}(loc :: tech) \quad \forall loc :: tech \in loc :: techs_{store}$$

calliope.backend.pyomo.constraints.capacity.**energy\_capacity\_storage\_constraint\_rule** (*backend\_model, loc\_tech*)

Set an additional energy capacity constraint on storage technologies, based on their use of *charge\_rate*.

$$\mathbf{energy}_{cap}(loc :: tech) \leq \mathbf{storage}_{cap}(loc :: tech) \times \mathbf{charge\_rate}(loc :: tech) \quad \forall loc :: tech \in loc :: techs_{store}$$

calliope.backend.pyomo.constraints.capacity.**resource\_capacity\_constraint\_rule** (*backend\_model, loc\_tech*)

Add upper and lower bounds for *resource\_cap*.

The first valid case is applied:

$$\mathbf{resource}_{cap}(loc :: tech) \begin{cases} = \mathbf{resource}_{cap,equal}(loc :: tech), & \text{if } \mathbf{resource}_{cap,equal}(loc :: tech) \\ \leq \mathbf{resource}_{cap,max}(loc :: tech), & \text{if } \mathbf{resource}_{cap,max}(loc :: tech) \quad \forall loc :: tech \in loc :: techs_{finite\_resource\_supply\_plus} \\ \text{unconstrained,} & \text{otherwise} \end{cases}$$

and (if equals not enforced):

$$\mathbf{resource}_{cap}(loc :: tech) \geq \mathbf{resource}_{cap,min}(loc :: tech) \quad \forall loc :: tech \in loc :: techs_{finite\_resource\_supply\_plus}$$

calliope.backend.pyomo.constraints.capacity.**resource\_capacity\_equals\_energy\_capacity\_constraint\_rule** (*backend\_model, loc\_tech*)

Add equality constraint for *resource\_cap* to equal *energy\_cap*, for any technologies which have defined *resource\_cap\_equals\_energy\_cap*.

$$\mathbf{resource}_{cap}(loc :: tech) = \mathbf{energy}_{cap}(loc :: tech) \quad \forall loc :: tech \in loc :: techs_{finite\_resource\_supply\_plus} \text{ if } \mathbf{resource\_cap\_equals\_energy\_cap}(loc :: tech)$$

calliope.backend.pyomo.constraints.capacity.**resource\_area\_constraint\_rule** (*backend\_model, loc\_tech*)

Set upper and lower bounds for *resource\_area*.

The first valid case is applied:

$$\mathbf{resource}_{area}(loc :: tech) \begin{cases} = \mathbf{resource}_{area,equal}(loc :: tech), & \text{if } \mathbf{resource}_{area,equal}(loc :: tech) \\ \leq \mathbf{resource}_{area,max}(loc :: tech), & \text{if } \mathbf{resource}_{area,max}(loc :: tech) \quad \forall loc :: tech \in loc :: techs_{area} \\ \text{unconstrained,} & \text{otherwise} \end{cases}$$

and (if equals not enforced):

$$\mathbf{resource}_{area}(loc :: tech) \geq \mathbf{resource}_{area,min}(loc :: tech) \quad \forall loc :: tech \in loc :: techs_{area}$$

calliope.backend.pyomo.constraints.capacity.**resource\_area\_per\_energy\_capacity\_constraint\_rule** (*backend\_model, loc\_tech*)

Add equality constraint for *resource\_area* to equal a percentage of *energy\_cap*, for any technologies which have defined *resource\_area\_per\_energy\_cap*

$$\mathbf{resource}_{area}(loc :: tech) = \mathbf{energy}_{cap}(loc :: tech) \times \mathbf{area\_per\_energy\_cap}(loc :: tech) \quad \forall loc :: tech \in locs :: techs_{area}$$

calliope.backend.pyomo.constraints.capacity.**resource\_area\_capacity\_per\_loc\_constraint\_rule** (*backend\_model, locs*)

Set upper bound on use of area for all locations which have *available\_area* constraint set. Does not consider *resource\_area* applied to demand technologies

$$\sum_{tech} \mathbf{resource}_{area}(loc :: tech) \leq \mathbf{available\_area}(loc) \quad \forall loc \in locs \text{ if } \mathbf{available\_area}(loc)$$

`calliope.backend.pyomo.constraints.capacity.energy_capacity_constraint_rule` (*backend\_model*,  
*loc\_tech*)

Set upper and lower bounds for `energy_cap`.

The first valid case is applied:

$$\frac{\mathbf{energy\_cap}(loc :: tech)}{\mathbf{energy\_cap, scale}(loc :: tech)} \begin{cases} = \mathbf{energy\_cap, equals}(loc :: tech), & \text{if } \mathbf{energy\_cap, equals}(loc :: tech) \\ \leq \mathbf{energy\_cap, max}(loc :: tech), & \text{if } \mathbf{energy\_cap, max}(loc :: tech) \quad \forall loc :: tech \in loc :: techs \\ \text{unconstrained,} & \text{otherwise} \end{cases}$$

and (if `equals` not enforced):

$$\frac{\mathbf{energy\_cap}(loc :: tech)}{\mathbf{energy\_cap, scale}(loc :: tech)} \geq \mathbf{energy\_cap, min}(loc :: tech) \quad \forall loc :: tech \in loc :: techs$$

`calliope.backend.pyomo.constraints.capacity.energy_capacity_systemwide_constraint_rule` (*backend\_model*,  
*tech*)

Set constraints to limit the capacity of a single technology type across all locations in the model.

The first valid case is applied:

$$\sum_{loc} \mathbf{energy\_cap}(loc :: tech) \begin{cases} = \mathbf{energy\_cap, equals, systemwide}(loc :: tech), & \text{if } \mathbf{energy\_cap, equals, systemwide}(loc :: tech) \\ \leq \mathbf{energy\_cap, max, systemwide}(loc :: tech), & \text{if } \mathbf{energy\_cap, max, systemwide}(loc :: tech) \quad \forall tech \in techs \\ \text{unconstrained,} & \text{otherwise} \end{cases}$$

## Dispatch

`calliope.backend.pyomo.constraints.dispatch.carrier_production_max_constraint_rule` (*backend\_model*,  
*loc\_tech\_carrier*,  
*timestep*)

Set maximum carrier production. All technologies.

$$\mathbf{carrier\_prod}(loc :: tech :: carrier, timestep) \leq \mathbf{energy\_cap}(loc :: tech) \times \mathbf{timestep\_resolution}(timestep) \times \mathbf{parasitic\_efficiency}(loc :: tech, timestep)$$

`calliope.backend.pyomo.constraints.dispatch.carrier_production_min_constraint_rule` (*backend\_model*,  
*loc\_tech\_carrier*,  
*timestep*)

Set minimum carrier production. All technologies except `conversion_plus`.

$$\mathbf{carrier\_prod}(loc :: tech :: carrier, timestep) \geq \mathbf{energy\_cap}(loc :: tech) \times \mathbf{timestep\_resolution}(timestep) \times \mathbf{energy\_cap, min}(loc :: tech, timestep)$$

`calliope.backend.pyomo.constraints.dispatch.carrier_consumption_max_constraint_rule` (*backend\_model*,  
*loc\_tech\_carrier*,  
*timestep*)

Set maximum carrier consumption for demand, storage, and transmission techs.

$$\mathbf{carrier\_con}(loc :: tech :: carrier, timestep) \geq -1 \times \mathbf{energy\_cap}(loc :: tech) \times \mathbf{timestep\_resolution}(timestep)$$

`calliope.backend.pyomo.constraints.dispatch.resource_max_constraint_rule` (*backend\_model*,  
*loc\_tech*,  
*timestep*)

Set maximum resource consumed by `supply_plus` techs.

$$\mathbf{resource\_con}(loc :: tech, timestep) \leq \mathbf{timestep\_resolution}(timestep) \times \mathbf{resource\_cap}(loc :: tech)$$

calliope.backend.pyomo.constraints.dispatch.**storage\_max\_constraint\_rule**(*backend\_model*,  
*loc\_tech*,  
*timestep*)

Set maximum stored energy. Supply\_plus & storage techs only.

$$\mathbf{storage}(loc :: tech, timestep) \leq \mathbf{storage}_{cap}(loc :: tech)$$

calliope.backend.pyomo.constraints.dispatch.**ramping\_up\_constraint\_rule**(*backend\_model*,  
*loc\_tech\_carrier*,  
*timestep*)

Ramping up constraint.

$$\mathbf{diff}(loc :: tech :: carrier, timestep) \leq \mathbf{max\_ramping\_rate}(loc :: tech :: carrier, timestep)$$

calliope.backend.pyomo.constraints.dispatch.**ramping\_down\_constraint\_rule**(*backend\_model*,  
*loc\_tech\_carrier*,  
*timestep*)

Ramping down constraint.

$$-1 \times \mathbf{max\_ramping\_rate}(loc :: tech :: carrier, timestep) \leq \mathbf{diff}(loc :: tech :: carrier, timestep)$$

calliope.backend.pyomo.constraints.dispatch.**ramping\_constraint**(*backend\_model*,  
*loc\_tech\_carrier*,  
*timestep*, *direction=0*)

Ramping rate constraints.

Direction: 0 is up, 1 is down.

$$\mathbf{diff}(loc :: tech :: carrier, timestep) = (\mathbf{carrier}_{prod}(loc :: tech :: carrier, timestep) + \mathbf{carrier}_{con}(loc :: tech :: carrier, timestep))$$

calliope.backend.pyomo.constraints.dispatch.**storage\_intra\_max\_rule**(*backend\_model*,  
*loc\_tech*,  
*timestep*)

When clustering days, to reduce the timeseries length, set limits on intra-cluster auxiliary maximum storage decision variable. Ref: DOI 10.1016/j.apenergy.2018.01.023

$$\mathbf{storage}(loc :: tech, timestep) \leq \mathbf{storage}_{intra\_cluster, max}(loc :: tech, cluster(timestep)) \quad \forall loc :: tech \in loc :: techs_{sto}$$

Where  $cluster(timestep)$  is the cluster number in which the timestep is located.

calliope.backend.pyomo.constraints.dispatch.**storage\_intra\_min\_rule**(*backend\_model*,  
*loc\_tech*,  
*timestep*)

When clustering days, to reduce the timeseries length, set limits on intra-cluster auxiliary minimum storage decision variable. Ref: DOI 10.1016/j.apenergy.2018.01.023

$$\mathbf{storage}(loc :: tech, timestep) \geq \mathbf{storage}_{intra\_cluster, min}(loc :: tech, cluster(timestep)) \quad \forall loc :: tech \in loc :: techs_{sto}$$

Where  $cluster(timestep)$  is the cluster number in which the timestep is located.

calliope.backend.pyomo.constraints.dispatch.**storage\_inter\_max\_rule**(*backend\_model*,  
*loc\_tech*,  
*datestep*)

When clustering days, to reduce the timeseries length, set maximum limit on the intra-cluster and inter-date

stored energy. intra-cluster = all timesteps in a single cluster datesteps = all dates in the unclustered timeseries (each has a corresponding cluster) Ref: DOI 10.1016/j.apenergy.2018.01.023

$$storage_{inter\_cluster}(loc :: tech, datestep) + storage_{intra\_cluster,max}(loc :: tech, cluster(datestep)) \leq storage_{cap}(loc :: tech, datestep)$$

Where  $cluster(datestep)$  is the cluster number in which the datestep is located.

calliope.backend.pyomo.constraints.dispatch.**storage\_inter\_min\_rule** (*backend\_model*,  
*loc\_tech*,  
*datestep*)

When clustering days, to reduce the timeseries length, set minimum limit on the intra-cluster and inter-date stored energy. intra-cluster = all timesteps in a single cluster datesteps = all dates in the unclustered timeseries (each has a corresponding cluster) Ref: DOI 10.1016/j.apenergy.2018.01.023

$$storage_{inter\_cluster}(loc :: tech, datestep) \times (1 - storage\_loss(loc :: tech, timestep))^{24} + storage_{intra\_cluster,min}(loc :: tech, datestep) \leq storage_{cap}(loc :: tech, datestep)$$

Where  $cluster(datestep)$  is the cluster number in which the datestep is located.

## Costs

calliope.backend.pyomo.constraints.costs.**cost\_constraint\_rule** (*backend\_model*,  
*cost*, *loc\_tech*)

Combine investment and time varying costs into one cost per technology

$$cost(cost, loc :: tech) = cost_{investment}(cost, loc :: tech) + \sum_{timestep \in timesteps} cost_{var}(cost, loc :: tech, timestep)$$

calliope.backend.pyomo.constraints.costs.**cost\_investment\_constraint\_rule** (*backend\_model*,  
*cost*,  
*loc\_tech*)

Calculate costs from capacity decision variables.

Transmission technologies “exist” at two locations, so their cost is divided by 2.

$$cost_{con}(cost, loc :: tech) = depreciation\_rate * ts\_weight * (cost_{energy\_cap}(cost, loc :: tech) \times energy_{cap}(loc :: tech) + cost_{om\_con}(cost, loc :: tech, timestep))$$

calliope.backend.pyomo.constraints.costs.**cost\_var\_constraint\_rule** (*backend\_model*,  
*cost*,  
*loc\_tech*,  
*timestep*)

Calculate costs from time-varying decision variables

$$cost_{var}(cost, loc :: tech, timestep) = cost_{prod}(cost, loc :: tech, timestep) + cost_{con}(cost, loc :: tech, timestep)$$

$$cost_{prod}(cost, loc :: tech, timestep) = cost_{om\_prod}(cost, loc :: tech, timestep) \times weight(timestep) \times carrier_{prod}(loc :: tech, timestep)$$

$$prod\_con\_eff = \begin{cases} resource_{con}(loc :: tech, timestep), & \text{if } loc :: tech \in \text{carrier\_prod}(loc :: tech, timestep) \\ \frac{carrier_{prod}(loc :: tech, timestep)}{energy\_eff(loc :: tech, timestep)}, & \text{if } loc :: tech \in \text{carrier\_prod}(loc :: tech, timestep) \end{cases}$$

$$cost_{con}(cost, loc :: tech, timestep) = cost_{om\_con}(cost, loc :: tech, timestep) \times weight(timestep)$$



## Export

`calliope.backend.pyomo.constraints.export.update_system_balance_constraint` (*backend\_model*,  
*loc\_carrier*,  
*timestep*)

Update system balance constraint (from `energy_balance.py`) to include export

Math given in `system_balance_constraint_rule()`

`calliope.backend.pyomo.constraints.export.export_balance_constraint_rule` (*backend\_model*,  
*loc\_tech\_carrier*,  
*timestep*)

Ensure no technology can ‘pass’ its export capability to another technology with the same carrier\_out, by limiting its export to the capacity of its production

$$\mathbf{carrier}_{prod}(loc :: tech :: carrier, timestep) \geq \mathbf{carrier}_{export}(loc :: tech :: carrier, timestep) \quad \forall loc :: tech :: carrier \in$$

`calliope.backend.pyomo.constraints.export.update_costs_var_constraint` (*backend\_model*,  
*cost*,  
*loc\_tech*,  
*timestep*)

Update time varying cost constraint (from `costs.py`) to include export

$$\mathbf{cost}_{var}(cost, loc :: tech, timestep) + = \mathbf{cost}_{export}(cost, loc :: tech, timestep) \times \mathbf{carrier}_{export}(loc :: tech :: carrier, time$$

`calliope.backend.pyomo.constraints.export.export_max_constraint_rule` (*backend\_model*,  
*loc\_tech\_carrier*,  
*timestep*)

Set maximum export. All exporting technologies.

$$\mathbf{carrier}_{export}(loc :: tech :: carrier, timestep) \leq \mathbf{export}_{cap}(loc :: tech) \quad \forall loc :: tech :: carrier \in locs :: tech :: carriers_e$$

If the technology is defined by integer units, not a continuous capacity, this constraint becomes:

$$\mathbf{carrier}_{export}(loc :: tech :: carrier, timestep) \leq \mathbf{export}_{cap}(loc :: tech) \times \mathbf{operating}_{units}(loc :: tech, timestep)$$

## MILP

`calliope.backend.pyomo.constraints.milp.unit_commitment_constraint_rule` (*backend\_model*,  
*loc\_tech*,  
*timestep*)

Constraining the number of integer units  $\mathbf{operating}_{units}(loc_tech, timestep)$  of a technology which can operate in a given timestep, based on maximum purchased units  $\mathbf{units}(loc_tech)$

$$\mathbf{operating}_{units}(loc :: tech, timestep) \leq \mathbf{units}(loc :: tech) \quad \forall loc :: tech \in loc :: techs_{milp}, \forall timestep \in timesteps$$

`calliope.backend.pyomo.constraints.milp.unit_capacity_constraint_rule` (*backend\_model*,  
*loc\_tech*)

Add upper and lower bounds for purchased units of a technology

$$\mathbf{units}(loc :: tech) \begin{cases} = \mathbf{units}_{equals}(loc :: tech), & \text{if } \mathbf{units}_{equals}(loc :: tech) \\ \leq \mathbf{units}_{max}(loc :: tech), & \text{if } \mathbf{units}_{max}(loc :: tech) \\ \text{unconstrained,} & \text{otherwise} \end{cases} \quad \forall loc :: tech \in loc :: techs_{milp}$$

and (if equals not enforced):

$$\mathbf{units}(loc :: tech) \geq \mathbf{units}_{min}(loc :: tech) \quad \forall loc :: tech \in loc :: techs_{milp}$$

calliope.backend.pyomo.constraints.milp.**carrier\_production\_max\_milp\_constraint\_rule** (*backend\_model, loc\_tech, timestep*)

Set maximum carrier production of MILP techs that aren't conversion plus

$$\mathbf{carrier}_{prod}(loc :: tech :: carrier, timestep) \leq energy_{cap,perunit}(loc :: tech) \times timestep\_resolution(timestep) \times \mathbf{operational}$$

$\eta_{parasitic}$  is only activated for *supply\_plus* technologies

calliope.backend.pyomo.constraints.milp.**carrier\_production\_max\_conversion\_plus\_milp\_constraint\_rule** (*backend\_model, loc\_tech, timestep*)

Set maximum carrier production of conversion\_plus MILP techs

$$\sum_{loc :: tech :: carrier \in loc :: tech :: carriers_{out}} \mathbf{carrier}_{prod}(loc :: tech :: carrier, timestep) \leq energy_{cap,perunit}(loc :: tech) \times timestep\_resolution(timestep) \times \mathbf{operational}$$

calliope.backend.pyomo.constraints.milp.**carrier\_production\_min\_milp\_constraint\_rule** (*backend\_model, loc\_tech, timestep*)

Set minimum carrier production of MILP techs that aren't conversion plus

$$\mathbf{carrier}_{prod}(loc :: tech :: carrier, timestep) \geq energy_{cap,perunit}(loc :: tech) \times timestep\_resolution(timestep) \times \mathbf{operational}$$

calliope.backend.pyomo.constraints.milp.**carrier\_production\_min\_conversion\_plus\_milp\_constraint\_rule** (*backend\_model, loc\_tech, timestep*)

Set minimum carrier production of conversion\_plus MILP techs

$$\sum_{loc :: tech :: carrier \in loc :: tech :: carriers_{out}} \mathbf{carrier}_{prod}(loc :: tech :: carrier, timestep) \geq energy_{cap,perunit}(loc :: tech) \times timestep\_resolution(timestep) \times \mathbf{operational}$$

calliope.backend.pyomo.constraints.milp.**carrier\_consumption\_max\_milp\_constraint\_rule** (*backend\_model, loc\_tech, timestep*)

Set maximum carrier consumption of demand, storage, and transmission MILP techs

$$\mathbf{carrier}_{con}(loc :: tech :: carrier, timestep) \geq -1 * energy_{cap,perunit}(loc :: tech) \times timestep\_resolution(timestep) \times \mathbf{operational}$$

calliope.backend.pyomo.constraints.milp.**energy\_capacity\_units\_constraint\_rule** (*backend\_model, loc\_tech*)

Set energy capacity decision variable as a function of purchased units

$$\mathbf{energy}_{cap}(loc :: tech) = \mathbf{units}(loc :: tech) \times energy_{cap,perunit}(loc :: tech) \quad \forall loc :: tech \in loc :: techs_{milp}$$

calliope.backend.pyomo.constraints.milp.**storage\_capacity\_units\_constraint\_rule** (*backend\_model, loc\_tech*)

Set storage capacity decision variable as a function of purchased units

$$\mathbf{storage}_{cap}(loc :: tech) = \mathbf{units}(loc :: tech) \times storage_{cap,perunit}(loc :: tech) \quad \forall loc :: tech \in loc :: techs_{milp,store}$$

calliope.backend.pyomo.constraints.milp.**energy\_capacity\_max\_purchase\_constraint\_rule** (*backend\_model, loc\_tech*)

Set maximum energy capacity decision variable upper bound as a function of binary purchase variable

The first valid case is applied:

$$\frac{\mathbf{energy\_cap}(loc :: tech)}{\mathbf{energy\_cap, scale}(loc :: tech)} \begin{cases} = \mathbf{energy\_cap, equals}(loc :: tech) \times \mathbf{purchased}(loc :: tech), & \text{if } \mathbf{energy\_cap, equals}(loc :: tech) \\ \leq \mathbf{energy\_cap, max}(loc :: tech) \times \mathbf{purchased}(loc :: tech), & \text{if } \mathbf{energy\_cap, max}(loc :: tech) \forall \\ \text{unconstrained,} & \text{otherwise} \end{cases}$$

calliope.backend.pyomo.constraints.milp.**energy\_capacity\_min\_purchase\_constraint\_rule** (*backend\_*  
*loc\_tech*)

Set minimum energy capacity decision variable upper bound as a function of binary purchase variable

and (if equals not enforced):

$$\frac{\mathbf{energy\_cap}(loc :: tech)}{\mathbf{energy\_cap, scale}(loc :: tech)} \geq \mathbf{energy\_cap, min}(loc :: tech) \times \mathbf{purchased}(loc :: tech) \quad \forall loc :: tech \in loc :: techs$$

calliope.backend.pyomo.constraints.milp.**storage\_capacity\_max\_purchase\_constraint\_rule** (*backend\_*  
*loc\_tech*)

Set maximum storage capacity.

The first valid case is applied:

$$\mathbf{storage\_cap}(loc :: tech) \begin{cases} = \mathbf{storage\_cap, equals}(loc :: tech) \times \mathbf{purchased}, & \text{if } \mathbf{storage\_cap, equals} \\ \leq \mathbf{storage\_cap, max}(loc :: tech) \times \mathbf{purchased}, & \text{if } \mathbf{storage\_cap, max}(loc :: tech) \forall loc :: tech \in loc \\ \text{unconstrained,} & \text{otherwise} \end{cases}$$

calliope.backend.pyomo.constraints.milp.**storage\_capacity\_min\_purchase\_constraint\_rule** (*backend\_*  
*loc\_tech*)

Set minimum storage capacity decision variable as a function of binary purchase variable

if equals not enforced for storage\_cap:

$$\mathbf{storage\_cap}(loc :: tech) \geq \mathbf{storage\_cap, min}(loc :: tech) \times \mathbf{purchased}(loc :: tech) \quad \forall loc :: tech \in loc :: techs_{\mathbf{purchase, store}}$$

calliope.backend.pyomo.constraints.milp.**update\_costs\_investment\_units\_constraint** (*backend\_mod\_*  
*cost,*  
*loc\_tech*)

Add MILP investment costs (cost \* number of units purchased)

$$\mathbf{cost\_investment}(cost, loc :: tech) += \mathbf{units}(loc :: tech) \times \mathbf{cost\_purchase}(cost, loc :: tech) * \mathbf{timestep\_weight} * \mathbf{depreciation}$$

calliope.backend.pyomo.constraints.milp.**update\_costs\_investment\_purchase\_constraint** (*backend\_*  
*cost,*  
*loc\_tech*)

Add binary investment costs (cost \* binary\_purchased\_unit)

$$\mathbf{cost\_investment}(cost, loc :: tech) += \mathbf{purchased}(loc :: tech) \times \mathbf{cost\_purchase}(cost, loc :: tech) * \mathbf{timestep\_weight} * \mathbf{depreciation}$$

calliope.backend.pyomo.constraints.milp.**unit\_capacity\_systemwide\_constraint\_rule** (*backend\_mod\_*  
*tech*)

Set constraints to limit the number of purchased units of a single technology type across all locations in the model.

The first valid case is applied:

$$\sum_{loc} \mathbf{units}(loc :: tech) + \mathbf{purchased}(loc :: tech) \begin{cases} = \mathbf{units\_equals, systemwide}(tech), & \text{if } \mathbf{units\_equals, systemwide}(tech) \\ \leq \mathbf{units\_max, systemwide}(tech), & \text{if } \mathbf{units\_max, systemwide}(tech) \forall tech \\ \text{unconstrained,} & \text{otherwise} \end{cases}$$

## Conversion

calliope.backend.pyomo.constraints.conversion.**balance\_conversion\_constraint\_rule** (*backend\_model*, *loc\_tech*, *timestep*)

Balance energy carrier consumption and production

$$-1 * \mathbf{carrier}_{con}(loc :: tech :: carrier, timestep) \times \eta_{energy}(loc :: tech, timestep) = \mathbf{carrier}_{prod}(loc :: tech :: carrier, timestep)$$

calliope.backend.pyomo.constraints.conversion.**cost\_var\_conversion\_constraint\_rule** (*backend\_model*, *cost*, *loc\_tech*, *timestep*)

Add time-varying conversion technology costs

$$\mathbf{cost}_{var}(loc :: tech, cost, timestep) = \mathbf{carrier}_{prod}(loc :: tech :: carrier, timestep) \times \mathbf{timestep}_{weight}(timestep) \times \mathbf{cost}_{om}$$

## Conversion\_plus

calliope.backend.pyomo.constraints.conversion\_plus.**balance\_conversion\_plus\_primary\_constraint\_rule** (*backend\_model*, *loc\_tech*, *timestep*)

Balance energy carrier consumption and production for carrier\_in and carrier\_out

$$\sum_{loc::tech::carrier \in loc::tech::carriers_{out}} \frac{\mathbf{carrier}_{prod}(loc :: tech :: carrier, timestep)}{\mathbf{carrier}_{ratio}(loc :: tech :: carrier, 'out')} = -1 * \sum_{loc::tech::carrier \in loc::tech::carriers_{in}} \mathbf{carrier}_{con}(loc :: tech :: carrier, timestep)$$

calliope.backend.pyomo.constraints.conversion\_plus.**carrier\_production\_max\_conversion\_plus\_constraint\_rule** (*backend\_model*, *loc\_tech*, *timestep*)

Set maximum conversion\_plus carrier production.

$$\sum_{loc::tech::carrier \in loc::tech::carriers_{out}} \mathbf{carrier}_{prod}(loc :: tech :: carrier, timestep) \leq \mathbf{energy}_{cap}(loc :: tech) \times \mathbf{timestep}_{res}$$

calliope.backend.pyomo.constraints.conversion\_plus.**carrier\_production\_min\_conversion\_plus\_constraint\_rule** (*backend\_model*, *loc\_tech*, *timestep*)

Set minimum conversion\_plus carrier production.

$$\sum_{loc::tech::carrier \in loc::tech::carriers_{out}} \mathbf{carrier}_{prod}(loc :: tech :: carrier, timestep) \leq \mathbf{energy}_{cap}(loc :: tech) \times \mathbf{timestep}_{res}$$

calliope.backend.pyomo.constraints.conversion\_plus.**cost\_var\_conversion\_plus\_constraint\_rule** (*backend\_model*, *cost*, *loc\_tech*, *timestep*)

Add time-varying conversion\_plus technology costs

$$\mathbf{cost}_{var}(loc :: tech, cost, timestep) = \mathbf{carrier}_{prod}(loc :: tech :: carrier_{primary}, timestep) \times \mathbf{timestep}_{weight}(timestep) \times \mathbf{cost}_{om}$$

calliope.backend.pyomo.constraints.conversion\_plus.**balance\_conversion\_plus\_tiers\_constraint**

Force all carrier\_in\_2/carrier\_in\_3 and carrier\_out\_2/carrier\_out\_3 to follow carrier\_in and carrier\_out (respectively).

If *tier* in ['out\_2', 'out\_3']:

$$\sum_{loc::tech::carrier \in loc::tech::carriers_{out}} \left( \frac{carrier_{prod}(loc :: tech :: carrier, timestep)}{carrier\_ratio(loc :: tech :: carrier, 'out')} \right) = \sum_{loc::tech::carrier \in loc::tech::carriers_{tier}} \left( \frac{carrier_{prod}(loc :: tech :: carrier, timestep)}{carrier\_ratio(loc :: tech :: carrier, tier)} \right)$$

If *tier* in ['in\_2', 'in\_3']:

$$\sum_{loc::tech::carrier \in loc::tech::carriers_{in}} \frac{carrier_{con}(loc :: tech :: carrier, timestep)}{carrier\_ratio(loc :: tech :: carrier, 'in')} = \sum_{loc::tech::carrier \in loc::tech::carriers_{tier}} \frac{carrier_{con}(loc :: tech :: carrier, timestep)}{carrier\_ratio(loc :: tech :: carrier, tier)}$$

## Network

calliope.backend.pyomo.constraints.network.**symmetric\_transmission\_constraint\_rule** (*backend\_model*, *loc\_tech*)

Constrain e\_cap symmetrically for transmission nodes. Transmission techs only.

$$energy_{cap}(loc1 :: tech : loc2) = energy_{cap}(loc2 :: tech : loc1)$$

## Policy

calliope.backend.pyomo.constraints.policy.**group\_share\_energy\_cap\_constraint\_rule** (*backend\_model*, *tech\_list*, *what*)

Enforce shares in energy\_cap for groups of technologies. Applied to supply and supply\_plus technologies only.

$$\sum_{loc::tech \in given\_group} energy_{cap}(loc :: tech) = fraction \times \sum_{loc::tech \in loc\_techs\_supply loc\_techs\_supply\_plus} energy_{cap}(loc :: tech)$$

calliope.backend.pyomo.constraints.policy.**group\_share\_carrier\_prod\_constraint\_rule** (*backend\_model*, *tech\_list\_carrier*, *what*)

Enforce shares in carrier\_prod for groups of technologies. Applied to loc\_tech\_carriers\_supply\_all, which includes supply, supply\_plus, conversion, and conversion\_plus.

$$\sum_{loc::tech::carrier \in given\_group, timestep \in timesteps} carrier_{prod}(loc :: tech :: carrier, timestep) = fraction \times \sum_{loc::tech::carrier \in loc\_tech\_carriers\_supply\_all} carrier_{prod}(loc :: tech :: carrier, timestep)$$

calliope.backend.pyomo.constraints.policy.**reserve\_margin\_constraint\_rule** (*backend\_model*, *carrier*)

Enforces a system reserve margin per carrier.

$$\sum_{loc::tech::carrier \in loc\_tech\_carriers\_supply\_all} energy_{cap}(loc :: tech :: carrier, timestep_{max\_demand}) \geq \sum_{loc::tech::carrier \in loc\_tech\_carriers\_supply\_all} carrier_{prod}(loc :: tech :: carrier, timestep_{max\_demand}) \times reserve\_margin$$

## 1.9 Development guide

Contributions are very welcome! See our [contributors guide on GitHub](#) for information on how to contribute.

The code lives on GitHub at [calliope-project/calliope](#). Development takes place in the `master` branch. Stable versions are tagged off of `master` with [semantic versioning](#).

Tests are included and can be run with `py.test` from the project's root directory.

Also see the list of [open issues](#), planned [milestones](#) and [projects](#) for an overview of where development is heading, and [join us on Gitter](#) to ask questions or discuss code.

### 1.9.1 Installing a development version

As when installing a stable version, using `conda` is recommended.

If you only want to track the latest commit, without having a local Calliope repository, then just download the [base.yml](#) and [latest.yml](#) requirements files and run (assuming both are saved into a directory called `requirements`):

```
$ conda env create -n calliope_latest --file=requirements/base.yml --  
→file=requirements/latest.yml
```

This will create a conda environment called `calliope_latest`.

To actively contribute to Calliope development, you'll instead want to clone the repository, giving you an editable copy. This will provide you with the `master` branch in a known location on your local device.

First, clone the repository:

```
$ git clone https://github.com/calliope-project/calliope
```

Using Anaconda/conda, install all requirements, including the free and open source GLPK solver, into a new environment, e.g. `calliope_dev`:

```
$ conda env create -f ./calliope/requirements/base.yml -n calliope_dev  
$ source activate calliope_dev
```

On Windows:

```
$ conda env create -f ./calliope/requirements/base.yml -n calliope_dev  
$ activate calliope_dev
```

Then install Calliope itself with `pip`:

```
$ pip install -e ./calliope
```

### 1.9.2 Creating modular extensions

As of version 0.6.0, dynamic loading of custom constraint generator extensions has been removed due it not not being used by users of Calliope. The ability to dynamically load custom functions to adjust time resolution remains (see below).

## Time functions and masks

Custom functions that adjust time resolution can be loaded dynamically during model initialisation. By default, Calliope first checks whether the name of a function or time mask refers to a function from the `calliope.core.time.masks` or `calliope.core.time.funcs` module, and if not, attempts to load the function from an importable module:

```
time:
  masks:
    - {function: week, options: {day_func: 'extreme', tech: 'wind', how: 'min'}}
    - {function: my_custom_module.my_custom_mask, options: {...}}
  function: my_custom_module.my_custom_function
  function_options: {...}
```

## 1.9.3 Profiling

To profile a Calliope run with the built-in national-scale example model, then visualise the results with `snakeviz`:

```
make profile # will dump profile output in the current directory
snakeviz calliope.profile # launch snakeviz to visually examine profile
```

Use `mprof plot` to plot memory use.

Other options for visualising:

- Interactive visualisation with `KCachegrind` (on macOS, use `QCachegrind`, installed e.g. with `brew install qcachegrind`)

```
pyprof2calltree -i calliope.profile -o calliope.calltree
kchachegrind calliope.calltree
```

- Generate a call graph from the call tree via `graphviz`

```
# brew install gprof2dot
gprof2dot -f callgrind calliope.calltree | dot -Tsvg -o callgraph.svg
```

## 1.9.4 Checklist for new release

### Pre-release

- Make sure all unit tests pass
- Build up-to-date Plotly plots for the documentation with `(make doc-plots)`
- Re-run tutorial Jupyter notebooks, found in `doc/_static/notebooks`
- Make sure documentation builds without errors
- Make sure the release notes are up-to-date, especially that new features and backward incompatible changes are clearly marked

### Create release

- Change `_version.py` version number
- Update changelog with final version number and release date

- Commit with message “Release vXXXX”, then add a “vXXXX” tag, push both to GitHub
- Create a release through the GitHub web interface, using the same tag, titling it “Release vXXXX” (required for Zenodo to pull it in)
- Upload new release to PyPI: `make all-dist`
- **Update the conda-forge package:**
  - Fork [conda-forge/calliope-feedstock](#), and update `recipe/meta.yaml` with:
    - \* Version number: `{% set version = "XXXX" %}`
    - \* SHA256 of latest version from PyPI: `{% set sha256 = "XXXX" %}`
    - \* Reset build: `number: 0` if it is not already at zero
    - \* If necessary, carry over any changed requirements from `setup.py` or `requirements/base.yml`
  - Submit a pull request from an appropriately named branch in your fork (e.g. `vXXXX`) to the [conda-forge/calliope-feedstock](#) repository

### Post-release

- Update changelog, adding a new `vXXXX-dev` heading, and update `_version.py` accordingly, in preparation for the next master commit
- Update the `calliope_version` setting in all example models to match the new version, but without the `-dev` string (so `0.6.0-dev` is `0.6.0` for the example models)

---

**Note:** Adding ‘-dev’ to the version string, such as `__version__ = '0.1.0-dev'`, is required for the custom code in `doc/conf.py` to work when building in-development versions of the documentation.

---



Documents functions, classes and methods:

## 2.1 API Documentation

### 2.1.1 Model class

**class** `calliope.Model` (*config*, *model\_data=None*, \*args, \*\*kwargs)

A Calliope Model.

**save\_commented\_model\_yaml** (*path*)

Save a fully built and commented version of the model to a YAML file at the given *path*. Comments in the file indicate where values were overridden. This is Calliope's internal representation of a model directly before the *model\_data* `xarray.Dataset` is built, and can be useful for debugging possible issues in the model formulation.

**run** (*force\_rerun=False*, \*\*kwargs)

Run the model. If *force\_rerun* is True, any existing results will be overwritten.

Additional kwargs are passed to the backend.

**get\_formatted\_array** (*var*)

Return an `xr.DataArray` with *locs*, *techs*, and *carriers* as separate dimensions.

#### Parameters

**var** [str] Decision variable for which to return a `DataArray`.

**to\_netcdf** (*path*)

Save complete model data (inputs and, if available, results) to a NetCDF file at the given *path*.

**to\_csv** (*path*, *dropna=True*)

Save complete model data (inputs and, if available, results) as a set of CSV files to the given *path*.

#### Parameters

**dropna** [bool, optional] If True (default), NaN values are dropped when saving, resulting in significantly smaller CSV files.

## 2.1.2 Time series

`calliope.core.time.clustering.get_clusters` (*data*, *func*, *timesteps\_per\_day*, *tech=None*, *timesteps=None*, *k=None*, *variables=None*, *\*\*kwargs*)

Run a clustering algorithm on the timeseries data supplied. All timeseries data is reshaped into one row per day before clustering into similar days.

### Parameters

**data** [xarray.Dataset] Should be normalized

**func** [str] ‘kmeans’ or ‘hierarchical’ for KMeans or Agglomerative clustering, respectively

**timesteps\_per\_day** [int] Total number of timesteps in a day

**tech** [list, optional] list of strings referring to technologies by which clustering is undertaken. If none (default), all technologies within timeseries variables will be used.

**timesteps** [list or str, optional] Subset of the time domain within which to apply clustering.

**k** [int, optional] Number of clusters to create. If none (default), will use Hartigan’s rule to infer a reasonable number of clusters.

**variables** [list, optional] data variables (e.g. *resource*, *energy\_eff*) by whose values the data will be clustered. If none (default), all timeseries variables will be used.

**kwargs** [dict] Additional keyword arguments available depend on the *func*. For available KMeans kwargs see: <http://scikit-learn.org/stable/modules/generated/sklearn.cluster.KMeans.html> For available hierarchical kwargs see: <http://scikit-learn.org/stable/modules/generated/sklearn.cluster.AgglomerativeClustering.html>

### Returns

———  
**clusters** [dataframe] Indexed by timesteps and with locations as columns, giving cluster membership for first timestep of each day.

**clustered\_data** [sklearn.cluster object] Result of clustering using `sklearn.KMeans(k).fit(X)` or `sklearn.KMeans(k).AgglomerativeClustering(X)`. Allows user to access specific attributes, for detailed statistical analysis.

`calliope.core.time.masks.extreme` (*data*, *tech*, *var='resource'*, *how='max'*, *length='1D'*, *n=1*, *groupby\_length=None*, *padding=None*, *normalize=True*, *\*\*kwargs*)

Returns timesteps for period of *length* where *var* for the technology *tech* across the given list of *locations* is either minimal or maximal.

### Parameters

**data** [xarray.Dataset]

**tech** [str] Technology whose *var* to find extreme for.

**var** [str, optional] default ‘resource’

**how** [str, optional] ‘max’ (default) or ‘min’.

**length** [str, optional] Defaults to ‘1D’.

**n** [int, optional] Number of periods of *length* to look for, default is 1.

**groupby\_length** [str, optional] Group time series and return *n* periods of *length* for each group.

**padding** [str, optional] Either Pandas frequency (e.g. '1D') or 'calendar\_week'. If Pandas frequency, symmetric padding is undertaken, either side of *length*. If 'calendar\_week', padding is fit to the calendar week in which the extreme day(s) are found.

**normalize** [bool, optional] If True (default), data is normalized using `normalized_copy()`.

**kwargs** [dict, optional] Dimensions of the selected var over which to index. Any remaining dimensions will be flattened by mean

```
calliope.core.time.masks.extreme_diff(data, tech0, tech1, var='resource', how='max',
                                       length='1D', n=1, groupby_length=None,
                                       padding=None, normalize=True, **kwargs)
```

Returns timesteps for period of *length* where the difference in extreme value for *var* between technologies *tech0* and *tech1* is either a minimum or a maximum.

#### Parameters

**data** [xarray.Dataset]

**tech0** [str] First technology for which we find the extreme of *var*

**tech1** [str] Second technology for which we find the extreme of *var*

**var** [str, optional] default 'resource'

**how** [str, optional] 'max' (default) or 'min'.

**length** [str, optional] Defaults to '1D'.

**n** [int, optional] Number of periods of *length* to look for, default is 1.

**groupby\_length** [str, optional] Group time series and return *n* periods of *length* for each group.

**padding** [str, optional] Either Pandas frequency (e.g. '1D') or 'calendar\_week'. If Pandas frequency, symmetric padding is undertaken, either side of *length*. If 'calendar\_week', padding is fit to the calendar week in which the extreme day(s) are found.

**normalize** [bool, optional] If True (default), data is normalized using `normalized_copy()`.

**kwargs** [dict, optional] Dimensions of the selected var over which to index. Any remaining dimensions will be flattened by mean

```
calliope.core.time.funcs.resample(data, timesteps, resolution)
```

Function to resample timeseries data from the input resolution (e.g. 1H), to the given resolution (e.g. 2H)

#### Parameters

**data** [xarray.Dataset] calliope model data, containing only timeseries data variables

**timesteps** [str or list; optional] If given, apply resampling to a subset of the timeseries data

**resolution** [str] time resolution of the output data, given in Pandas time frequency format. E.g. 1H = 1 hour, 1W = 1 week, 1M = 1 month, 1T = 1 minute. Multiples allowed.

## 2.1.3 Analyzing models

```
class calliope.analysis.plotting.plotting.ModelPlotMethods(model)
```

```
    timeseries(**kwargs)
```

### Parameters

**array** [str or list; default = 'all'] options: 'all', 'results', 'inputs', the name/list of any energy carrier(s) (e.g. 'power'), the name/list of any input/output DataArray(s).

User can specify 'all' for all input/results timeseries plots, 'inputs' for just input timeseries, 'results' for just results timeseries, or the name of any data array to plot (in either inputs or results). In all but the last case, arrays can be picked from dropdown in visualisation. In the last case, output can be saved to SVG and a rangeslider can be used.

**timesteps\_zoom** [int, optional] Number of timesteps to show initially on the x-axis (if not given, the full time range is shown by default).

**rangeslider** [bool, optional] If True, displays a range slider underneath the plot for navigating (helpful primarily in interactive use).

**subset** [dict, optional] Dictionary by which data is subset (uses xarray *loc* indexing). Keys any of ['timeseries', 'locs', 'techs', 'carriers', 'costs'].

**sum\_dims** [str, optional] List of dimension names to sum plot variable over.

**squeeze** [bool, optional] Whether to squeeze out dimensions of length = 1.

**html\_only** [bool, optional; default = False] Returns a html string for embedding the plot in a webpage

**to\_file** [False or str, optional; default = False] Will save plot to file with the given name and extension. *to\_file='plot.svg'* to save to SVG, *to\_file='plot.png'* for a static PNG image. Allowed file extensions are: ['png', 'jpeg', 'svg', 'webp'].

**layout\_updates** [dict, optional] The given dict will be merged with the Plotly layout dict generated by the Calliope plotting function, overwriting keys that already exist.

**plotly\_kwarg\_updates** [dict, optional] The given dict will be merged with the Plotly plot function's keyword arguments generated by the Calliope plotting function, overwriting keys that already exist.

**capacity** (\*\*kwargs)

### Parameters

**array** [str or list; default = 'all'] options: 'all', 'results', 'inputs', the name/list of any energy capacity DataArray(s) from inputs/results. User can specify 'all' for all input/results capacities, 'inputs' for just input capacities, 'results' for just results capacities, or the name(s) of any data array(s) to plot (in either inputs or results). In all but the last case, arrays can be picked from dropdown in visualisation. In the last case, output can be saved to SVG.

**orient** [str, optional] 'h' for horizontal or 'v' for vertical barchart

**subset** [dict, optional] Dictionary by which data is selected (using xarray indexing *loc[]*). Keys any of ['timeseries', 'locs', 'techs', 'carriers', 'costs'].

**sum\_dims** [str, optional] List of dimension names to sum plot variable over.

**squeeze** [bool, optional] Whether to squeeze out dimensions containing only single values.

**html\_only** [bool, optional; default = False] Returns a html string for embedding the plot in a webpage

**to\_file** [False or str, optional; default = False] Will save plot to file with the given name and extension. *to\_file='plot.svg'* to save to SVG, *to\_file='plot.png'* for a static PNG image. Allowed file extensions are: ['png', 'jpeg', 'svg', 'webp'].

**layout\_updates** [dict, optional] The given dict will be merged with the Plotly layout dict generated by the Calliope plotting function, overwriting keys that already exist.

**plotly\_kwarg\_updates** [dict, optional] The given dict will be merged with the Plotly plot function's keyword arguments generated by the Calliope plotting function, overwriting keys that already exist.

**transmission** (*\*\*kwargs*)

#### Parameters

**mapbox\_access\_token** [str, optional] If given and a valid Mapbox API key, a Mapbox map is drawn for lat-lon coordinates, else (by default), a more simple built-in map.

**html\_only** [bool, optional; default = False] Returns a html string for embedding the plot in a webpage

**to\_file** [False or str, optional; default = False] Will save plot to file with the given name and extension. *to\_file='plot.svg'* to save to SVG, *to\_file='plot.png'* for a static PNG image. Allowed file extensions are: ['png', 'jpeg', 'svg', 'webp'].

**layout\_updates** [dict, optional] The given dict will be merged with the Plotly layout dict generated by the Calliope plotting function, overwriting keys that already exist.

**plotly\_kwarg\_updates** [dict, optional] The given dict will be merged with the Plotly plot function's keyword arguments generated by the Calliope plotting function, overwriting keys that already exist.

**summary** (*\*\*kwargs*)

Plot a summary containing timeseries, installed capacities, and transmission plots. Returns a HTML string by default, returns None if *to\_file* given (and saves the HTML string to file).

#### Parameters

**to\_file** [str, optional] Path to output file to save HTML to.

**mapbox\_access\_token** [str, optional] (passed to *plot\_transmission*) If given and a valid Mapbox API key, a Mapbox map is drawn for lat-lon coordinates, else (by default), a more simple built-in map.

## 2.1.4 Pyomo backend interface

**class** `calliope.backend.pyomo.interface.BackendInterfaceMethods` (*model*)

**access\_model\_inputs** ()

If the user wishes to inspect the parameter values used as inputs in the backend model, they can access a new Dataset of all the backend model inputs, including defaults applied where the user did not specify anything for a `loc::tech`

**update\_param** (*\*args, \*\*kwargs*)

A Pyomo Param value can be updated without the user directly accessing the backend model.

#### Parameters

**param** [str] Name of the parameter to update

**index** [tuple of strings] Tuple of dimension indices, in the order given in `model.inputs` for the reciprocal parameter

**value** [int, float, bool, or str] Value to assign to the Pyomo Param at the given index

#### Returns

Value will be updated in-place, requiring the user to run the model again to see the effect on results.

**activate\_constraint** (\*args, \*\*kwargs)

Takes a constraint or objective name, finds it in the backend model and sets its status to either active or deactive.

#### Parameters

**constraint** [str] Name of the constraint/objective to activate/deactivate Built-in constraints include `'_constraint'`

**active: bool, default=True** status to set the constraint/objective

**rerun** (\*args, \*\*kwargs)

Rerun the Pyomo backend, perhaps after updating a parameter value, (de)activating a constraint/objective or updating run options in the model `model_data` object (e.g. `run.solver`).

#### Returns

**run\_data** [xarray.Dataset] Raw data from this rerun, including both inputs and results. to filter inputs/results, use `run_data.filter_by_attrs(is_result=...)` with 0 for inputs and 1 for results.

## 2.1.5 Utility classes: AttrDict, Exceptions, Logging

**class** `calliope.core.attrdict.AttrDict` (*source\_dict=None*)

A subclass of `dict` with key access by attributes:

```
d = AttrDict({'a': 1, 'b': 2})
d.a == 1 # True
```

Includes a range of additional methods to read and write to YAML, and to deal with nested keys.

**keys** () → a set-like object providing a view on D's keys

**values** () → an object providing a view on D's values

**items** () → a set-like object providing a view on D's items

**copy** ()

Override copy method so that it returns an `AttrDict`

**init\_from\_dict** (d)

Initialize a new `AttrDict` from the given dict. Handles any nested dicts by turning them into `AttrDict`s too:

```
d = AttrDict({'a': 1, 'b': {'x': 1, 'y': 2}})
d.b.x == 1 # True
```

**classmethod from\_yaml** (f, *resolve\_imports=True*)

Returns an `AttrDict` initialized from the given path or file object `f`, which must point to a YAML file.

If `resolve_imports` is `True`, `import:` statements are resolved recursively, else they are treated like any other key.

When resolving import statements, anything defined locally overrides definitions in the imported file.

**classmethod from\_yaml\_string** (string, *resolve\_imports=False*)

Returns an `AttrDict` initialized from the given string, which must be valid YAML.

**set\_key** (*key*, *value*)

Set the given key to the given value. Handles nested keys, e.g.:

```
d = AttrDict ()
d.set_key('foo.bar', 1)
d.foo.bar == 1 # True
```

**get\_key** (*key*, *default*=<calliope.core.attrdict.\_\_Missing object>)

Looks up the given key. Like set\_key(), deals with nested keys.

If default is anything but `_MISSING`, the given default is returned if the key does not exist.

**del\_key** (*key*)

Delete the given key. Properly deals with nested keys.

**as\_dict** (*flat*=False, *filtered*=True)

Return the AttrDict as a pure dict (with nested dicts if necessary).

**get\_comments** (*key*)

Get comments for the given key. Returns a dict of the form `{'above': ..., 'inline': ..., 'below': ...}`.

**set\_comment** (*key*, *comment*, *kind*='inline', *exist\_ok*=False)

Set a comment for the given key. Returns None if successful, `KeyError` if key does not exist, and `ValueError` if a comment already exists, unless `exist_ok` is set to False.

**Parameters**

**key** [str]

**comment** [str]

**kind** [str, optional, default 'inline'] Can be 'inline', 'above'.

**exist\_ok** [bool, optional, default False] If True, existing comments are overwritten.

**del\_comments** (*key*)

Remove any comments at the given key. Returns None if successful, `KeyError` if key has no comments.

**to\_yaml** (*path*=None)

Saves the AttrDict to the `path` as a YAML file, or returns a YAML string if `path` is None.

**keys\_nested** (*subkeys\_as*='list', *filtered*=True)

Returns all keys in the AttrDict, sorted, including the keys of nested subdicts (which may be either regular dicts or AttrDicts).

If `subkeys_as`='list' (default), then a list of all keys is returned, in the form `['a', 'b.b1', 'b.b2']`.

If `subkeys_as`='dict', a list containing keys and dicts of subkeys is returned, in the form `['a', {'b': ['b1', 'b2']}]`.

**union** (*other*, *allow\_override*=False, *allow\_replacement*=False, *allow\_subdict\_override\_with\_none*=False)

Merges the AttrDict in-place with the passed `other` AttrDict. Keys in `other` take precedence, and nested keys are properly handled.

If `allow_override` is False, a `KeyError` is raised if `other` tries to redefine an already defined key.

If `allow_replacement`, allow “\_REPLACE\_” key to replace an entire sub-dict.

If `allow_subdict_override_with_none` is False (default), a key of the form `this.that`: None in `other` will be ignored if subdicts exist in `self` like `this.that.foo: 1`, rather than wiping them.

**exception** `calliope.exceptions.ModelError`

ModelErrors should stop execution of the model, e.g. due to a problem with the model formulation or input data.

**exception** `calliope.exceptions.BackendError`

**exception** `calliope.exceptions.ModelWarning`

ModelWarnings should be raised for possible model errors, but where execution can still continue.

**exception** `calliope.exceptions.BackendWarning`

`calliope.exceptions.print_warnings_and_raise_errors` (*warnings=None, errors=None*)

Print warnings and raise ModelError from errors.

#### Parameters

**warnings** [list, optional]

**errors** [list, optional]

`calliope.core.util.logging.set_log_level` (*level*)

Set the minimum logging verbosity in a Python console. Higher verbosity levels will include their output and all those of following levels. Level options (in descending order of verbosity):

- 'DEBUG'
- 'SOLVER' -> Calliope custom level, assigned value of 19, returns solver (e.g. GLPK) stream
- 'INFO' -> default level
- 'WARNING'
- 'ERROR'
- 'CRITICAL'

## 2.2 Index



## 3.1 Release History

### 3.1.1 0.6.2 (2018-06-04)

new `units_max_systemwide` and `units_equals_systemwide` can be applied to an integer/binary constrained technology (capacity limited by `units` not `energy_cap`, or has an associated purchase (binary) cost). Constraint works similarly to existing `energy_cap_max_systemwide`, limiting the number of units of a technology that can be purchased across all locations in the model.

new backwards-incompatible `primary_carrier` for `conversion_plus` techs is now split into `primary_carrier_in` and `primary_carrier_out`. Previously, it only accounted for output costs, by separating it, `om_con` and `om_prod` are correctly accounted for. These are required `conversion_plus` essentials if there's more than one input and output carrier, respectively.

new Storage can be set to cyclic using `run.cyclic_storage`. The last timestep in the series will then be used as the 'previous day' conditions for the first timestep in the series. This also applies to `storage_inter_cluster`, if clustering. Defaults to False, with intention of defaulting to True in 0.6.3.

new On clustering timeseries into representative days, an additional set of decision variables and constraints is generated. This addition allows for tracking stored energy between clusters, by considering storage between every `datestep` of the original (unclustered) timeseries as well as storage variation within a cluster.

new CLI now uses the IPython debugger rather than built-in `pdb`, which provides highlighting, tab completion, and other UI improvements

new `AttrDict` now persists comments when reading from and writing to YAML files, and gains an API to view, add and remove comments on keys

fixed Fix CLI error when running a model without transmission technologies

fixed Allow plotting for inputs-only models, single location models, and models without location coordinates

fixed Fixed negative `om_con` costs in `conversion` and `conversion_plus` technologies

### 3.1.2 0.6.1 (2018-05-04)

new Addition of user-defined datestep clustering, accessed by `clustering_func:file=filename.csv:column` in time aggregation config

new Added `layout_updates` and `plotly_kwarg_updates` parameters to plotting functions to override the generated Plotly configuration and layout

changed Cost class and sense (maximize/minimize) for objective function may now be specified in run configuration (default remains monetary cost minimization)

changed Cleaned up and documented `Model.save_commented_model_yaml()` method

fixed Fixed error when calling `--save_plots` in CLI

fixed Minor improvements to warnings

fixed Pure dicts can be used to create a `Model` instance

fixed `AttrDict.union` failed on all-empty nested dicts

### 3.1.3 0.6.0 (2018-04-20)

Version 0.6.0 is an almost complete rewrite of most of Calliope's internals. See [New in v0.6.0](#) for a more detailed description of the many changes.

#### Major changes

changed backwards-incompatible Substantial changes to model configuration format, including more verbose names for most settings, and removal of run configuration files. See [0.6.0 model configuration changes](#) for a full list of changes.

new backwards-incompatible Complete rewrite of Pyomo backend, including new various new and improved functionality to interact with a built model (see [New in v0.6.0](#)).

new Addition of a `calliope convert` CLI tool to convert 0.5.x models to 0.6.0.

new Experimental ability to link to non-Pyomo backends.

new New constraints: `resource_min_use` constraint for `supply` and `supply_plus` techs.

changed backwards-incompatible Removal of settings and constraints includes `subset_x`, `subset_y`, `s_time`, `r2`, `r_scale_to_peak`, `weight`. See [0.6.0 model configuration changes](#) for a full list.

changed backwards-incompatible `system_margin` constraint replaced with `reserve_margin` constraint.

changed backwards-incompatible Removed the ability to load additional custom constraints or objectives.

### 3.1.4 0.5.5 (2018-02-28)

- fixed Allow `r_area` to be non-zero if either of `e_cap.max` or `e_cap.equals` is set, not just `e_cap.max`.
- fixed Ensure static parameters in resampled timeseries are caught in constraint generation
- fixed Fix time masking when `set_t.csv` contains sub-hourly resolutions

### 3.1.5 0.5.4 (2017-11-10)

#### Major changes

- fixed *r\_area\_per\_e\_cap* and *r\_cap\_equals\_e\_cap* constraints have been separated from *r\_area* and *r\_cap* constraints to ensure that user specified *r\_area.max* and *r\_cap.max* constraints are observed.
- changed technologies and location subsets are now communicated with the solver as a combined location:technology subset, to reduce the problem size, by ignoring technologies at locations in which they have not been allowed. This has shown drastic improvements in Pyomo preprocessing time and memory consumption for certain models.

#### Other changes

- fixed Allow plotting carrier production using *calliope.analysis.plot\_carrier\_production* if that carrier does not have an associated demand technology (previously would raise an exception).
- fixed Define time clustering method (sum/mean) for more constraints that can be time varying. Previously only included *r* and *e\_eff*.
- changed storage technologies default *s\_cap.max* to *inf*, not 0 and are automatically included in the *loc\_tech\_store* subset. This ensures relevant constraints are not ignored by storage technologies.
- changed Some values in the urban scale MILP example were updated to provide results that would show the functionality more clearly
- changed technologies have set colours in the urban scale example model, as random colours were often hideous.
- changed *ruamel.yaml*, not *ruamel\_yaml*, is now used for parsing YAML files.
- fixed *e\_cap* constraints for *unmet\_demand* technologies are ignored in operational mode. Capacities are fixed for all other technologies, which previously raised an exception, as a fixed infinite capacity is not physically allowable.
- fixed *stack\_weights* were strings rather than numeric datatypes on reading NetCDF solution files.

### 3.1.6 0.5.3 (2017-08-22)

#### Major changes

- new (BETA) Mixed integer linear programming (MILP) capabilities, when using *purchase cost* and/or *units.max/min>equals* constraints. Integer/Binary decision variables will be applied to the relevant technology-location sets, avoiding unnecessary complexity by describing all technologies with these decision variables.

#### Other changes

- changed YAML parser is now *ruamel\_yaml*, not *pyyaml*. This allows scientific notation of numbers in YAML files (#57)
- fixed Description of PV technology in urban scale example model now more realistic
- fixed Optional ramping constraint no longer uses backward-incompatible definitions (#55)
- fixed One-way transmission no longer forces unidirectionality in the wrong direction

- fixed Edge case timeseries resource combinations, where infinite resource sneaks into an incompatible constraint, are now flagged with a warning and ignored in that constraint (#61)
- fixed `e_cap.equals: 0` sets a technology to a capacity of zero, instead of ignoring the constraint (#63)
- fixed `depreciation_getter` now changes with location overrides, instead of just checking the technology level constraints (#64)
- fixed Time clustering now functions in models with time-varying costs (#66)
- changed Solution now includes time-varying costs (`costs_variable`)
- fixed Saving to NetCDF does not affect in-memory solution (#62)

### 3.1.7 0.5.2 (2017-06-16)

- changed Calliope now uses Python 3.6 by default. From Calliope 0.6.0 on, Python 3.6 will likely become the minimum required version.
- fixed Fixed a bug in distance calculation if both lat/lon metadata and distances for links were specified.
- fixed Fixed a bug in storage constraints when both `s_cap` and `e_cap` were constrained but no `c_rate` was given.
- fixed Fixed a bug in the system margin constraint.

### 3.1.8 0.5.1 (2017-06-14)

new backwards-incompatible Better coordinate definitions in metadata. Location coordinates are now specified by a dictionary with either lat/lon (for geographic coordinates) or x/y (for generic Cartesian coordinates), e.g. `{lat: 40, lon: -2}` or `{x: 0, y: 1}`. For geographic coordinates, the `map_boundary` definition for plotting was also updated in accordance. See the built-in example models for details.

new Unidirectional transmission links are now possible. See the [documentation on transmission links](#).

#### Other changes

- fixed Missing urban-scale example model files are now included in the distribution
- fixed Edge cases in `conversion_plus` constraints addressed
- changed Documentation improvements

### 3.1.9 0.5.0 (2017-05-04)

#### Major changes

new Urban-scale example model, major revisions to the documentation to accommodate it, and a new `calliope.examples` module to hold multiple example models. In addition, the `calliope` new command now accepts a `--template` option to select a template other than the default national-scale example model, e.g.: `calliope new my_urban_model --template=UrbanScale`.

new Allow technologies to generate revenue (by specifying negative costs)

new Allow technologies to export their carrier directly to outside the system boundary

new Allow storage & `supply_plus` technologies to define a charge rate (`c_rate`), linking storage capacity (`s_cap`) with charge/discharge capacity (`e_cap`) by `s_cap * c_rate => e_cap`. As such, either `s_cap.max & c_rate` or `e_cap.max &`

`c_rate` can be defined for a technology. The smallest of `s_cap.max * c_rate` and `e_cap.max` will be taken if all three are defined.

changed backwards-incompatible Revised technology definitions and internal definition of sets and subsets, in particular subsets of various technology types. Supply technologies are now split into two types: `supply` and `supply_plus`. Most of the more advanced functionality of the original `supply` technology is now contained in `supply_plus`, making it necessary to update model definitions accordingly. In addition to the existing `conversion` technology type, a new more complex `conversion_plus` was added.

### Other changes

- changed backwards-incompatible Creating a `Model()` with no arguments now raises a `ModelError` rather than returning an instance of the built-in national-scale example model. Use the new `calliope.examples` module to access example models.
- changed Improvements to the national-scale example model and its tutorial notebook
- changed Removed `SolutionModel` class
- fixed Other minor fixes

### 3.1.10 0.4.1 (2017-01-12)

- new Allow profiling with the `--profile` and `--profile_filename` command-line options
- new Permit setting random seed with `random_seed` in the run configuration
- changed Updated installation documentation using conda-forge package
- fixed Other minor fixes

### 3.1.11 0.4.0 (2016-12-09)

#### Major changes

new Added new methods to deal with time resolution: clustering, resampling, and heuristic timestep selection

changed backwards-incompatible Major change to solution data structure. Model solution is now returned as a single `xarray DataSet` instead of multiple pandas `DataFrames` and `Panels`. Instead of as a generic HDF5 file, complete solutions can be saved as a NetCDF4 file via `xarray`'s NetCDF functionality.

While the recommended way to save and process model results is by NetCDF4, CSV saving functionality has now been upgraded for more flexibility. Each variable is saved as a separate CSV file with a single value column and as many index columns as required.

changed backwards-incompatible Model data structures simplified and based on `xarray`

#### Other changes

- new Functionality to post-process parallel runs into aggregated NetCDF files in `calliope.read`
- changed Pandas 0.18/0.19 compatibility
- changed 1.11 is now the minimum required numpy version. This version makes `datetime64` tz-naive by default, thus preventing some odd behavior when displaying time series.
- changed Improved logging, status messages, and error reporting

- fixed Other minor fixes

### 3.1.12 0.3.7 (2016-03-10)

#### Major changes

changed Per-location configuration overrides improved. All technology constraints can now be set on a per-location basis, as can costs. This applies to the following settings:

- `techname.x_map`
- `techname.constraints.*`
- `techname.constraints_per_distance.*`
- `techname.costs.*`

The following settings cannot be overridden on a per-location basis:

- Any other options directly under `techname`, such as `techname.parent` or `techname.carrier`
- `techname.costs_per_distance.*`
- `techname.depreciation.*`

#### Other changes

- fixed Improved installation instructions
- fixed Pyomo 4.2 API compatibility
- fixed Other minor fixes

### 3.1.13 0.3.6 (2015-09-23)

- fixed Version 0.3.5 changes were not reflected in tutorial

### 3.1.14 0.3.5 (2015-09-18)

#### Major changes

new New constraint to constrain total (model-wide) installed capacity of a technology (`e_cap.total_max`), in addition to its per-node capacity (`e_cap.max`)

changed Removed the `level` option for locations. Level is now implicitly derived from the nested structure given by the `within` settings. Locations that define no or an empty `within` are implicitly at the topmost (0) level.

changed backwards-incompatible Revised configuration of capacity constraints: `e_cap_max` becomes `e_cap.max`, addition of `e_cap.min` and `e_cap.equals` (analogous for `r_cap`, `s_cap`, `rb_cap`, `r_area`). The `e_cap.equals` constraint supersedes `e_cap_max_force` (analogous for the other constraints). No backwards-compatibility is retained, models must change all constraints to the new formulation. See [List of possible constraints](#) for a complete list of all available constraints. Some additional constraints have name changes:

- `e_cap_max_scale` becomes `e_cap_scale`
- `rb_cap_follows` becomes `rb_cap_follow`, and addition of `rb_cap_follow_mode`
- `s_time_max` becomes `s_time.max`

changed backwards-incompatible All optional constraints are now grouped together, under `constraints.optional`:

- `constraints.group_fraction.group_fraction` becomes `constraints.optional.group_fraction`
- `constraints.ramping.ramping_rate` becomes `constraints.optional.ramping_rate`

### Other changes

- new `analysis.map_results` function to extract solution details from multiple parallel runs
- new Various other additions to analysis functionality, particularly in the `analysis_utils` module
- new `analysis.get_levelized_cost` to get technology and location specific costs
- new Allow dynamically loading time mask functions
- changed Improved summary table in the model solution: now shows only aggregate information for transmission technologies, also added missing `s_cap` column and technology type
- fixed Bug causing some total levelized transmission costs to be infinite instead of zero
- fixed Bug causing some CSV solution files to be empty

### 3.1.15 0.3.4 (2015-04-27)

- fixed Bug in construction and fixed O&M cost calculations in operational mode

### 3.1.16 0.3.3 (2015-04-03)

#### Major changes

changed In preparation for future enhancements, the ordering of location levels is flipped. The top-level locations at which balancing takes place is now level 0, and may contain level 1 locations. This is a backwards-incompatible change.

changed backwards-incompatible Refactored time resolution adjustment functionality. Can now give a list of masks in the run configuration which will all be applied, via `time.masks`, with a base resolution via `time.resolution` (or instead, as before, load a resolution series from file via `time.file`). Renamed the `time_functions` submodule to `time_masks`.

#### Other changes

- new Models and runs can have a name
- changed More verbose `calliope run`
- changed Analysis tools restructured
- changed Renamed `debug.keepfiles` setting to `debug.keep_temp_files` and better documented debug configuration

### 3.1.17 0.3.2 (2015-02-13)

- new Run setting `model_override` allows specifying the path to a YAML file with overrides for the model configuration, applied at model initialization (path is given relative to the run configuration file used). This is in addition to the existing `override` setting, and is applied first (so `override` can override `model_override`).
- new Run settings `output.save_constraints` and `output.save_constraints_options`
- new Run setting `parallel.post_run`
- changed Solution column names more in line with model component names
- changed Can specify more than one output format as a list, e.g. `output.format: ['csv', 'hdf']`
- changed Run setting `parallel.additional_lines` renamed to `parallel.pre_run`
- changed Better error messages and CLI error handling
- fixed Bug on saving YAML files with numpy dtypes fixed
- Other minor improvements and fixes

### 3.1.18 0.3.1 (2015-01-06)

- Fixes to `time_functions`
- Other minor improvements and fixes

### 3.1.19 0.3.0 (2014-12-12)

- Python 3 and Pyomo 4 are now minimum requirements
- Significantly improved documentation
- Improved model solution management by saving to HDF5 instead of CSV
- Calculate shares of technologies, including the ability to define groups for the purpose of computing shares
- Improved operational mode
- Simplified `time_tools`
- Improved output plotting, including dispatch, transmission flows, and installed capacities, and added model configuration to support these plots
- `r` can be specified as power or energy
- Improved solution speed
- Better error messages and basic logging
- Better sanity checking and error messages for common mistakes
- Basic distance-dependent constraints (only implemented for `e_loss` and cost of `e_cap` for now)
- Other improvements and fixes



### 3.1.20 0.2.0 (2014-03-18)

- Added cost classes with a new set  $k$
- Added energy carriers with a new set  $c$
- Added conversion technologies
- Speed improvements and simplifications
- Ability to arbitrarily nest model configuration files with `import` statements
- Added additional constraints
- Improved configuration handling
- Ability to define timestep options in run configuration
- Cleared up terminology (nodes vs locations)
- Improved TimeSummarizer masking and added new masks
- Removed technology classes
- Improved operational mode with results output matching planning mode and dynamic updating of parameters in model instance
- Working `parallel_tools`
- Improved documentation
- Apache 2.0 licensed
- Other improvements and fixes

### 3.1.21 0.1.0 (2013-12-10)

- Some semblance of documentation
- Usable built-in example model
- Improved and working TimeSummarizer
- More flexible masking for TimeSummarizer
- Ability to add additional constraints without editing core source code
- Some basic test coverage
- Working parallel run configuration system

*Release history*



## CHAPTER 4

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### License

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